

UM1913 User manual

Developing applications on STM32Cube™ with STMTouch® touch sensing library

Introduction

STM32Cube[™] is an STMicroelectronics original initiative to make developers' life easier by reducing development effort, time and cost. STM32Cube[™] covers the whole STM32 portfolio.

STM32Cube™ includes:

- STM32CubeMX, a graphical software configuration tool that allows the generation of C initialization code using graphical wizards
- a comprehensive embedded software platform, delivered per Series (such as STM32Cubexx for STM32xx Series):
 - the STM32Cube™ HAL, STM32 abstraction layer embedded software ensuring maximized portability across the STM32 portfolio
 - a consistent set of middleware components such as RTOS, USB, TCP/IP, Graphics and STMTouch[®]
 - all embedded software utilities coming with a full set of examples

This user manual describes the STMTouch[®] touch sensing library which is part of the STM32Cube[™] firmware package, available as a free download from the STMicroelectronics website (http://www.st.com/stm32cube). It is intended for developers who use STM32Cube firmware on STM32 Arm[®]-based microcontrollers from the STM32F0, STM32F3, STM32L0, STM32L1 or STM32L4 Series (STM32CubeF0, STM32CubeF3, STM32CubeL0, STM32CubeL1 or STM32CubeL4). It describes how to start and implement a touch sensing application.

The STMTouch® touch sensing library includes:

- a complete register address mapping with all bits, bitfields and registers declared in C
 This avoids a cumbersome task and more importantly, it brings the benefits of a bug free reference mapping file, speeding up the early project phase.
- a collection of routines and data structures covering all functions to manage the touch sensing technology

The source code is developed using the ANSI-C standard. It is fully documented and is MISRA C^{\circledR} 2004 compliant. Writing the whole library in 'Strict ANSI-C' makes it independent from the development tools. Only the start-up files depend on the development tools. Since this library is generic and covers many functionalities and microcontrollers, the size and/or execution speed of the application code may not be optimized. For many applications, this library may be used as is. However, for applications having tough constraints in terms of code size and/or execution speed, this library may need to be fine tuned.



September 2018 UM1913 Rev 7 1/156

Contents UM1913

Contents

1	Cod	ing rule	es and conventions	10
	1.1	Acron	yms and abbreviations	10
	1.2	Namin	ng conventions	
	1.3	Coding	g rules	
		1.3.1	General	11
		1.3.2	Variable types	11
		1.3.3	Peripheral registers	11
	1.4	MISRA	A C 2004 compliance	12
		1.4.1	Generalities	12
		1.4.2	Compliance matrix	12
2	STM	Touch t	touch sensing library	15
	2.1	Suppo	orted microcontrollers and development tools	15
		2.1.1	Supported microcontrollers	15
		2.1.2	Development tools	15
	2.2	Packa	age description	16
	2.3		features	
	2.4		ecture	
		2.4.1	Overview	
		2.4.2	STMTouch touch sensing library layers	
		2.4.3	Acquisition and processing layers	
		2.4.4	Header files inclusion	
	2.5	Chann	nel	
		2.5.1	Principle	
		2.5.2	Resources	
		2.5.3	Parameters	
		2.5.4	Usage example	
	2.6	Bank		24
		2.6.1	Principle	
		2.6.2	Resources	
		2.6.3	Parameters	
		2.6.4	Usage example	
	2.7	Object	ts	
		•		



	2.7.1	Principle
	2.7.2	Resources
	2.7.3	Parameters
	2.7.4	Usage example
2.8	Touchke	ey sensor
	2.8.1	Principle
	2.8.2	Resources
	2.8.3	Parameters
	2.8.4	Usage example
2.9	Linear a	and rotary touch sensors
	2.9.1	Principle
	2.9.2	Number of channels
	2.9.3	Delta coefficient table
	2.9.4	Electrodes placement
	2.9.5	Resources
	2.9.6	Parameters
	2.9.7	Usage example
2.10	Main sta	ate machine 34
2.11	Sensors	s state machine
2.11		•
2.11	2.11.1	Overview
2.11		
2.11	2.11.1	Overview
2.11	2.11.1 2.11.2	Overview
2.11	2.11.1 2.11.2 2.11.3	Overview37States constant table37States detail40
2.11	2.11.1 2.11.2 2.11.3 2.11.4	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8 2.11.9	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43 ERROR state 43
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8 2.11.9 2.11.10	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43 ERROR state 43 OFF state 43
2.11	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8 2.11.9 2.11.10 2.11.11	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43 ERROR state 43 OFF state 43 DEBOUNCE states 43
2.12	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8 2.11.9 2.11.10 2.11.11 2.11.12 2.11.13	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43 ERROR state 43 OFF state 43 DEBOUNCE states 43 Reading the current state 43
	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8 2.11.9 2.11.10 2.11.11 2.11.12 2.11.13	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43 ERROR state 43 OFF state 43 DEBOUNCE states 43 Reading the current state 43 Enabling a specific state 44
	2.11.1 2.11.2 2.11.3 2.11.4 2.11.5 2.11.6 2.11.7 2.11.8 2.11.9 2.11.10 2.11.11 2.11.12 2.11.13 Environ	Overview 37 States constant table 37 States detail 40 CALIBRATION state 42 RELEASE state 42 PROXIMITY state 42 DETECT state 42 TOUCH state 43 ERROR state 43 OFF state 43 DEBOUNCE states 43 Reading the current state 43 Enabling a specific state 44 ment change system (ECS) 44

		2.12.4	Usage example	. 45
	2.13	Detection	on exclusion system (DXS)	47
		2.13.1	Principle	. 47
		2.13.2	Resources	. 49
		2.13.3	Parameters	. 49
		2.13.4	Usage example	. 49
	2.14	Detection	on time out (DTO)	50
		2.14.1	Principle	. 50
		2.14.2	Resources	. 50
		2.14.3	Parameters	. 50
		2.14.4	Usage	. 50
	2.15	Noise fil	Iters	51
		2.15.1	Principle	. 51
		2.15.2	Resources	. 51
		2.15.3	Parameters	. 51
		2.15.4	Usage	. 51
	2.16	Timing r	management	51
		2.16.1	Principle	. 51
		2.16.2	Resources	. 52
		2.16.3	Parameters	. 52
		2.16.4	Usage	. 52
	2.17	Parame	eters	52
	2.18	Sensors	s acquisition timings	53
		2.18.1	Acquisition timing using touchkey sensors	. 53
		2.18.2	Acquisition timing using linear or rotary sensors	. 58
		2.18.3	Acquisition timing using touchkey, linear and rotary sensors	. 61
	2.19	Error ma	anagement	64
3	Devic	es with	TSC peripheral	65
	3.1	Acquisit	iion	65
	3.2	Timings		65
	3.3	_	eters	
	3.4		sources	
	3.5		F0 Series microcontrollers	
	0.0	3.5.1	Memory footprint	
		3.5.2	Available touch sensing channels	
		J.J.L		. 01

3.6	3.5.3	Hardware implementation example	84
3.6			
3.0	STM32F	3 Series microcontrollers	. 86
	3.6.1	Memory footprint	86
	3.6.2	Available touch sensing channels	86
	3.6.3	Hardware implementation example	. 103
3.7	STM32L	.0 Series microcontrollers	105
	3.7.1	Memory footprint	. 105
	3.7.2	Available touch sensing channels	. 105
	3.7.3	Hardware implementation example	. 114
3.8	STM32L	.4 Series microcontrollers	.116
	3.8.1	Memory footprint	. 116
	3.8.2	Available touch sensing channels	. 116
	3.8.3	Hardware implementation example	. 125
STM3	2L1 Ser	ies microcontrollers	127
4.1	Acquisit	on	127
4.2	Timings		127
4.3	Parame	ters	128
4.4			
	•	·	
		-	
4.7	Taruwai	e implementation example	140
Gettin	g starte	ed	150
5.1	Create y	our application	150
	5.1.1	Toolchain compiler preprocessor section	. 150
	5.1.2	The tsl_conf.h file	. 150
	5.1.3	The main file	. 150
	5.1.4	The tsl_user file	. 150
5.2	Debug v	vith STM Studio	151
5.3	Low-pov	ver strategy	152
5.4	Tips and	I tricks	153
	5.4.1	Recommendations to increase the noise immunity on the PCB	. 153
	5.4.2	•	
	5.4.3	Channel assignment	. 154
	5.4.4	IO Default state parameter	. 154
	3.8 STM3: 4.1 4.2 4.3 4.4 4.5 4.6 4.7 Gettin 5.1	3.6.2 3.6.3 3.7 STM32L 3.7.1 3.7.2 3.7.3 3.8 STM32L 3.8.1 3.8.2 3.8.3 STM32L1 Ser 4.1 Acquisiti 4.2 Timings 4.3 Paramet 4.4 Memory 4.5 MCU res 4.6 Available 4.7 Hardwar Getting starte 5.1 Create y 5.1.1 5.1.2 5.1.3 5.1.4 5.2 Debug v 5.3 Low-pov 5.4 Tips and 5.4.1 5.4.2 5.4.3	3.6.2 Available touch sensing channels 3.6.3 Hardware implementation example 3.7 STM32L0 Series microcontrollers 3.7.1 Memory footprint 3.7.2 Available touch sensing channels 3.7.3 Hardware implementation example 3.8 STM32L4 Series microcontrollers 3.8.1 Memory footprint 3.8.2 Available touch sensing channels 3.8.3 Hardware implementation example STM32L1 Series microcontrollers 4.1 Acquisition 4.2 Timings 4.3 Parameters 4.4 Memory footprint 4.5 MCU resources 4.6 Available touch sensing channels 4.7 Hardware implementation example Getting started 5.1 Create your application 5.1.1 Toolchain compiler preprocessor section 5.1.2 The tsl_conf.h file 5.1.3 The main file 5.1.4 The tsl_user file 5.1 Debug with STM Studio 5.3 Low-power strategy 5.4 Tips and tricks 5.4.1 Recommendations to increase the noise immunity on the PCB 5.4.2 Bank definition 5.4.3 Channel assignment

Contents											U	M1	913
	5.5	Related of	documen	ts .	 	 	 	 	 	 			154
6	Revi	sion histo	orv		 	 	 	 	 	 		. •	155

UM1913 List of tables

List of tables

Table 1.	Terms and acronyms	. 10
Table 2.	MISRA C 2004 rules not followed	
Table 3.	Supported linear and rotary touch sensors	. 31
Table 4.	Detailed sensors states 1/2	
Table 5.	Detailed sensors states 2/2	
Table 6.	Example based on G1/G2 (3 touchkey sensors)	
Table 7.	Example G1/G2 (3 touchkey sensors) - Acquisition time line	
Table 8.	Example G1/G2 (3 touchkey sensors) - Synthesis	
Table 9.	Example based on G1/G2/G3/G4 (3 touchkey sensors)	
Table 10.	Example G1/G2/G3/G4 (3 touchkey sensors) - Acquisition time line	
Table 11.	Example G1/G2/G3/G4 (3 touchkey sensors) - Synthesis	
Table 12.	Example based on G1/G2/G3/G4 (9 touchkey sensors)	
Table 13.	Example G1/G2/G3/G4 (9 touchkey sensors) - Acquisition time line	
Table 14.	Example G1/G2/G3/G4 (9 keys)- Synthesis	
Table 15.	Example G1/G2/G3/G4 (specific touch key sensors only) - Acquisition time line	
Table 16.	Example based on G1/G2/G3/G4 (1 linear sensor)	
Table 17.	Example G1/G2/G3/G4 (1 sensor) - Acquisition time line	
Table 18.	Example G1/G2/G3/G4 (1 sensor) - Synthesis.	
Table 19.	Example based on G1/G2/G3/G4 (3 L/R sensors)	
Table 20.	Example G1/G2/G3/G4 (3 L/R sensors) - Acquisition time line	
Table 21.	Example G1/G2/G3/G4 (3 L/R sensors) - Synthesis	
Table 22.	Example based on G1, G2, G3 and G4 (3 touchkey, 1 linear, 1 rotary sensors)	
Table 23.	Example G1/G2/G3/G4 (3 touchkey, 1 linear, 1 rotary sensors) - Acquisition time line	
Table 24.	Example G1/G2/G3/G4 (3 touchkey, 1 linear, 1 rotary sensors) - Synthesis	
Table 25.	STM32F0 Series MCU resources used	
Table 26.	STM32F0 Series memory footprint	
Table 27.	Available touch sensing channels for STM32F098xx	
Table 28.	Available touch sensing channels for STM32F091xx	
Table 29.	Available touch sensing channels for STM32F078xx	
Table 30.	Available touch sensing channels for STM32F072xx	
Table 31.	Available touch sensing channels for STM32F071xx	
Table 31.	Available touch sensing channels for STM32F058xx	
Table 33.	Available touch sensing channels for STM32F051xx	
Table 33.	Available touch sensing channels for STM32F048xx	
Table 35.	Available touch sensing channels for STM32F042xx	
Table 36.	STM32F3 Series memory footprint	
Table 37.	Available touch sensing channels for STM32F398VE	
Table 37.	Available touch sensing channels for STM32F378xx	
Table 39.	Available touch sensing channels for STM32F373xx	
Table 40.	Available touch sensing channels for STM32F358xC	
Table 41.	Available touch sensing channels for STM32F334x4/x6/x8	
Table 41.	Available touch sensing channels for STM32F328C8	
Table 42.	Available touch sensing channels for STM32F318x8	
Table 43.	Available touch sensing channels for STM32F303xD/xE	
Table 44.	Available touch sensing channels for STM32F303xB/xC	
Table 45.	Available touch sensing channels for STM32F303x6/x8	
Table 40.	Available touch sensing channels for STM32F303x0/x6	
Table 47.	Available touch sensing channels for STM32F302xB/xC	
i abic 40.	Available touch scholing charmers for a rividal Juzabiac	100



List of tables UM1913

Table 49.	Available touch sensing channels for STM32F302x6/x8	. 101
Table 50.	Available touch sensing channels for STM32F301x6/x8	. 102
Table 51.	STM32L0 Series memory footprint	. 105
Table 52.	Capacitive sensing GPIOs available on STM32L083xx devices	. 106
Table 53.	Capacitive sensing GPIOs available on STM32L082xx devices	. 107
Table 54.	Available touch sensing channels for STM32L063x8	. 108
Table 55.	Available touch sensing channels for STM32L062K8	. 109
Table 56.	Available touch sensing channels for STM32L053x6/x8	. 110
Table 57.	Available touch sensing channels for STM32L052x6/x8	. 112
Table 58.	STM32L4 Series memory footprint	
Table 59.	Available touch sensing channels for STM32L4A6xG	
Table 60.	Available touch sensing channels for STM32L496xx	. 119
Table 61.	Available touch sensing channels for STM32L486xx	. 121
Table 62.	Available touch sensing channels for STM32L476xx	. 122
Table 63.	STM32L1 Series with hardware acquisition mode memory footprint	. 128
Table 64.	STM32L1 Series with software acquisition mode memory footprint	. 128
Table 65.	MCU resources used on STM32L1 Series with hardware acquisition	. 129
Table 66.	MCU resources used on STM32L1 Series with software acquisition	. 129
Table 67.	Available touch sensing channels for STM32L1 Series 512K	. 130
Table 68.	Available touch sensing channels for STM32L1 Series 384K	
Table 69.	Available touch sensing channels for STM32L1 Series 256K (table 1/2)	
Table 70.	Available touch sensing channels for STM32L1 Series 256K (table 2/2)	. 142
Table 71.	Available touch sensing channels for STM32L15x 32K to 128K	. 145
Table 72.	Document revision history	. 155



UM1913 List of figures

List of figures

Figure 1.	Installation folder 1/2 (library)	16
Figure 2.	Installation folder 2/2 (application example)	17
Figure 3.	STM32Cube touch sensing library overview	18
Figure 4.	STMTouch touch sensing library detailed layers	19
Figure 5.	Acquisition and processing layers	20
Figure 6.	Header files inclusion	21
Figure 7.	Channels arrangement	23
Figure 8.	Electrodes designs	30
Figure 9.	Positions 0 and 255	31
Figure 10.	Main state machine	35
Figure 11.	Example of main state machine	36
Figure 12.	Simplified sensors state machine	37
Figure 13.	Reference versus K filter value	45
Figure 14.	DXS principle	48
Figure 15.	DXS example 1	48
Figure 16.	DXS example 2	49
Figure 17.	STM32F0 Series hardware implementation example	85
Figure 18.	STM32F3 Series hardware implementation example	
Figure 19.	STM32L0 Series hardware implementation example	115
Figure 20.	STM32L4 Series hardware implementation example	126
Figure 21.	STM32L1 Series hardware implementation example	149
Figure 22.	STM Studio snapshot	152
Figure 23.	Low-power strategy	153



UM1913 Rev 7 9/156

1 Coding rules and conventions

1.1 Acronyms and abbreviations

The table below summarizes all acronyms and abbreviations used inside this user manual.

Table 1. Terms and acronyms

Name	Definition
Bank	A group of channels acquired simultaneously
Channel	Elementary acquisition item
Cs	Charge-Transfer sampling capacitor or capacitance
Ct	Equivalent touch capacitance
СТ	Charge-Transfer acquisition principle
Сх	Equivalent sensor capacitance
Delta	Difference between the Measure and the Reference
рто	Detection Time Out
DXS	Detection Exclusion System
ECS	Environment Change System
Linear sensor	Multi-channels sensor with the electrodes positioned in a linear way
LinRot sensor	A linear or rotary touch sensor
Measure or Meas	Current signal measured on a channel
Reference or Ref	Reference signal initialized during calibration and then regularly updated by the ECS
Rotary sensor	Multi-channels sensor with the electrodes positioned in a circular way
Rs	ESD protection serial resistor
Sensor or Object	Any touch sensor (such as touchkey, linear or rotary)
Timer acquisition mode	Acquisition using two timers and PWM signals (also called hardware acquisition mode). Only available on STM32L1 Series microcontrollers
Touchkey or TKey sensor	Single channel sensor
TSC	Touch sensing controller peripheral

1.2 Naming conventions

The following naming conventions are used in the STMTouch touch sensing library source files:

- Source and header files are in lower-case and preceded by 'tsl' or 'tsl_'.
- The microcontroller family is added at the end of the file name if needed.
- Functions, globals, typedefs and defines are preceded by 'TSL'.
- Constants are written in upper case and preceded by 'TSLPRM_'.
- Constants used in one file are defined within this file only.
- Constants used in more than one file are defined in a header file.
- Typedef names are suffixed with 'T'.
- Enum typedefs are suffixed with ' enum T'.
- Functions are named according to the 'TSL_[module]_[function]' scheme.
 - [module]: abbreviation of the file (acq, tim, dxs, etc.).
 - [function]: the first letter in each word is in upper case.

1.3 Coding rules

This section describes the coding rules used in the STMTouch touch sensing library source files.

1.3.1 General

- Source code complies with ANSI C standard.
- No warning after compilation. Any warning that cannot be eliminated is commented in the source code.
- ANSI standard data types are used and defined in the ANSI C header file <stdint.h>.
- No blocking code is present and all required waiting loops (polling loops) are controlled by a timeout.

1.3.2 Variable types

Specific variable types are already defined with a fixed type and size.

- The types that are used by all modules are defined in the **tsl_types.h** file.
- Other variable types are defined in their corresponding module header file.

1.3.3 Peripheral registers

The peripheral registers are accessed using the pointers described in the CMSIS device peripheral access layer header file.

577

UM1913 Rev 7 11/156

1.4 MISRA C 2004 compliance

1.4.1 Generalities

The C programming language is growing in importance for embedded systems. However, when it comes to developing code for safety-critical applications, this language has many drawbacks. There are several unspecified, implementation-defined, and undefined aspects of the C language that make it unsuited for developing safety-critical systems.

The motor industry software reliability association describes a subset of the C language well suited for developing safety-critical systems in [1] MISRA C 2004 Guidelines for the use of the C language in critical systems.

The STMTouch touch sensing library has been developed to be MISRA C 2004 compliant.

The following section describes how the STMTouch touch sensing library complies with MISRA C 2004 (as described in section *4.4 Claiming compliance of the standard* of [1]):

- A compliance matrix has been completed which shows how compliance has been enforced.
- The whole STMTouch touch sensing library source code is compliant with MISRA C 2004 rules.
- Deviations are documented. A list of all instances of rules not being followed is being maintained, and for each instance there is an appropriately signed-off deviation.
- All the issues listed in section 4.2 The programming language and coding context of the standard of [1], that need to be checked during the firmware development phase, have been addressed during the development of the STMTouch touch sensing library and appropriate measures have been taken.

1.4.2 Compliance matrix

The compliance of the STMTouch touch sensing library with MISRA C 2004 has been checked in two ways:

- using PC-lint tool for C/C++ (NT) versus 8.00v, copyright gimpel software 1985-2006
- performing regular code reviews.

The following table lists the MISRA C 2004 rules that are frequently violated in the code:

MISRA C 2004 Required/ Reason of deviance Summary rule number advisorv Compilers extensions All code shall conform are enabled. 1 1 to ISO 9899:1990 Required Comments starting with 1.2 standard C, with no "//" symbol for code extensions permitted. readability. A tag name shall be a Due to the usage of 5.4 Required unique identifier. objects methods.

Table 2. MISRA C 2004 rules not followed



Table 2. MISRA C 2004 rules not followed (continued)

MISRA C 2004	Required/	,	,
rule number	advisory	Summary	Reason of deviance
8.1	Required	No prototype seen. Functions shall always have prototype declarations and the prototype shall be visible at both the function definition.	This rule is violated as there is no functions prototypes for the objects methods.
10.1 10.2	Required	The value of an expression of integer/floating type shall not be implicitly converted to a different underlying type.	Code complexity
10.3	Required	The value of a complex expression of integer type may only be cast to a type that is narrower and of the same signedness as the underlying type of the expression.	Code complexity
10.5	Required	If the bitwise operators are applied to an operand of underlying type unsigned char or unsigned short, the result shall be immediately cast to the underlying type of the operand.	Use shift on signed quantity for the linear/rotary position
11.3	Advisory	A cast must not be performed between a pointer type and an integral type.	Needed when addressing memory mapped registers.
12.7	Required	Bitwise operators shall not be applied to operands whose underlying type is signed.	Shift of signed value needed
14.3	Required	Before preprocessing, a null statement shall only occur on a line by itself.	Usage of macros to simplify the code



Table 2. MISRA C 2004 rules not followed (continued)

MISRA C 2004 rule number	Required/ advisory	Summary	Reason of deviance
14.5	Required	The continue statement shall not be used.	Used to optimize the code speed execution.
19.11	Required	All macro identifiers in preprocessor directives shall be defined before use, except in ifdef and ifndef preprocessor directives and the defined() operator.	All parameters are checked in the check_config files



2 STMTouch touch sensing library

2.1 Supported microcontrollers and development tools

2.1.1 Supported microcontrollers

This STMTouch touch sensing library version supports the following microcontrollers and acquisition modes:

- Any STM32 microcontroller using the embedded touch sensing controller (TSC): STM32F0 Series, STM32F3 Series, STM32L0 Series and STM32L4 Series, all Arm^{®(a)}-based devices:
 - Surface charge-transfer acquisition principle managed by the touch sensing controller
 - Up to 24 channels (8 groups of 3 channels maximum)
 - Up to 8 channels can be acquired simultaneously
 - Spread spectrum feature
 - Programmable charge transfer frequency and max count value
- STM32L1 Series microcontrollers
 - Surface charge-transfer acquisition principle managed by:
 - Two timers + routing interface (hardware acquisition mode). This mode is not supported on STM32L1 Series microcontrollers featuring 256 K or less memory.
 - GPIOs + routing interface (software acquisition mode). This mode is supported by all microcontrollers.
 - Up to 34 channels
 - Up to 11 channels can be acquired simultaneously



2.1.2 Development tools

The STM32 microcontrollers are supported by a full range of development solutions from lead suppliers that deliver start-to-finish control of application development from a single integrated development environment.

The STMTouch touch sensing library has been developed with the following toolchains:

- **EWARM** (IAR™)
- MDK-ARM (Keil[®])
- SW4STM32 (AC6)

For more details about the compilers versions used, please see the STM32Cube package release note.

a. Arm is a registered trademark of Arm Limited (or its subsidiaries) in the US and/or elsewhere.

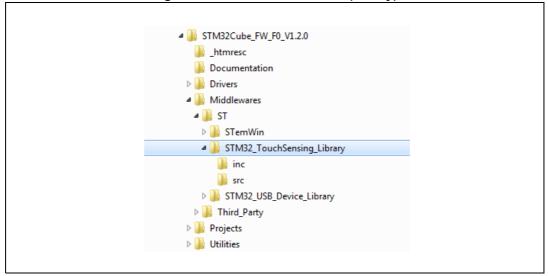


UM1913 Rev 7 15/156

2.2 Package description

The following snapshots show an example of installation inside the STM32CubeF0 package.

Figure 1. Installation folder 1/2 (library)



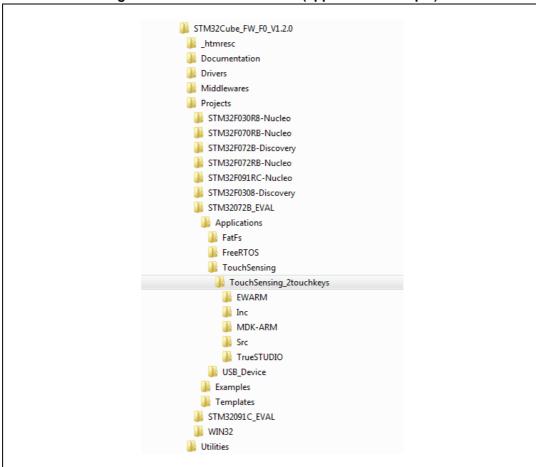


Figure 2. Installation folder 2/2 (application example)

2.3 Main features

- Supports proximity, touchkeys, linear and rotary touch sensors
- Environment change system (ECS)
- Detection time out (DTO)
- Detection exclusion system (DXS)
- Noise filter
- Unlimited number of sensors
- · Modular architecture allowing easy addition of new acquisitions or sensors
- Each sensor can have its own state machine
- · Simplified timing management
- Management of error during acquisition



UM1913 Rev 7 17/156

2.4 Architecture

2.4.1 Overview

The following figure shows the interactions between the STMTouch touch sensing library and the other firmware layers.

Level 2

Eval board and Discovery Kit demonstration

STM32Cube touch sensing examples

Level 1

STM32Cube touch sensing library

Level 0

HAL peripheral drivers

Figure 3. STM32Cube touch sensing library overview

2.4.2 STMTouch touch sensing library layers

The following figure shows a more detailed view of the different STM32Cube touch sensing library layers.

Application User application layer DTO DXS **Timing** STM32Cube touch sensing **Processing** layer **ECS Filters** Acquisition Acquisition **Acquisition** layer MCU₁ MCU₂ MSv39221V2

Figure 4. STMTouch touch sensing library detailed layers

The STMTouch touch sensing library is composed of three main layers:

- The acquisition layer
- The processing layer
- The configuration layer

The configuration layer corresponds to what the user needs to write in his application code in order to correctly use the STMTouch touch sensing library. This includes all the channels and sensors declarations, the parameters, etc.

The acquisition and processing layers are described in more details below.

2.4.3 Acquisition and processing layers

The following figure details the acquisition and processing layers and the different elements used in each layer.

UM1913 Rev 7 19/156

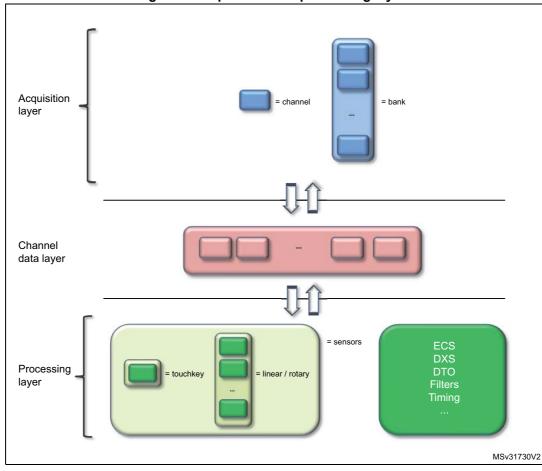


Figure 5. Acquisition and processing layers

The **acquisition layer** role is to perform the acquisition of the different channels. The result of the acquisition (measure and flags) is stored inside the channel data layer. These informations are accessed by the processing layer.

The acquisition layer has only access to the channels and banks. It does not have access to the sensors.

The **channel data layer** role is to share information between the acquisition and processing layers. It stores the result of the acquisition (measure) for each channel and store different informations coming from the processing layer (reference, delta, flags, etc.).

Located in RAM, the ChannelData structure is the only interface between the acquisition and processing layers.

This **processing layer** consists in executing each sensors state machine, executing the different data processing like ECS, DXS, DTO and storing any useful information for the acquisition layer inside the channel data area.

The processing layer does not have direct access to the channels and banks. This access is made through the sensors.



2.4.4 Header files inclusion

The figure below provides a global view of the STMTouch touch sensing library usage and the interaction between the different header files.

In the actual version of the STMTouch touch sensing library, the <XXX> is equal to "tsc" or "stm32l1xx".

Note:

To simplify the drawing, only the most important links are shown. For example the tsl_globals.h file is also included in different files.

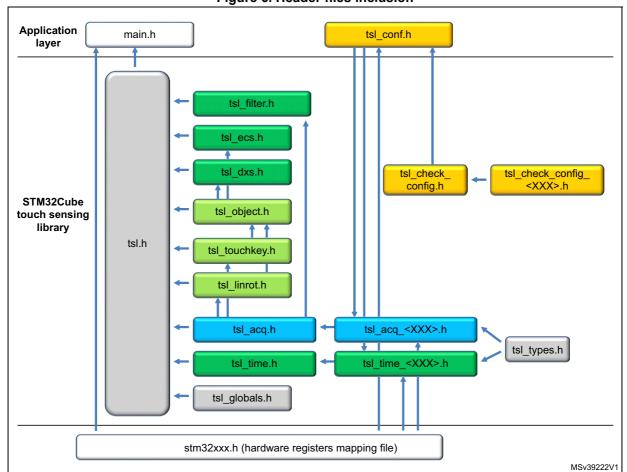


Figure 6. Header files inclusion

2.5 Channel

2.5.1 Principle

A channel is the basic element that is used to store several information like:

- where the source measurement can be found after the acquisition is performed (i.e. TSC_IOGxCR registers for TSC acquisition).
- where are stored the measure, the reference, the delta, flags etc.



UM1913 Rev 7 21/156

2.5.2 Resources

A channel is defined by 3 data structures:

- **TSL_ChannelSrc_T**: contains all information about the source measurement (index of the register containing the measurement, masks,...)
- **TSL_ChannelDest_T**: contains all information about the measurement destination (index in the channel data array).
- TSL ChannelData T: contains all data for the channel (measure, delta, reference, ...)

The channel depends on the acquisition technology. This is why the contents of this structures are not common for all acquisitions. They are declared in each acquisition header files (tsl acq <XXX>.h):

- tsl_acq_stm32l1xx_hw.h for STM32L1 Series microcontrollers using the hardware acquisition mode
- tsl_acq_stm32l1xx_sw.h for STM32L1 Series microcontrollers using the software acquisition mode
- tsl_acq_tsc.h for any STM32 microcontrollers featuring the TSC peripheral

The maximum number of channels is only limited by the device (memory size and channels supported).

The user must declare all the channels arrays in his application code. It can be done directly in the main.c file or in any other file.

2.5.3 Parameters

TSLPRM TOTAL CHANNELS

2.5.4 Usage example

The 3 channels structures must be declared in the application code.

Example of **channel source** array declaration for microcontrollers featuring TSC peripheral. This structure must always be placed in ROM.

Example of **channel destination** array declaration for microcontrollers featuring TSC peripheral. This structure must always be placed in ROM.

```
const TSL_ChannelDest_T MyChannels_Dest[TSLPRM_TOTAL_CHANNELS] =
{     CHANNEL_0_DEST },
     { CHANNEL_1_DEST },
     { CHANNEL_2_DEST }};
```

Note:

The "CHANNEL_x_SRC" and "CHANNEL_x_DEST" are "#define" constants and are used for readability. The values are acquisition dependant.



Example of **channel data** array declaration (i.e. channel data layer). This structure must always be placed in RAM.

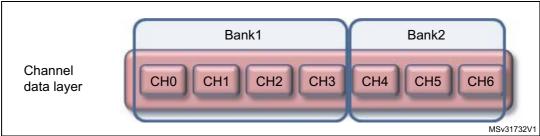
```
TSL_ChannelData_T MyChannels_Data[TSLPRM_TOTAL_CHANNELS];
```

Warning: When several banks are present, it is mandatory to declare all channels of each bank consecutively in the source and

destination structures.

Example:

Figure 7. Channels arrangement



Example of channel source array declaration for microcontrollers featuring TSC peripheral.

```
CONST TSL_ChannelSrc_T MyChannels_Src[TSLPRM_TOTAL_CHANNELS] =
{
// Bank 1
{    CHANNEL_0_SRC,    CHANNEL_0_IO_MSK,    CHANNEL_0_GRP_MSK },
{    CHANNEL_1_SRC,    CHANNEL_1_IO_MSK,    CHANNEL_1_GRP_MSK },
{    CHANNEL_2_SRC,    CHANNEL_2_IO_MSK,    CHANNEL_2_GRP_MSK },
{    CHANNEL_3_SRC,    CHANNEL_3_IO_MSK,    CHANNEL_3_GRP_MSK },
// Bank 2
{    CHANNEL_4_SRC,    CHANNEL_4_IO_MSK,    CHANNEL_4_GRP_MSK },
{    CHANNEL_5_SRC,    CHANNEL_5_IO_MSK,    CHANNEL_5_GRP_MSK },
{    CHANNEL_6_SRC,    CHANNEL_6_IO_MSK,    CHANNEL_6_GRP_MSK }
};
```

57

23/156

2.6 Bank

2.6.1 Principle

A bank is a group of channels that are acquired simultaneously. The number of channels in the bank is variable.

2.6.2 Resources

The bank data are held by only one structure:

- TSL_Bank_T
- The bank depends also on the acquisition technology. Structures are declared in each acquisition header files (tsl_acq_<XXX>.h):

The maximum number of banks is only limited by the device.

The user must declare all the bank arrays in his application code. It can be done directly in the main.c file or in any other file.

The banks are used mainly by the functions described below. Some functions are common whatever the device and acquisition technology. Some others are dependent on the device.

Common functions:

- TSL_acq_BankGetResult()
- TSL_acq_BankCalibrate()

Device dependent functions:

- TSL_acq_BankConfig()
- TSL acg BankStartAcg()
- TSL_acq_BankWaitEOC()

2.6.3 Parameters

TSLPRM_TOTAL_BANKS

2.6.4 Usage example

Example of 3 banks declaration for microcontrollers featuring TSC peripheral:

```
CONST TSL_Bank_T MyBanks[TSLPRM_TOTAL_BANKS] = {
    {&MyChannels_Src[0], &MyChannels_Dest[0], MyChannels_Data,
BANK_0_NBCHANNELS, BANK_0_MSK_CHANNELS, BANK_0_MSK_GROUPS},
    {&MyChannels_Src[1], &MyChannels_Dest[1], MyChannels_Data,
BANK_1_NBCHANNELS, BANK_1_MSK_CHANNELS, BANK_1_MSK_GROUPS},
    {&MyChannels_Src[2], &MyChannels_Dest[2], MyChannels_Data,
BANK_2_NBCHANNELS, BANK_2_MSK_CHANNELS, BANK_2_MSK_GROUPS}
};
```

2.7 Objects

2.7.1 Principle

The term "object" or "sensor" stands for any sensor type (touchkeys, linear and rotary touch sensors, etc.) supported by the STMTouch touch sensing library.

2.7.2 Resources

All processing that affect the sensors in general are defined in:

- tsl_object.c
- tsl_object.h

The functions are:

- TSL obj GroupInit()
- TSL_obj_GroupProcess()
- TSL_obj_SetGlobalObj()

A sensor is described by the structures:

- TSL_Object_T
- TSL_ObjectGroup_T

2.7.3 Parameters

TSLPRM_TOTAL_OBJECTS

2.7.4 Usage example

First, all touchkeys, linear and rotary touch sensors (described after) used in the application must be described first as 'generic' sensors or objects.

Example:

```
// Mix of touchkeys and Linear touch sensors
const TSL_Object_T MyObjects[TSLPRM_TOTAL_OBJECTS] =
{
    // TKeys
    { TSL_OBJ_TOUCHKEYB, (TSL_TouchKeyB_T *) &MyTKeys[0] },
    { TSL_OBJ_TOUCHKEYB, (TSL_TouchKeyB_T *) &MyTKeys[1] },
    // Linear touch sensors
    { TSL_OBJ_LINEARB, (TSL_LinRotB_T *) &MyLinRots[0] }
};
```

These objects must be placed in ROM memory.

Once this done, it is necessary to create at least one group of sensors. Groups of sensors are used by the different processing routines (ECS, DXS, etc.).

These groups of objects must be placed in RAM.

Example:

```
TSL_ObjectGroup_T MyObjGroup_All = {
   MyObjects,
```



UM1913 Rev 7 25/156

```
3,
0,
TSL_STATE_NOT_CHANGED
};
```

Then, all the sensors must be initialized and "processed". This is done in the main function of the application:

```
int main(void) {
    ...
    TSL_obj_GroupInit(&MyObjGroup_All);
    ...
    while (1) {
        ...
        TSL_obj_GroupProcess(&MyObjGroup_All);
        ...
    }
}
```

2.8 Touchkey sensor

2.8.1 Principle

The touchkey sensor is composed of only one channel. It acts as a simple "button" with two states RELEASE and DETECT (or TOUCH if DXS is enabled).

2.8.2 Resources

All the functions related to this sensor are described in the files:

- tsl touchkey.c
- tsl_touchkey.h

Two types of touchkey sensor are available:

- Basic: defined by the TSL_TouchKeyB_T structure
- Extended: defined by the TSL_TouchKey_T structure

Two functions (called methods) are used to initialize the sensor parameters and to run the sensor state machine:

- TSL tkey Init()
- TSL_tkey_Process()

The difference between the "basic" and "extended" types concerns the usage of the methods and sensor state machine.

For the "basic" sensor, the methods and state machine are those used in the **TSL_Params** structure.

For the "extended" sensor, the methods and state machine are those declared in their own structure.



2.8.3 Parameters

TSLPRM_TOTAL_TKEYS

2.8.4 Usage example

The user must declare these methods in the application code.

Note:

One can also use one's own initialization and process functions instead:

```
const TSL_TouchKeyMethods_T MyTKeys_Methods =
{
   TSL_tkey_Init,
   TSL_tkey_Process
};
```

MyTKeys_StateMachine, &MyTKeys_Methods },

MyTKeys StateMachine, &MyTKeys Methods }

The declaration of the touchkey sensor is done by the user in the application code:

Example with "basic" sensor:

{ &MyTKeys_Data[2], &MyTKeys_Param[2], &MyChannels_Data[2],

577

};

UM1913 Rev 7 27/156

2.9 Linear and rotary touch sensors

2.9.1 Principle

The linear and rotary touch sensors are like a touchkey sensor except that they are composed of a variable number of channels. The difference between the linear and rotary touch sensors is how the electrodes are organized together.

The linear and rotary touch sensors have additional fields in their structure compared to touchkey sensors:

- Number of channels
- Delta coefficient table
- Position offset table
- Sector computation parameter
- Position correction parameter for linear sensor

The last 3 fields are used to calculate the position.

2.9.2 Number of channels

Only 1, 3, 4, 5 and 6 channels are supported today by the STMTouch touch sensing library. Additional number of channels can be added by the end-user.

Note:

A linear touch sensor with 1 channel is equivalent to one touchkey sensor. When an application uses both touchkey sensor and linear and rotary sensor, it is better to use touchkeys with a 1-channel linear touch sensor. In this case the gain in memory size is important as the touchkey sensor state machine is not used.

2.9.3 Delta coefficient table

The delta coefficient table is used to adjust each channel of the linear and rotary touch sensors. Each value is a 16-bit integer. The MSB is the integer part, the LSB is the real part.

Examples:

To apply a factor of 1.10:

- MSB equal 0x01
- LSB equal 0x1A (0.10 x 256 = 25.6 -> rounded to 26 = 0x1A)

To apply a factor 1.00:

- MSB equal 0x01
- LSB equal 0x00

To apply a factor 0.90:

- MSB equal 0x00
- LSB equal 0xE6 (0.90 x 256 = 230.4 -> rounded to 230 = 0xE6)

This results in the following delta coefficient table:

```
CONST uint16_t MyLinRot0_DeltaCoeff[3] = {0x011A, 0x0100, 0x00E6};
```

The number of delta coefficient table is not limited. The same delta coefficient table can be shared by several linear and rotary touch sensors.



2.9.4 Electrodes placement

The placement (design) of the electrodes can be done in three different manners:

1. Mono electrode design

The number of electrodes is equivalent to the number of channels. This design is used for linear and rotary touch sensors.

Abbreviations: LIN_M1, LIN_M2 and ROT_M

Examples:

- CH1 CH2 CH3
- CH1 CH2 CH3 CH4
- CH1 CH2 CH3 CH4 CH5
- Dual electrode design

All the electrodes are duplicated and interlaced together in order to increase the touch area.

This design is used for linear and rotary touch sensors composed with at least 5 channels.

Abbreviation: **ROT_D**Examples with 5 channels:

- CH1 CH2 CH3 CH4 CH5 CH1 CH3 CH5 CH2 CH4
- CH1 CH2 CH3 CH4 CH5 CH2 CH4 CH1 CH3 CH5
- CH1 CH2 CH3 CH4 CH5 CH3 CH1 CH4 CH2 CH5
- Half-ended electrode design

The first electrode is duplicated and the replica is placed at the end. The size of the first and last electrode is **half the size** of the other electrodes. This design is used for **linear sensors only**. The 0 and 255 positions are obtained more easily compared to the Mono electrodes design.

Abbreviation: LIN_H

Examples:

- ch1 CH2 CH3 ch1
- ch1 CH2 CH3 CH4 ch1
- ch1 CH2 CH3 CH4 CH5 ch1

The following figure summarizes the different electrodes designs we can have on linear and rotary touch sensors:

57

UM1913 Rev 7 29/156

Rotary ROT M LIN_M1 Mono LIN_M2 electrodes CH2 CH3 design LIN H Half-ended electrodes design ROT_D Dual electrodes design MSv31733V2

Figure 8. Electrodes designs

Positions 0 and 255

Special care must be taken for the 0 and 255 positions on linear sensors. These positions are placed differently depending on the electrodes design used:

- **LIN_M1**: the 0 and 255 positions are placed completely at the sensor's **extremities**. These positions can be obtain with difficulty if the electrodes are too big or if they are separated by an important space.
- LIN_M2, LIN_H: the 0 position is placed between the first and second electrodes. The 255 position is placed between the last two electrodes.
- ROT_M and ROT_D: the 0 and 255 positions are always placed between the first and the last electrodes.

The following figures summarizes the different placements of the 0 and 255 positions with 4 channels sensors:

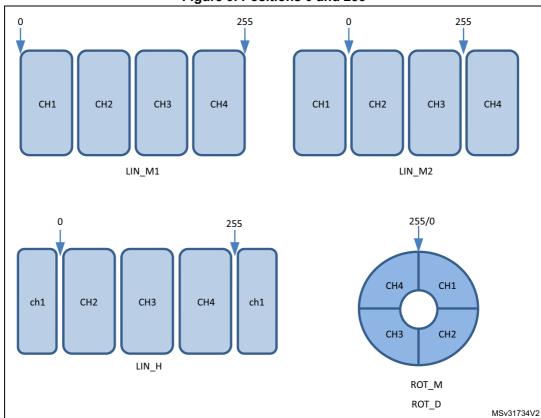


Figure 9. Positions 0 and 255

The following table summarizes the different linear and rotary touch sensors electrodes designs supported by the STMTouch touch sensing library:

Number LIN_M1 LIN_M2 LIN_H ROT_M ROT_D of Channels 3 Yes Yes Yes Yes No 4 Yes Yes Yes Yes No 5 Yes Yes Yes Yes Yes 6 Yes Yes Yes Yes No

Table 3. Supported linear and rotary touch sensors

Each supported electrode design is described by 3 fields in the ${\sf TSL_LinRot_T}$ or ${\sf TSL_LinRotB_T}$ structures:

- Position offset table
- Sector computation parameter
- Position correction parameter for linear sensor

These 3 fields are defined in the **tsl_linrot.c** and **tsl_linrot.h** files and follow the naming convention:

Position offset table: TSL_POSOFF_nCH_[LIN|ROT]_[M1|M2|H|D]



UM1913 Rev 7 31/156

 $Sector\ computation\ parameter:\ TSL_SCTCOMP_nCH_[LIN|ROT]_[M1|M2|H|D]$

Position correction parameter for linear sensor: TSL_POSCORR_nCH_LIN_[M1|M2|H|D]

With:

- n = number of channels
- LIN = linear sensor
- ROT = rotary sensor
- M1 = mono electrodes design with 0/255 position at extremities
- M2 = mono electrodes design
- H = half-ended electrodes design
- D = dual electrodes design

In order to gain memory space, each table is only compiled if its corresponding parameter is set in the configuration file:

TSLPRM_USE_nCH_[LIN|ROT]_[M1|M2|H|D]

2.9.5 Resources

All the functions related to this sensor are described in the files:

- tsl linrot.c
- tsl_linrot.h

Two types of linear and rotary sensor are available:

- basic: defined by the TSL_LinRotB_T structure
- extended: defined by the TSL_LinRot_T structure

The difference between "basic" and "extended" is the same as for the touchkey sensor.

Three functions (called methods) are used to initialized the sensor parameters, run the sensor state machine and calculate the position.

- TSL_linrot_lnit()
- TSL linrot Process()
- TSL_linrot_CalcPos()

2.9.6 Parameters

TSLPRM TOTAL LINROTS

2.9.7 Usage example

The user must declared these methods in the application code.

Note:

One can also use one's own initialization and process functions instead:

```
CONST TSL_LinRotMethods_T MyLinRots_Methods =
{
   TSL_linrot_Init,
   TSL_linrot_Process,
   TSL_linrot_CalcPos
};
```

The declaration of the linear and rotary sensor is done by the user in the application code in the same manner as for touchkey sensor.

Example with 2 "basic" linear touch sensors, one with 3 channels half-ended and the other with 5 channels mono electrodes design:

```
CONST TSL_LinRotB_T MyLinRots[2] =
  // LinRot sensor 0
 &MyLinRots_Data[0],
  &MyLinRots_Param[0],
  &MyChannels_Data[CHANNEL_9_DEST],
 3, // Number of channels
 MyLinRot0 DeltaCoeff, // Delta coefficient table
  (TSL_tsignPosition_T *)TSL_POSOFF_3CH_LIN_H, // Position table
 TSL_SCTCOMP_3CH_LIN_H, // Sector compensation
 TSL POSCORR 3CH LIN H, // Position correction
  // LinRot sensor 1
 &MyLinRots_Data[1],
 &MyLinRots Param[1],
 &MyChannels Data[CHANNEL 12 DEST],
  5, // Number of channels
 MyLinRot1_DeltaCoeff, // Delta coefficient table
  (TSL tsignPosition T *)TSL POSOFF 5CH LIN M2, // Position table
 TSL_SCTCOMP_5CH_LIN_M2, // Sector compensation
 TSL POSCORR 5CH LIN M2 // Position correction
};
```

Example of one "extended" (i.e. having its own state machine and methods) linear touch sensor with 3 channels half-ended:

```
CONST TSL_LinRot_T MyLinRots[1] =
{
    // LinRot sensor 0
    &MyLinRots_Data[0],
    &MyLinRots_Param[0],
    &MyChannels_Data[CHANNEL_0_DEST],
    3, // Number of channels
    MyLinRot0_DeltaCoeff,
    (TSL_tsignPosition_T *)TSL_POSOFF_3CH_LIN_H,
    TSL_SCTCOMP_3CH_LIN_H,
    TSL_POSCORR_3CH_LIN_H,
    MyLinRots_StateMachine, // Specific state machine
    &MyLinRots_Methods // Specific methods
};
```

Example of one "extended" rotary touch sensor with 3 channels mono electrode design:

```
CONST TSL_LinRot_T MyLinRots[0] =
{
```

577

UM1913 Rev 7 33/156

```
// LinRot sensor 0
&MyLinRots_Data[0],
&MyLinRots_Param[0],
&MyChannels_Data[CHANNEL_0_DEST],
3, // Number of channels
MyLinRot0_DeltaCoeff,
(TSL_tsignPosition_T *)TSL_POSOFF_3CH_ROT_M,
TSL_SCTCOMP_3CH_ROT_M,
0, // No position correction needed on a Rotary sensor
MyLinRots_StateMachine, // Specific state machine
&MyLinRots_Methods // Specific methods
};
```

2.10 Main state machine

The main state machine is managed by the user in the application layer. A set of functions are available to accomplish this task. The main state machine can be defined with polling or with interrupt modes, using one or several banks. The modularity of the STMTouch touch sensing library allows also the application code to be inserted between acquisition and processing tasks. Several examples are given below.

The functions to use for the acquisition are:

- TSL_acq_BankConfig()
- TSL_acq_BankStartAcq()
- TSL_acq_BankWaitEOC()
- TSL_acq_BankGetResult()

These functions are device dependent and are described in the tsl_acq_<XXX>.c files.

The functions to use for the processing are:

- TSL_obj_GroupProcess()
- TSL ecs Process()
- TSL_dxs_FirstObj()

Other functions that can be used during the processing:

- TSL_tim_CheckDelay_ms()
- TSL_obj_SetGlobalObj()
- TSL tkey GetStateId()
- TSL_tkey_GetStateMask()
- TSL_linrot_SetStateOff()
- TSL linrot SetStateCalibration()

The main state machine principle is illustrated by the figure below:

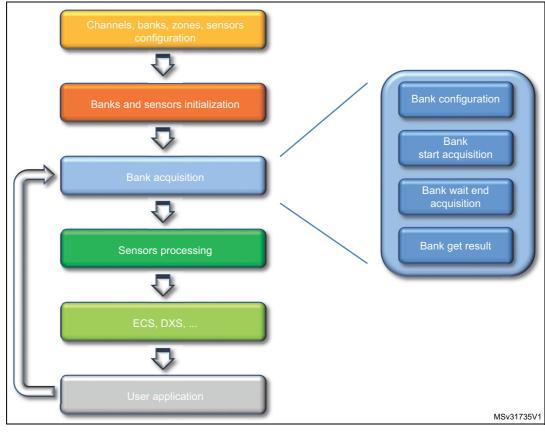


Figure 10. Main state machine

The main state machine steps are:

- 1. The **channels**, **banks and sensors configuration** step are used to declare all the different elements. This is done in the global declaration section in the main application file. See the section associated to each element for more details.
- 2. The **banks and sensors initialization** step is used to initialize the STMTouch touch sensing library modules. The sensors parameters are initialized with their default value defined in the configuration files.
- 3. **The banks acquisition** step is used to perform the acquisition of the banks. It is composed of 4 sub-steps:
 - configuration: used to configure all channels of the bank
 - start acquisition: used to launch the measurement on all channels of the bank
 - wait end acquisition: used to wait the end of acquisition of all channels of the bank
 - get result: used to read all the channels measurements and to store them in the channel data layer.
- 4. **The sensors processing** step is used to execute the state machine of the sensors.

577

UM1913 Rev 7 35/156

Note: The debouncing, Detection Time Out and re-calibration are automatically performed inside this step.

- 5. The **ECS**, **DXS** step is used to execute other algorithms that are not performed in the sensor state machine like the ECS, DXS, other filters, etc. This step is optional and it can be executed at certain time intervals (mainly for ECS).
- 6. The **user application** step is used to execute the application layer (read the sensors state, decide which actions to perform, manage ERROR states, etc.). The user application can also be placed between other steps, for example it can be done between the "sensors processing" step and the "ECS/DXS".

There are multiple manners to perform the main state machine. The following figures show some examples with two banks.

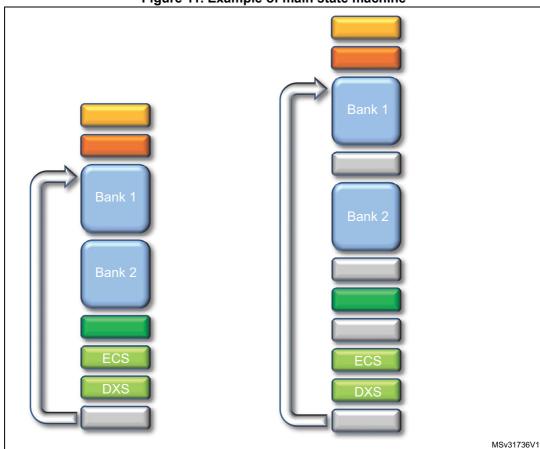


Figure 11. Example of main state machine



2.11 Sensors state machine

2.11.1 Overview

The state machine is managed in the files:

- tsl_touchkey.c and tsl_touchkey.h for the touchkey sensors
- tsl_linrot.c and tsl_linrot.h for the linear and rotary touch sensors

There is a total of **20 states** defined in the **TSL_StateId_enum_T** structure.

The following figure shows the simplified state machine used by any sensor (for clarity not all the connections between states are shown).

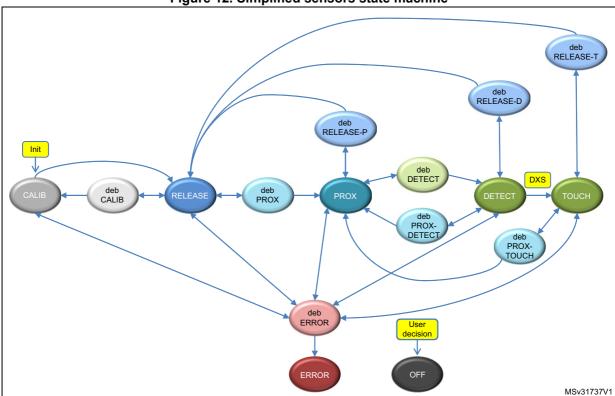


Figure 12. Simplified sensors state machine

2.11.2 States constant table

Each state ID is associated to a mask and a function. The association STATE_ID-mask-function is made in the user application code using a constant table of the **TSL_State_T** type. The name of this table is free and user can give any name he wants. If no function is needed simply put a zero instead of the function name.

Here below an example of touchkey sensors state machine:

577

UM1913 Rev 7 37/156

```
//-----
// Calibration states
/* 0 */ { TSL_STATEMASK_CALIB, TSL_tkey_CalibrationStateProcess },
/* 1 */ { TSL STATEMASK DEB CALIB, TSL tkey DebCalibrationStateProcess },
// RELEASE states
/* 2 */ { TSL_STATEMASK_RELEASE,
                                         TSL_tkey_ReleaseStateProcess },
#if TSLPRM USE PROX > 0
/* 3 */ { TSL STATEMASK DEB RELEASE PROX,
TSL tkey DebReleaseProxStateProcess },
/* 3 */ { TSL STATEMASK DEB RELEASE PROX, 0 },
#endif
/* 4 */ { TSL STATEMASK DEB RELEASE DETECT,
TSL tkey DebReleaseDetectStateProcess },
/* 5 */ { TSL_STATEMASK_DEB_RELEASE_TOUCH,
TSL_tkey_DebReleaseTouchStateProcess },
#if TSLPRM USE PROX > 0
// Proximity states
/* 6 */ { TSL_STATEMASK_PROX,
                                           TSL_tkey_ProxStateProcess },
/* 7 */ { TSL STATEMASK DEB PROX,
                                         TSL tkey DebProxStateProcess },
/* 8 */ { TSL STATEMASK DEB PROX DETECT,
TSL_tkey_DebProxDetectStateProcess },
/* 9 */ { TSL STATEMASK DEB PROX TOUCH,
TSL tkey DebProxTouchStateProcess },
#else
/* 6 */ { TSL_STATEMASK_PROX,
                                           0 },
/* 7 */ { TSL STATEMASK DEB PROX,
                                           0 },
/* 8 */ { TSL_STATEMASK_DEB_PROX_DETECT,
                                           0 },
/* 9 */ { TSL_STATEMASK_DEB_PROX_TOUCH,
                                           0 },
#endif
// DETECT states
/* 10 */ { TSL_STATEMASK_DETECT,
                                          TSL_tkey_DetectStateProcess },
/* 11 */ { TSL_STATEMASK_DEB_DETECT,
                                         TSL_tkey_DebDetectStateProcess
},
// TOUCH state
/* 12 */ { TSL_STATEMASK_TOUCH,
                                           TSL tkey TouchStateProcess },
// ERROR states
/* 13 */ { TSL STATEMASK ERROR,
                                           MyTKeys ErrorStateProcess },
/* 14 */ { TSL STATEMASK DEB ERROR CALIB,
                                           TSL tkey DebErrorStateProcess
},
/* 15 */ { TSL STATEMASK DEB ERROR RELEASE, TSL tkey DebErrorStateProcess
},
/* 16 */ { TSL_STATEMASK_DEB_ERROR_PROX,
                                           TSL_tkey_DebErrorStateProcess
/* 17 */ { TSL STATEMASK DEB ERROR DETECT,
                                           TSL tkey DebErrorStateProcess
```

The STMTouch touch sensing library contains all the functions needed to manage each state. However the user can copy and adapt one or several functions to fit the requirements of his application.

Example:

```
/* 0 */ { TSL_STATEMASK_CALIB, MyTkeys_CalibrationStateProcess },
```

Note:

The two functions used to manage the ERROR and OFF states are not part of the STMTouch touch sensing library. These functions are managed by the application.

For linear and rotary sensor state machine, it is the same principle. The functions used to manage each state start with the prefix "TSL_linrot_":

```
CONST TSL_State_T MyLinRots_StateMachine[] =
{
// Calibration states
/* 0 */ { TSL_STATEMASK_CALIB, TSL_linrot_CalibrationStateProcess },
```



UM1913 Rev 7 39/156

2.11.3 States detail

The two tables below show the detail of how each state is entered following the thresholds measured.

Table 4. Detailed sensors states 1/2

Previous state	all excepted 13	all excepted 13	2p,10p,12p,3, 4p,5p,7,8,9, 11p	2,4,11	2p,6,4p,7,8,1 1p	DXS,5	DXS,5p,9	2,2p,1	2,2p,6,10, 10p,12,12p ,0,1418
state nb	2	2 p	6	10	10p	12	12p	0	13
Current state	RELEASE	RELEASE with PROX	PROX	DETECT	DETECT with PROX	тоисн	TOUCH with PROX	CALIB	ERROR
Delta									
DETECT IN Th	deb DETECT or DETECT+DTO	deb DETECT or DETECT+DTO	deb DETECT or DETECT+DTO	same or	same or	same or	same or		
ı		deb PROX or	sama	CALIB if DTO	CALIB if DTO	CALIB if DTO	CALIB if DTO		
DETECT OUT Th PROX IN Th	same	PROX+DTO	same or CALIB if DTO		deb PROX- DETECT		deb PROX- TOUCH	RELEASE or	same
-	Jame	same		deb RELEASE-	or PROX+DTO	deb RELEASE-	or PROX+DTO	ERROR	danie
PROX OUT Th		dame	deb RELEASE-	DETECT or RELEASE	deb RELEASE-	TOUCH or RELEASE	deb RELEASE-		
CALIB Th	deb CALIB or CALIB	deb CALIB or CALIB	PROX or RELEASE		DETECT or RELEASE	NELLAGE	TOUCH or RELEASE		
if ACQ ERROR	deb ERROR or ERROR	deb ERROR or ERROR	deb ERROR or ERROR	deb ERROR or ERROR	deb ERROR or ERROR	deb ERROR or ERROR	deb ERROR or ERROR	deb ERROR or ERROR	same



1

				Tabl	e 5. Detail	ed sensor	s states 2/	2				
Previous state	6	10	10p,8	12	12p,9	2p,11p	10p	12p	2	2p,6,7	2,2p	2,2p,6,10, 10p,12,12 p,0
state nb	3	4	4p	5	5p	7	8	9	11	11p	1	1418
Currentstate	deb RE LEASE- PROX	deb RE LEASE- DETECT	deb RE LEASE- DETECT with PROX	deb RE LEASE- TOUCH	deb RE LEASE- TOUCH with PROX	deb PROX	deb PROX- DETECT	deb PROX- TOUCH	deb DETECT	deb DETECT with PROX	deb CALIB	deb ERROR
Delta			1									
DETECT IN Th		DETECT	DETECT	TOUCH	TOUCH	deb DETECT or DETECT+ DTO	DETECT	TOUCH	same or DETECT+ DTO	same or DETECT+ DTO		
-	PROX					same or				deb PROX	RELEAS	DE
DETECT OUT Th PROX IN Th			PROX		PROX	PROX+ DTO	same or PROX+	same or PROX+		or PROX+ DTO	E	RE LEASE PROX DETECT
-		same		same			DTO	DTO	RELEAS E			TOUCH CALIB
PROX OUT Th	same	or RELEAS E	same	or RELEAS E	same	RELEAS	deb RELEAS	deb RELEAS		RELEAS		
CALIB Th	or RELEAS E		or RELEAS E		or E RELEAS E	E	E- DETECT or RELEAS E	E- TOUCH or RELEAS E		Е	same or CALIB	
if ACQ ERROR	PROX	DETECT	DETECT	TOUCH	TOUCH	RELEAS E	DETECT	TOUCH	RELEAS E	RELEAS E	RELEAS E	ERROR

2.11.4 CALIBRATION state

It consists in calculating the reference for all the channels of a sensor. An average of a certain number of measurements is done.

The number of measurement samples to use for the calibration is defined by the **TSLPRM_CALIB_SAMPLES** parameter.

After reset the initialization method of each object is called. This method initializes the sensor parameters and then goes in the CALIBRATION state. After the calibration is done, the sensor goes in the RELEASE state or ERROR state if an error occurred.

Related functions:

- TSL tkey CalibrationStateProcess()
- TSL_linrot_CalibrationStateProcess()
- TSL tkey SetStateCalibration()
- TSL_linrot_SetStateCalibration()

Calibration delay

If a noise filter is used, it is necessary to wait a certain amount of measurement samples before to start the reference calculation. This number of samples to wait is defined by the **TSLPRM_CALIB_DELAY** parameter.

Re-calibration

If the calibration threshold is reached while in RELEASE state, a new calibration is performed. This "re-calibration" prevents the application to get stuck if something touches permanently the sensor like a drop of water for example or if the sensor is touched upon power-on.

2.11.5 RELEASE state

Corresponds to the "idle" state of the sensor when no presence is detected.

Related functions:

- TSL_tkey_ReleaseStateProcess()
- TSL linrot ReleaseStateProcess()

2.11.6 PROXIMITY state

This state is optional and is enabled or disabled using the **TSLPRM_USE_PROX** parameter.

Related functions:

- TSL tkey ProxStateProcess()
- TSL linrot ProxStateProcess()

2.11.7 DETECT state

It is the "normal" state when the sensor is touched.



Related functions:

- TSL_tkey_DetectStateProcess()
- TSL_linrot_DetectStateProcess()

2.11.8 TOUCH state

Same as DETECT state excepted that it is entered only by the DXS processing. If the DXS is not used this state is never entered.

Related functions:

- TSL tkey TouchStateProcess()
- TSL_linrot_TouchStateProcess()

2.11.9 ERROR state

It is used to catch all acquisition errors detected in the other states.

The management of this state must be performed at application level.

2.11.10 OFF state

It is used to inform the acquisition module to stop the burst and/or acquisition on the sensor's channels.

The management of this state must be performed at application level.

2.11.11 DEBOUNCE states

The debounce is optional and is enabled/disabled using the different debounce counters parameters: TSLPRM_DEBOUNCE_PROX, TSLPRM_DEBOUNCE_DETECT, TSLPRM_DEBOUNCE_RELEASE, TSLPRM_DEBOUNCE_CALIB, TSLPRM_DEBOUNCE_ERROR

The debounce is off if the corresponding parameter is equal to zero.

2.11.12 Reading the current state

The current state can be obtained by using the functions:

For touchkey sensor:

- TSL tkey GetStateId()
- TSL_tkey_GetStateMask()

For linear and rotary sensor:

- TSL_linrot_GetStateId()
- TSL linrot GetStateMask()

The functions **TSL_tkey_lsChanged()** or **TSL_linrot_lsChanged()** allows the check if a sensor state has changed.

You can also directly read the state inside the sensor data structure:

if MyTKeys[0].p Data->StateId == TSL STATEID DETECT)



UM1913 Rev 7

43/156

2.11.13 Enabling a specific state

It is possible to enter directly in the calibration, OFF and OFF with "burst only" states. The OFF with "burst only" state consists in only bursting the electrode without performing acquisition on it. It can be used in specific cases to improve the robustness against noise or to keep optimum sensor sensitivity.

This is done by using the following functions:

For touchkey sensor:

- TSL_tkey_SetStateCalibration()
- TSL_tkey_SetStateOff()
- TSL_tkey_SetStateBurstOnly()

For linear and rotary sensor:

- TSL_linrot_SetStateCalibration()
- TSL linrot SetStateOff()
- TSL linrot SetStateBurstOnly()

2.12 Environment change system (ECS)

2.12.1 Principle

Power supply voltage, temperature and air humidity may induce a slow variation of the measured signal. The environment change system (ECS) is used to adapt the reference to these environment changes.

The ECS processing is based on an infinite response digital low pass filter of the first order (IIR filter):

$$Y(n) = K \times X(n) + (1 - K) \times Y(n - 1)$$

with:

Y = reference

X = acquisition value (last measurement)

K = coefficient.

The higher value is K, the faster is the response time. Two default K coefficients are available to obtain fast and slow responses.

The sampling frequency is programmable using a timing utility routine (see example below).

If the sensor is in PROX, DETECT or TOUCH states, the ECS is disabled for the duration of the detection timeout or for the duration of the touch (whichever ends first).

When the ECS is disabled, Yn=Yn-1

As soon as the recalibration times out or the detection ends, the filter is set active again.

57

The diagram in *Figure 13* shows K filter effect to staircase on reference. The horizontal axis represents the number of calls to ECS_process() api. So the response time depends on the ECS_DELAY.

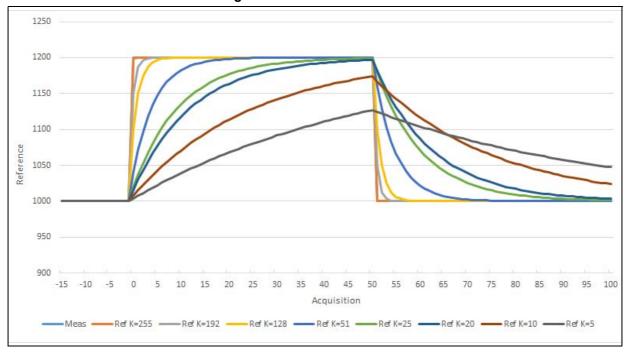


Figure 13. Reference versus K filter value

2.12.2 Resources

The ECS functions are provided in the files:

- tsl_ecs.c
- tsl_ecs.h

The functions are:

- TSL_ecs_Process(): main function to be used by the user
- TSL_ecs_CalcK(): additional function
- TSL_ecs_ProcessK(): additional function

2.12.3 Parameters

- TSLPRM ECS K FAST
- TSLPRM_ECS_K_SLOW
- TSLPRM_ECS_DELAY

2.12.4 Usage example

The ECS processing is usually performed in the main state machine at regular time intervals defined by the user. But it can be done also in interrupt routines. It must be performed after the sensors state machine is processed.

577

The ECS is activated only when all the sensors are in RELEASE, ERROR or OFF states, with at least one sensor in RELEASE state. It can also be delayed from milli-seconds to few seconds.

The ECS processing is performed on a group of sensors defined by the user. Different groups can be created and ECS can be applied on these groups with different K coefficients.

It is user's choice to decide the best thing to do for his application.

The simplest way is to call the **TSL_ecs_Process()** function in the main application loop using the default K coefficients defined in the configuration file:

```
TSL_ecs_Process(&MyObjGroup);
```

To call this functions at regular time intervals you can use the provide timing routine TSL_tim_CheckDelay_ms().

Example with ECS executed every 100ms:

```
TSL_tTick_ms_T time_ECS_tick;
int main(void) {
  while (1) {
    ...
    // ECS every 100 ms
    if (TSL_tim_CheckDelay_ms(100, &time_ECS_tick) == TSL_STATUS_OK)
    {
        TSL_ecs_Process(&MyObjGroup);
    }
    ...
}
```

The **TSL_ecs_ProcessK()** function allows the use of a K coefficient different than the default value:

```
if (TSL_tim_CheckDelay_ms(100, &time_ECS_tick) == TSL_STATUS_OK)
{
  if ((MyObjGroup->StateMask & TSL_STATE_RELEASE_BIT_MASK) &&
    !(MyObjGroup->StateMask & TSL_STATEMASK_ACTIVE))
  {
    TSL_ecs_ProcessK(&MyObjGroup, 120);
  }
}
```

To update TSL_Globals.Tick_ms, system tick handler must be updated as follows:

```
void SysTick_Handler(void)
{
   /* USER CODE BEGIN SysTick_IRQn 0 */
   /* USER CODE END SysTick_IRQn 0 */
   HAL_IncTick();
   HAL_SYSTICK_IRQHandler();
   /* USER CODE BEGIN SysTick IRQn 1 */
```

```
// TSL timing for ECS, DTO, ...
TSL_tim_ProcessIT();

/* USER CODE END SysTick_IRQn 1 */
}
```

2.13 Detection exclusion system (DXS)

2.13.1 Principle

The DXS processing is used to prevent several sensors to be in the DETECT state at the same time. This may happen if the sensors are closed to each other or if their sensitivity is too high. This can be useful also in some applications to prevent the user to touch at the same time several sensors with "opposite" meaning (volume up and volume down for example).

The first sensor in the group of sensors has the priority and enters in the DETECT state (with the DxSLock flag set). The other sensors are "blocked" and enter instead in the TOUCH state.

Note:

A particular care must be taken when designing sensors that are shared between multiple DXS groups. The sensor that is assigned in the DETECT state depends on the sensors position in the DXS groups and also on the order of the DXS groups processing. See the examples 1 and 2 for more detail.

The figure below illustrates the difference in behavior for a group of 3 sensors (touchkeys) when the DXS is OFF and ON. The three touchkeys are part of the same DXS group.

Note:

The touchkeys can be replaced by a linear or a rotary sensor.



UM1913 Rev 7

47/156

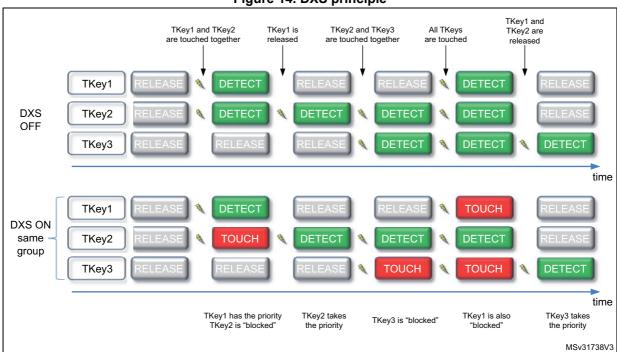


Figure 14. DXS principle

Example 1: 3 sensors with one shared between two groups.

In this example the group1 is composed of the two sensors s1 and s2 in this order and the group2 of the two sensors s2 and s3 in this order.

The DXS groups are processed in this order: group1 first and then group2.

We can see in the step DXS5 that the sensor 2 (s2) goes in DETECT state instead of the sensor 3 (s3). This is simply because s2 is placed first in the group2.

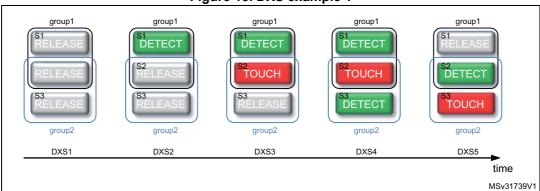


Figure 15. DXS example 1

Example 2: 4 sensors with one shared between three groups.

In this example the group1 is composed of the two sensors s1 and s2 in this order, the group2 of the two sensors s2 and s3 in this order and the group3 of the two sensors s2 and s4 in this order.

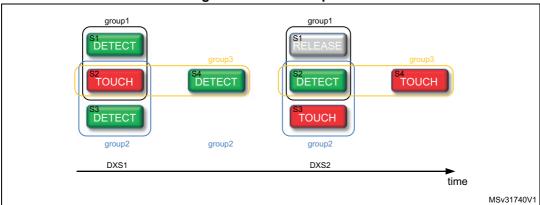
The DXS groups are processed in this order: group1 first, then group2 and finally group3.



We can see in the step DXS2 that the sensor 2 takes the priority over the sensors 3 and 4.

To summarize, the decision to be in DETECT state depends on the sensors placement inside the group and also on the order of the groups processing.

Figure 16. DXS example 2



2.13.2 Resources

The DXS functions are provided in the files:

- tsl_dxs.c
- tsl dxs.h

The functions to use are:

TSL dxs FirstObj()

2.13.3 Parameters

TSLPRM_USE_DXS

2.13.4 Usage example

The DXS processing is performed usually in the main state machine but it can also be done in interrupt routines.

Warning:

The DXS must be absolutely performed after the sensors state machine is processed, that is after the call to the TSL_obj_GroupProcess() function (see the main state machine for more details).

The DXS processing is performed on a **group of sensors** defined by the user. Different groups of DXS can be created.

It's up to the user to decide the best partitioning for his application.

Example:

```
int main(void) {
  while (1) {
```



UM1913 Rev 7 49/156

```
TSL_obj_GroupProcess(&MyObjGroup1);
TSL_obj_GroupProcess(&MyObjGroup2);
TSL_dxs_FirstObj(&MyObjGroup1);
TSL_dxs_FirstObj(&MyObjGroup2);
...
}
```

2.14 Detection time out (DTO)

2.14.1 Principle

The detection time out (DTO) introduces a simple way to cope with water film and any obstacle that may come in contact with a sensor. It introduces a maximum duration for the 'detected' state of any sensor called the DTO.

After this period of time, the sensor is automatically re-calibrated. This allows the sensor to be made touch sensitive again, even if the obstacle or the liquid film is still present on the application front panel.

This feature is application dependent and the time out must be tuned according to the user interface specifications.

The DTO is applied on the PROX, DETECT and TOUCH states and can be disabled.

2.14.2 Resources

The DTO functions are provided in the files:

- tsl_touchkey.c
- tsl touchkey.h
- tsl_linrot.c
- tsl linrot.h

The functions used by the DTO are:

- TSL tkey DTOGetTime()
- TSL_linrot_DTOGetTime()
- TSL tim CheckDelay sec()

Note: The user doesn't need to call these functions to perform the DTO.

2.14.3 Parameters

TSLPRM_DTO

2.14.4 Usage

The DTO is automatically performed inside the sensor state machine. The user doesn't need to call any function in the application code.

The DTO is disabled by writing zero in the TSLPRM_DTO parameter.



2.15 Noise filters

2.15.1 Principle

The STMTouch touch sensing library has been designed to facilitate the implementation of different noise filters. These filters can be used for many purpose and can range from very simple design to very complicated.

2.15.2 Resources

The filters are defined in the files:

- tsl filter.c
- tsl_filter.h

Each filter is described by a function:

- TSL_filt_MeasFilter(): filter on measurement values
- TSL_filt_DeltaFilter(): filter on delta values

2.15.3 Parameters

There is no parameter for the filter module.

2.15.4 Usage

The filter functions can be called at anytime in the main application. In order to speed-up the execution time and to gain RAM space, the measure and delta filters are called by the TSL_acq_BankGetResult() function.

Examples:

```
// Apply a filter on the measures only
TSL_acq_BankGetResult(0, TSL_filt_MeasFilter, 0);
// Get the measures without applying any filter
TSL_acq_BankGetResult(0, 0, 0);
```

Note:

The user can also create his own filter functions.

2.16 Timing management

2.16.1 Principle

The STMTouch touch sensing library needs an internal clock ("timing"), in particular for the ECS and DTO processing.

The timing process consists to increment a global variable at a regular interval. Different functions are then used to compare the current "time" and to check if a certain delay has elapsed.

The Systick is used as timebase for the STMTouch touch sensing library. Its initialization must be done in the user code layer. Usually it is already done by the HAL_Init function. The TSLPRM_TICK_FREQ parameter must be set accordingly.



51/156

2.16.2 Resources

The common timing routines are described in the files:

- tsl time.c
- tsl_time.h

Functions:

- TSL_tim_ProcessIT()
- TSL_tim_CheckDelay_ms()
- TSL_tim_CheckDelay_sec()

2.16.3 Parameters

 TSLPRM_TICK_FREQ: the value must be in line with the Systick frequency that is initialized in the user code.

2.16.4 Usage

The function **TSL_tim_CheckDelay_ms()** can be used in the main application code to execute some code (for example the ECS) at a regular interval.

Example:

```
TSL_tTick_ms_T time_ECS_tick;
TSL_tTick_ms_T time_LED_tick;
int main(void) {
  TSL Init(MyBanks); // The timing starts...
  while (1) {
    . . .
    // Launch the ECS every 100 ms
    if (TSL_tim_CheckDelay_ms(100, &time_ECS_tick) == TSL_STATUS_OK)
      TSL_ecs_Process(&MyObjGroup);
    // Toggle LED every 500 ms
    if (TSL_tim_CheckDelay_ms(500, &time_LED_tick) == TSL_STATUS_OK)
    {
      ToggleLED();
    }
    . . .
  }
}
```

2.17 Parameters

All the parameters are described in the **tsl_conf.h** file.

Note:

The tsl_conf_<XXX>_template.h file present in the STM32_TouchSensing_Library/inc folder must be copied in the application project inc/tsl_conf.h and adapted to your application (number of channels, banks, debounce, DTO, etc.).



The structure **TSL_Params_T** is used to hold certain parameters that are common to all sensors. These parameters can be changed by the user while the application is running.

Parameters checking

All common parameters are verified (presence and value range) in the file:

tsl_check_config.h

All device specific parameters are verified in the tsl check config <XXX>.h file.

2.18 Sensors acquisition timings

Reminders regarding terminology used in this section are given below:

- Bank: set of channels acquired simultaneously belonging to different groups
- Channel: elementary acquisition item (a GPIO from a group connected to a sensor)
- **Group** (also known as TSC group): set of up to four GPIOs defined as one sampling capacitor (Cs) with up to three channels or an active shield
- Shield: set of track and hatched plane used to increase noise robustness
- Active shield: a channel connected to an hatched plane driven simultaneously to sensor channels belonging to the same bank. An active shield requires its own sampling capacitor.
- Passive shield: a plane preferably hatched connected to the ground

This section details sequences for system with the following configurations:

- TouchKey sensor only
- Linear or rotary sensor only
- Mixed configuration using touchkey, and/or linear and/or rotary sensors

2.18.1 Acquisition timing using touchkey sensors

Using up to three touchkey sensors on the same group

As a group is able to handle up to three channels, this use case can be handled using only one group. An extra group can also be added for the shield.

The main advantages of this configuration are the following:

- reduced number of used GPIOs
- only one sampling capacitor required for 3 touchkeys

Table 6 gives an example based on G1 and G2 and *Table 7* details the corresponding acquisition time line.



UM1913 Rev 7

53/156

Group	I/O	Channel ⁽¹⁾	Sampling	Touchkey	Bank	
	IO1	-	CS = 22 nF	-	-	
G1	IO2	CH1	-	K1		
Gi	IO3	CH2	-	K2	B1	
	104	CH3	-	K3		
	IO1	-	CS = 47 nF	-	-	
G2	IO2	SHIELD	-	-	-	
G2	103	-	-	-	_	

Table 6. Example based on G1/G2 (3 touchkey sensors)

104

Table 7. Example G1/G2 (3 touchkey sensors) - Acquisition time line

Time	ТО	T1	T2	Т3	T4	T5	T6	T7	Т8
D4	↑ ⁽¹⁾		eoa ⁽²⁾	↑		eoa	↑		eoa
B1	P ⁽³⁾ (4)	P I	ΡΙ	ΡΙ	Ρ Ι	ΡΙ	ΡΙ	Ρ Ι	ΡΙ
K1/CH1	Γ ⁽⁵⁾			Γ			Γ		
K2/CH2		Γ			Γ			Γ	
K3/CH3			Γ			Γ			Γ
SHIELD	Γ	Γ	Γ	Γ	Γ	Γ	Γ	Γ	Γ

- 1. \uparrow = start of bank Bx acquisition.
- 2. eoa = end of Bx acquisition.
- 3. P = program groups and channels.
- 4. I = interrupt.
- 5. Γ = charge transfer cycle (green for CHx and blue for SHIELD).

Table 8 provides a synthesis list of features for this example.

This is the most simple use case. In this case sensor acquisition is sequential.

Table 8. Example G1/G2 (3 touchkey sensors) - Synthesis

Features	Value
Sampling capacitance	1 + 1 (shield)
Pins without shield	4
Pins with shield	6
Cost	Low
Response time	3 * T0

^{1.} Green is used for CHx and blue for SHIELD.

Using up to three touchkey sensors on three groups

To speed up the acquisition, the configuration one group per touchkey is better. An extra group can also be added for the shield.

Table 9 gives an example based on G1, G2, G3 and G4 (3 touchkey sensors) and *Table 10* details the corresponding acquisition time line.

Table 9. Example based on G1/G2/G3/G4 (3 touchkey sensors)

Group	I/O	Channel ⁽¹⁾	Sampling	Touchkey	Bank	
	IO1	-	CS = 22 nF	-	-	
G1	IO2	CH1	-	K1	B1	
Gi	IO3	-	-	-	-	
	104	-	-	-	-	
	IO1	-	CS = 22 nF	-	-	
G2	IO2	CH2	-	K2	B2	
G2	IO3	-	-	-	-	
	IO4	-	-	-	-	
	IO1	-	CS = 22 nF	-	-	
G3	IO2	CH3	-	K3	В3	
93	103	-	-	-	-	
	IO4	-	-	-	-	
	IO1	-	CS = 47 nF	-	-	
G4	IO2	SHIELD	-	-	-	
G4	IO3	-	-	-	-	
	104	-	-	-	-	

^{1.} Green is used for CHx and blue for SHIELD.

Table 10. Example G1/G2/G3/G4 (3 touchkey sensors) - Acquisition time line

			•				•					•					
Time	ТО	T	1		T2		Т3		T4		T5		Т6		T7		Т8
B1/B2/	↑ ⁽¹⁾ eoa ⁽²⁾	↑	eoa	\uparrow	eoa	↑	eoa	↑	eoa	1	eoa	↑	eoa	↑	eoa	\uparrow	eoa
B3	P ⁽³⁾ I ⁽⁴⁾	Р		Р		Р		Р		Р		Р	I	Р		Р	
K1/CH1	Γ ⁽⁵⁾	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ	
K2/CH2	Γ	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ	
К3/СН3	Γ	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ	
SHIELD	Γ	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ	

- 1. ↑ = start of bank Bx acquisition.
- 2. eoa = end of Bx acquisition.
- 3. P = program groups and channels.
- 4. I = interrupt.
- 5. Γ = charge transfer cycle (green for CHx and blue for SHIELD).



UM1913 Rev 7 55/156

Table 11 provides a synthesis list of features for this example.

This is the way to acquire all sensors at the same time.

Table 11. Example G1/G2/G3/G4 (3 touchkey sensors) - Synthesis

Feature	Value
Sampling capacitance	3+ 1 (shield)
Pins without shield	6
Pins with shield	8
Cost	Medium
Response time	1 * T0

Note:

The Groups pin not used for channel handling (such as IO3/4 in the example above) must not be used for analog features.

Using more than three touchkey sensors

To handle more than three touchkey sensors, more than one group is needed as the maximum number of channels per group is three. An extra group can also be used for the shield.

Table 12 gives an example based on G1, G2, G3 and G4 with 9 touchkey sensors and Table 13 details the corresponding acquisition time line.

Table 12. Example based on G1/G2/G3/G4 (9 touchkey sensors)

Group	I/O	Channel ⁽¹⁾	Sampling	Key	Bank	
	IO1	-	CS = 22 nF	-	-	
G1	IO2	CH1	-	K1	B1	
Gī	IO3	CH2	-	K2	B2	
	104	CH3	-	K3	В3	
	IO1	-	CS = 22 nF	-	-	
G2	IO2	CH4	-	K4	B1	
G2	103	CH5	-	K5	B2	
	104	CH6	-	K6	В3	
	IO1	-	CS = 22 nF	-	-	
G3	102	CH7	-	K7	B1	
G3	103	CH8	-	K8	B2	
	104	CH9	-	K9	В3	
	IO1	-	CS = 47 nF	-	-	
G4	IO2	SHIELD	-	-	-	
34	103	-	-	-	-	
	104	-	-	-	-	

^{1.} Green is used for CHx and blue for SHIELD.

				(5 15 6		, , , ,	40		
Time	ТО	T1	T2	Т3	T4	T5	T6	Т7	Т8
B1/B2/B3	↑ ⁽¹⁾		eoa ⁽²⁾	1		eoa	1		eoa
D 1/D2/D3	P ⁽³⁾ (4)	Ρ Ι	ΡΙ	ΡΙ	P	ΡΙ	ΡΙ	Ρ Ι	ΡΙ
K1/CH1	Γ ⁽⁵⁾			Γ			Γ		
K2/CH2		Γ			Γ			Γ	
K3/CH3			Γ			Γ			Γ
K4/CH4	Γ			Γ			Γ		
K5/CH5		Γ			Γ			Γ	
K6/CH6			Γ			Γ			Γ
K7/CH7	Γ			Γ			Γ		
K8/CH8		Γ			Γ			Γ	
K9/CH9			Γ			Γ			Γ
SHIELD	Γ	Г	Γ	Γ	Г	Γ	Γ	Г	Г

Table 13. Example G1/G2/G3/G4 (9 touchkey sensors) - Acquisition time line

- 1. ↑ = start of bank Bx acquisition.
- 2. eoa = end of Bx acquisition.
- 3. P = program groups and channels.
- 4. I = interrupt.
- 5. Γ = charge transfer cycle (green for CHx and blue for SHIELD).

Table 11 provides a synthesis list of features for this example.

This is the most complex use case.

Table 14. Example G1/G2/G3/G4 (9 keys)- Synthesis

Feature	Value					
Sampling capacitance	3+ 1 (shield)					
Pins without shield	12					
Pins with shield	14					
Cost	Medium					
Response time	3 * T0					



UM1913 Rev 7 57/156

Using only few specific touchkey sensors

If only some touchkey sensors must be acquired, the bank helps to start the acquisition only on these specific touchkeys.

Table 15 shows an example of the acquisition time line in this case.

Table 15. Example G1/G2/G3/G4 (specific touch key sensors only) - Acquisition time line

Time	ТО	T1	T	T2		Т3		T4		T5		T6	Т7		Т8	
B1	↑ ⁽¹⁾ eoa ⁽²⁾		↑	eoa	↑	eoa	\uparrow			eoa	↑					eoa
ы	P ⁽³⁾ (4)		Р	I	Р	I	Р		Р	I	Р	I	Р	I	Р	I
K1/CH1	Γ ⁽⁵⁾		Γ		Γ						Γ					
K2/CH2							Γ						Γ			
K3/CH3									Γ						Γ	
K4/CH4	Γ		Γ		Γ						Γ					
K5/CH5							Γ						Γ			
K6/CH6									Γ						Γ	
K7/CH7	Γ		Γ		Γ						Γ					
K8/CH8							Γ						Γ			
K9/CH9									Γ						Γ	
SHIELD	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ	

^{1.} \uparrow = start of bank Bx acquisition.

2.18.2 Acquisition timing using linear or rotary sensors

To handle linear or rotary sensors in a proper way regarding sensitivity, it is recommended to split linear and rotary channels on various groups.

For example, three groups needed to handle three linear/rotary channels.

Using one linear/rotary sensor

Three groups are used to handle the three channels. An extra group can also be used for the shield.

Table 16 gives an example based on G1, G2, G3 and G4 (one linear sensor) and *Table 17* details the corresponding acquisition time line.

^{2.} eoa = end of Bx acquisition.

^{3.} P = program groups and channels.

^{4.} I = interrupt.

^{5.} Γ = charge transfer cycle (green for CHx and blue for SHIELD).

Table 16. Example based on G1/G2/G3/G4 (1 linear sensor)

Group	I/O	Channel ⁽¹⁾	Sampling	Linear	Bank
	IO1	-	CS = 47 nF	-	-
G1	IO2	CH1	-	S1	B1
Gi	IO3	-	-	-	-
	IO4	-	-	-	-
	IO1		CS = 47 nF	-	-
G2	IO2	CH2	-	S1	B1
G2	IO3	-	-	-	-
	IO4	-	-	-	-
	IO1	-	CS = 47 nF	-	-
G3	IO2	CH3	-	S1	B1
G5	IO3	-	-	-	-
	IO4	-	-	-	-
	IO1	-	CS = 47 nF	-	-
G4	IO2	SHIELD	-	-	-
G4	IO3	-	-	-	-
	104	-	-	-	-

^{1.} Green is used for CHx and blue for SHIELD.

Table 17. Example G1/G2/G3/G4 (1 sensor) - Acquisition time line

Time	ТО		T1		T2		Т3		T4		T5		T6		Т7		Т8	
D4	↑ ⁽¹⁾ eoa ⁽²⁾	\uparrow	eoa	↑	eoa	↑	eoa	↑	eoa	↑	eoa	\uparrow	eoa	↑	eoa	↑	eoa	
B1	P ⁽³⁾ (4)	Р	I	Р	I	Р	I	Р	I	Р	I	Р	I	Р	I	Р	I	
S1/CH1	Γ ⁽⁵⁾	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ		
S1/CH2	Γ	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ		
S1/CH3	Γ	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ		
SHIELD	Γ	Γ		Γ		Γ		Γ		Γ		Γ		Γ		Γ		

- 1. ↑ = start of bank Bx acquisition.
- 2. eoa = end of Bx acquisition.
- 3. P = program groups and channels.
- 4. I = interrupt.
- 5. Γ = charge transfer cycle (green for CHx and blue for SHIELD).



UM1913 Rev 7 59/156

Table 18 provides a synthesis list of features for this example.

Table 18. Example G1/G2/G3/G4 (1 sensor) - Synthesis

Feature	Value
Sampling capacitance	3+ 1 (shield)
Pins without shield	6
Pins with shield	8
Cost	Medium
Response time	1 * T0

Using two linear and one rotary sensors

The three sensors allows the handling of nine channels.

Table 19 gives an example based on G1, G2, G3 and G4 (three sensors) and *Table 20* details the corresponding acquisition time line.

Table 19. Example based on G1/G2/G3/G4 (3 L/R sensors)

Group	I/O	Channel ⁽¹⁾	Sampling	Linear/Rotary	Bank
	IO1	-	CS = 47 nF	-	-
G1	IO2	CH1	-	S1	B1
Gi	IO3	CH4	-	S2	B2
	104	CH7	-	R1	В3
	IO1	-	CS = 47 nF	-	-
G2	IO2	CH2	-	S1	B1
G2	IO3	CH5	-	S2	B2
	104	CH8	-	R1	В3
	IO1	-	CS = 47 nF	-	-
G3	102	CH3	-	S1	B1
G3	IO3	CH6	-	S2	B2
	104	CH9	-	R1	В3
	IO1	-	CS = 47 nF	-	-
G4	IO2	SHIELD	-	-	-
04	IO3	-	-	-	-
	104	-	-	-	-

^{1.} Green is used for CHx and blue for SHIELD.

T0 T1 **T2** Т3 **T4** T5 **T6** Time **T7 T8** ↑⁽¹⁾eoa⁽²⁾ eoa eoa В1 P(3) (4) Р I Р I eoa eoa eoa B2 Ρ I Ρ eoa eoa eoa В3 Ρ Ρ $\Gamma^{(5)}$ S1/CH1 Γ Г S1/CH2 Γ S1/CH3 Γ S2/CH4 Γ S2/CH5 S2/CH6 R1/CH7 Γ Γ R1/CH8 Γ R1/CH9 SHIELD [

Table 20. Example G1/G2/G3/G4 (3 L/R sensors) - Acquisition time line

- 1.

 † = start of bank Bx acquisition.
- 2. eoa = end of Bx acquisition.
- 3. P = program groups and channels.
- 4. I = interrupt.
- 5. Γ = charge transfer cycle (green for CHx and blue for SHIELD).

Table 21 provides a synthesis list of features for this example.

Table 21. Example G1/G2/G3/G4 (3 L/R sensors) - Synthesis

Feature	Value
Sampling capacitance	3+ 1 (shield)
Pins without shield	12
Pins with shield	14
Cost	Medium
Response time	3 * T0

2.18.3 Acquisition timing using touchkey, linear and rotary sensors

Table 22 gives an example based on G1, G2, G3 and G4, with three touchkey, one linear and one rotary sensors and *Table 23* details the corresponding acquisition time line.



UM1913 Rev 7 61/156

Table 22. Example based on G1, G2, G3 and G4 (3 touchkey, 1 linear, 1 rotary sensors)

Group	I/O	Channel ⁽¹⁾	Sampling	Touchkey	Linear/Rotary	Bank
	IO1	-	CS = 47 nF	-	-	-
G1	IO2	CH1	-	-	S1	B1
Gi	IO3	CH4	-	K1	-	B2
	IO4	CH7	-	-	R1	В3
	IO1	-	CS = 47 nF	-	-	-
G2	IO2	CH2	-	-	S1	B1
G2	IO3	CH5	-	K1	-	B2
	IO4	CH8	-	-	R1	В3
	IO1	-	CS = 47 nF	-	-	-
G3	IO2	CH3	-	-	S1	B1
GS	IO3	CH6	-	K1	-	B2
	IO4	CH9	-	-	R1	В3
	IO1	-	CS = 47 nF	-	-	-
G4	102	SHIELD	-	-	-	-
94	IO3	-	-	-	-	-
	104	-	-	-	-	-

^{1.} Green is used for CHx and blue for SHIELD.

Table 23. Example G1/G2/G3/G4 (3 touchkey, 1 linear, 1 rotary sensors) - Acquisition time line

Time	T0	T1	T2	Т3	T4	T5	T6	T7	Т8
B1	↑ ⁽¹⁾ eoa ⁽²⁾			↑ eoa			↑ eoa		
B2		↑ eoa			↑ eoa			↑ eoa	
В3			↑ eoa			↑ eoa			↑ eoa
S1/CH1	L(3)			Γ			Γ		
S1/CH2	Γ			Γ			Γ		
S1CH3	Γ			Γ			Γ		
K1/CH4		Γ			Γ			Γ	
K1/CH5		Γ			Γ			Γ	
K1/CH6		Γ			Γ			Γ	
R1/CH7			Γ			Γ			Γ
R1/CH8			Γ			Γ			Γ
R1/CH9			Γ			Γ			Γ
SHIELD	Γ	Γ	Γ	Γ	Γ	Γ	Γ	Γ	Γ

- 1. ↑ = start of bank Bx acquisition.
- 2. eoa = end of Bx acquisition.
- 3. Γ = charge transfer cycle (green for CHx and blue for SHIELD).

Table 21 provides a synthesis list of features for this example.

Table 24. Example G1/G2/G3/G4 (3 touchkey, 1 linear, 1 rotary sensors) - Synthesis

Feature	Value
Sampling capacitance	3+ 1 (shield)
Pins without shield	12
Pins with shield	14
Cost	Medium
Response time	3 * T0



UM1913 Rev 7

63/156

2.19 Error management

Top level error management can be done at user application level.

The APIs are described in tsl_user.c where we split keys and linrot error cases.

The customer may decide which action to be done in these cases (such as reboot, re-init or alarm).

The corresponding APIs are detailed in the below code:

```
* @brief Executed when a sensor is in Error state

* @param None

* @retval None

*/

void MyTKeys_ErrorStateProcess(void)

{

/* Add here your own processing when a sensor is in Error state */
}

void MyLinRots_ErrorStateProcess(void)

{

/* Add here your own processing when a sensor is in Error state */
}

/**

* @brief Executed when a sensor is in Off state

* @param None

* @retval None

*/

void MyTKeys_OffStateProcess(void)

{

/* Add here your own processing when a sensor is in Off state */
}

void MyLinRots_OffStateProcess(void)

{

/* Add here your own processing when a sensor is in Off state */
}
```

3 Devices with TSC peripheral

This section concerns all STM32 microcontrollers that include the touch sensing controller peripheral (TSC).

3.1 Acquisition

The acquisition is done in the files:

- tsl_acq_tsc.c
- tsl acq tsc.h

Functions used by the application layer and that are device dependent:

- TSL acq BankConfig()
- TSL acq BankStartAcq()
- TSL_acq_BankWaitEOC()
- TSL_acq_GetMeas()

The other functions in this file are for internal use and the user doesn't need to call them directly.

The device selection must be done at the end of the tsl_conf.h file:

```
#include "stm32f0xx.h" /* Select the file corresponding to the device in use (i.e. stm32f3xx.h, stm32f0xx.h, ...) */
```

3.2 Timings

The timing management is done in the files:

- tsl time.c
- tsl time.h

The **Systick** is used to generate a timebase for the ECS and DTO modules. It must be initialized in the user code (already done by the HAL init function).

3.3 Parameters

The parameters are described in the file:

- tsl conf_tsc_template.h (to be copied in the project and rename in tsl_conf.h)
- and are checked in the file:
- tsl_check_config_tsc.h

3.4 MCU resources

The table below shows the peripherals that are used by the STMTouch touch sensing library on any STM32 microcontroller with the touch sensing controller. Care must be taken when using them to avoid any unwanted behavior.



UM1913 Rev 7 65/156

Table 25. STM32F0 Series MCU resources used

Peripheral	Function
GPIOs	Acquisition
Systick	Time base for ECS and DTO
Touch sensing controller (TSC)	Acquisition

3.5 STM32F0 Series microcontrollers

3.5.1 Memory footprint

Conditions

- IAR ANSI C/C++ compiler/linker V7.40.3.8902 for Arm®
- Compiler optimization: high size
- Counted files: tsl*.o
- STM32 TouchSensing library options: ECS=ON, DTO=ON, DXS=OFF, PROX=OFF
- Each sensor has its own parameters placed in RAM

The following table summarizes the memory footprint with different configurations:

Table 26. STM32F0 Series memory footprint⁽¹⁾

Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)
1	1	1 TKey	3.0	100
2	1	2 TKeys	3.0	120
2	2	2 TKeys	3.0	120
24	3	24 TKeys	4.0	620
3	1	1 Linear-3ch	4.1	130
15	3	12 TKeys + 1 Linear-3ch	6.2	420
24	3	18 TKeys + 2 Linear-3ch	6.5	610

^{1.} The content of this table is provided for information purposes only.



3.5.2 Available touch sensing channels

The tables below provide an overview of the available touch sensing channels for the STM32F0 Series microcontrollers.

Note: The following tables are not restrictive in term of part numbers supported by the STMTouch touch sensing library. The STMTouch

touch sensing library can be used on any new device that may become available as part of ST microcontrollers portfolio. Please

contact your ST representative for support.

Note: For n available pins in an I/O group, one pin is used as sampling capacitor and n-1 pins are used as channels.

The I/O group cannot be used if the number of available pins in less or equal to one.

Table 27. Available touch sensing channels for STM32F098xx

	Capacitive			STM32	F098Vx				STM32	F098Rx			STM32	F098Cx
Analog I/O group	sensing signal name	Pin name	UFBGA100		LQFP100		UFB	UFBGA64		P64	WLCSP64		LQFP48 UFQFPN48	
	TSC_G1_IO1	PA0	Х		Х		Х		Х		х		Х	
G1	TSC_G1_IO2	PA1	Х	3	Х	3	Х	3	х	3	Х	3	х	3
	TSC_G1_IO3	PA2	Х	3	Х	3	Х	3	Х	3	Х		Х	
	TSC_G1_IO4	PA3	Х		Х		Х		Х		Х		Х	
00	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		Х		Х		Х	- 3	Х	3
	TSC_G2_IO2	PA5 ⁽¹⁾	Х	3 -	Х	3	Х	3	Х	3	Х		Х	
G2	TSC_G2_IO3	PA6	Х		Х		Х		Х		Х		Х	
	TSC_G2_IO4	PA7	Х		Х		Х		Х		Х		Х	
	TSC_G3_IO1	PC5	Х		Х		Х		Х		х		-	1
62	TSC_G3_IO2	PB0	Х	2	Х		Х		Х	2	Х		Х	
G3	TSC_G3_IO3	PB1	Х	2	Х	2	Х	2	Х	2	Х	2	Х	
	TSC_G3_IO4	-	-		-		-	1	-		-		-	
	TSC_G4_IO1	PA9	Х		Х		Х		Х		х	3	Х	3
C4	TSC_G4_IO2	PA10	Х	3	Х	,	Х	,	Х	3	х		Х	
G4	TSC_G4_IO3	PA11	х	٥	Х	3	Х	3	Х		х		Х	
	TSC_G4_IO4	PA12	Х		Х		Х		Х		Х		Х	

UM1913 Rev 7

Capacitive

TSC_G8_IO3

TSC_G8_IO4

Number of capacitive

sensing channels (sampling I/Os not counted)

STM32F098Cx

16

	Capacitive																
Analog I/O group	sensing signal name	Pin name	UFBO	SA100	LQF	P100	UFB	GA64	LQF	P64	WLC	SP64		P48 PN48			
	TSC_G5_IO1	PB3	Х		Х		Х		Х		Х		Х				
G5	TSC_G5_IO2	PB4	Х	3	Х	3	Х	3	Х	3	Х	3	Х	,			
GS	TSC_G5_IO3	PB6	Х	3	Х	3	Х	3	Х	٦	Х	3	Х	3			
	TSC_G5_IO4	PB7	Х		Х		Х		Х					Х		Х	
	TSC_G6_IO1	PB11	Х		Х		Х		Х		Х		Х	x x x			
G6	TSC_G6_IO2	PB12	Х	3	Х	3	Х	3	Х	3	Х	3	Х				
Go	TSC_G6_IO3	PB13	Х	3	Х	3	Х	3	Х	3	Х	3	Х				
	TSC_G6_IO4	PB14	Х		Х		Х		Х		Х		Х				
	TSC_G7_IO1	PE2	Х		Х		Х		-		-		-				
G 7	TSC_G7_IO2	PE3	Х	3	Х	3	Х	0	-	0	-	0	-	0			
G/	TSC_G7_IO3	PE4	Х	3	Х	3	Х		-		-	0	-				
	TSC_G7_IO4	PE5	Х		Х		Х		-		-		-				
	TSC_G8_IO1	PD12	Х		Х		х		-		-		-				
G8	TSC_G8_IO2	PD13	Х	,	Х		Х		-		-	0	-				
G8	TOO OO 100	DD44		3		3		0		0		0		0			

Χ

Х

23

Χ

Х

17

Table 27. Available touch sensing channels for STM32F098xx (continued)

STM32F098Rx

17

17

STM32F098Vx

Х

Х

23

PD14

PD15

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



Table 28. Available touch sensing channels for STM32F091xx

	Capacitive			STM32	F091Vx	_			STM32	F091Rx			STM32	F091Cx	
Analog I/O group	sensing signal name	Pin name	UFBC	UFBGA100		LQFP100		UFBGA64		LQFP64		WLCSP64		LQFP48 UFQFPN48	
	TSC_G1_IO1	PA0	Х		Х		х		х		х		Х		
G1	TSC_G1_IO2	PA1	Х	3	х	3 x	Х	3	Х	3	Х	3	Х	3	
G1	TSC_G1_IO3	PA2	Х	3	х	3	Х	3	Х	3	Х	3	Х	3	
	TSC_G1_IO4	PA3	Х		Х		Х		Х		Х		Х		
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		х		Х		Х		Х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х	3	Х	3	Х	3	Х	3	Х	3	Х	3	
G2	TSC_G2_IO3	PA6	Х	3 x	3	Х		Х	3	Х	3	Х	3		
	TSC_G2_IO4	PA7	Х		Х		Х		Х		Х		Х		
	TSC_G3_IO1	PC5	Х		Х		х	3	Х		Х		-		
62	TSC_G3_IO2	PB0	Х	,	Х	3	х		Х	3	Х	3	Х	2	
G3	TSC_G3_IO3	PB1	Х	3	Х		Х		Х	3	Х		Х		
	TSC_G3_IO4	PB2	Х		х		х		х		х		х		
	TSC_G4_IO1	PA9	Х		Х		х		Х		х		х		
G4	TSC_G4_IO2	PA10	Х	3	Х	3	х	,	Х	3	Х	3	Х	3	
G4	TSC_G4_IO3	PA11	Х	3	Х	3	Х	3	Х	3	Х	3	Х	3	
	TSC_G4_IO4	PA12	Х		Х		Х		Х	1	Х		Х	1	
	TSC_G5_IO1	PB3	Х		Х		х	3	х		х		х	x x 3	
G5	TSC_G5_IO2	PB4	Х		Х]	х		Х	3	Х	3	Х		
Go	TSC_G5_IO3	PB6	Х	3	Х	3	х		Х		Х	٥	Х	3	
	TSC_G5_IO4	PB7	Х		Х	1	Х		Х		Х		Х	1	

UM1913 Rev 7

Devices with TSC peripheral

Table 28. Available touch sensing channels for STM32F091xx (continued)

	Capacitive		STM32	F091Vx		STM32F091Rx							STM32F091Cx	
Analog I/O group sensing signal name		Pin name	UFBO	UFBGA100		LQFP100		UFBGA64		P64	WLCSP64		LQFP48 UFQFPN48	
	TSC_G6_IO1	PB11	Х		Х		Х		Х		Х		Х	
G6	TSC_G6_IO2	PB12	B12 x	3	Х	3	Х	3	Х	3	Х	3	Х	3
G0	TSC_G6_IO3	PB13	х]	Х	3	Х	3	x x	3	Х		Х	3
	TSC_G6_IO4	PB14	х		Х		Х				Х		х	
	TSC_G7_IO1	PE2	х		Х	- 3	х	0	-		-		-	
G7	TSC_G7_IO2	PE3	х	3	Х		Х		-	0	-	0	-	0
G/	TSC_G7_IO3	PE4	х	3	Х		Х		-		-		-	
	TSC_G7_IO4	PE5	х		Х		Х		-		-		-	
	TSC_G8_IO1	PD12	х		Х	3	х	0	-		-		-	- - 0
G	TSC_G8_IO2	PD13	х	3	х		Х		-	0	-		-	
G8	TSC_G8_IO3	PD14	х]	Х		Х		-		-	0	-	
	TSC_G8_IO4	PD15	х		Х		х		-		-		-	
	Number of capacitive sensing channels (sampling I/Os not counted)		24		24		18		18		18		17	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



		Table 29. A	vailable touch sens	ing channels fo	or STM32F078xx	
--	--	-------------	---------------------	-----------------	----------------	--

	Capacitive				F078Vx			F078Rx	STM32F078Cx				
Analog I/O group	sensing signal name	Pin name	UFBG	UFBGA100		LQFP100		LQFP64		LQFP48 UFQFPN48		WLCSP49	
	TSC_G1_IO1	PA0	х		х		х		х		х		
G1	TSC_G1_IO2	PA1	х	3	х	3	х	3	х	3	х	3	
Gi	TSC_G1_IO3	PA2	x	3	х	3	х		х	3	х	3	
	TSC_G1_IO4	PA3	х		х		х		х		х		
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		х		х		х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	х	3	х	3	х	3	х	3	
G2	TSC_G2_IO3	PA6	х	3	х	3	х		х		х		
	TSC_G2_IO4	PA7	x	-	х		х		х		х		
	TSC_G3_IO1	PC5	х		х		х	- 2	-	1	-	3	
G3	TSC_G3_IO2	PB0	х	2	х	2	х		х		х		
GS	TSC_G3_IO3	PB1	х		х		х		х		х		
	TSC_G3_IO4	-	-		-		-		-		-		
	TSC_G4_IO1	PA9	х		х		х		х		х		
G4	TSC_G4_IO2	PA10	x	3	х	3	х		х	3	х		
G4	TSC_G4_IO3	PA11	х	3	х	3	х		х		х		
	TSC_G4_IO4	PA12	х		х		х		х		х		
	TSC_G5_IO1	PB3	х		х		х		х		х		
G5	TSC_G5_IO2 PB4	x	3	х	3	х	3	х	3	х	2		
03	TSC_G5_IO3	PB6	х		х]	х	3	х	3	х	3	
	TSC_G5_IO4	PB7	Х		х		х		Х		х		

Devices with TSC peripheral

Table 29. Available touch sensing channels for STM32F078xx (continued)

	Capacitive			STM32	F078Vx		STM32F078Rx		STM32F078Cx			
Analog I/O group	sensing signal name	Pin name	UFBGA100		LQFP100		LQFP64		LQFP48 UFQFPN48		WLCSP49	
	TSC_G6_IO1	PB11	х		х		х		х		х	
G6	TSC_G6_IO2	PB12	х	3	х	3	х	3	х	3	х	3
Go	TSC_G6_IO3	PB13	х		х		х	3	х	3	х	
	TSC_G6_IO4	PB14	х		х		х		х		х	
	TSC_G7_IO1	PE2	х		х	3	-	- - 0	-	0	-	0
G7	TSC_G7_IO2	PE3	х	3	х		-		-		-	
G/	TSC_G7_IO3	PE4	х	3	х		-		-		-	
	TSC_G7_IO4	PE5	х		х		-		-		-	
	TSC_G8_IO1	PD12	х		х	3	-	0	-	0	-	- 0
Co	TSC_G8_IO2	PD13	х	3	х		-		-		-	
G8	TSC_G8_IO3	PD14	х		х		-	U	-		-	
	TSC_G8_IO4	PD15	PD15 x		х		-		-		-	
Number of capacitive sensing channels (sampling I/Os not counted)		counted)	2	3	23		17		16		16	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.





Table 30. Available touch sensing channels for STM32F072xx

	Capacitive			STM32	F072Vx		STM32	F072Rx		STM32	F072Cx	
Analog I/O group	sensing signal name	Pin name	UFBC	SA100	LQF	P100	LQF	P64	-	P48 PN48	WLC	SP49
	TSC_G1_IO1	PA0	х		х		х		х		х	
G1	TSC_G1_IO2	PA1	х	3	х	3	х	3	х	3	х	3
Gi	TSC_G1_IO3	PA2	х		х	3	х		х	3	х	
	TSC_G1_IO4	PA3	х		х		х		х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		х		х		х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	х	3	х	3	х	3	х	3
G2	TSC_G2_IO3	PA6	х		х	3	х		х	3	х	
	TSC_G2_IO4	PA7	х		х		х		х		х	
	TSC_G3_IO1	PC5	x		х		х		ı		-	
G3	TSC_G3_IO2	PB0	x	3	х	3	х	3	х	2	х	2
03	TSC_G3_IO3	PB1	x		х		х		x		x	
	TSC_G3_IO4	PB2	x		х		х		x		х	
	TSC_G4_IO1	PA9	x		х		х		х		х	
G4	TSC_G4_IO2	PA10	x	3	х	3	х	3	x	3	х	3
04	TSC_G4_IO3	PA11	x		x		х		x		x	
	TSC_G4_IO4	PA12	Х		х		х		Х		х	
	TSC_G5_IO1	PB3	x		х		х		x		х	
G5	TSC_G5_IO2	PB4	x	3	х	3	х	3	x	3	х	3
	TSC_G5_IO3	PB6	x		х]	х]	x		х]
	TSC_G5_IO4	PB7	x		х		х		x		х	

Devices with TSC peripheral

Table 30. Available touch sensing channels for STM32F072xx (continued)

	Capacitive			STM32	F072Vx		STM32	F072Rx		STM32	F072Cx	
Analog I/O group	sensing signal name	Pin name	UFBO	SA100	LQF	P100	LQF	P64		P48 PN48	WLC	SP49
	TSC_G6_IO1	PB11	х		х		х		х		Х	
G6	TSC_G6_IO2	PB12	х	3	х	3	х	3	х	3	х	3
Go	TSC_G6_IO3	PB13	х	3	х		х		х		х	3
	TSC_G6_IO4	PB14	х		х		х		х		х	
	TSC_G7_IO1	PE2	х		х		-		-		-	
G7	TSC_G7_IO2	PE3	х	3	х	3	-	0	-	0	-	0
G/	TSC_G7_IO3	PE4	х	3	х	3	-		-		-	
	TSC_G7_IO4	PE5	х		х		-		-		-	
	TSC_G8_IO1	PD12	х		х		-		-		-	
G8	TSC_G8_IO2	PD13	х	3	х	3	-	0	-	0	-	_
G6	TSC_G8_IO3	PD14	х	3	х	3	-		-		-	0
	TSC_G8_IO4	PD15	х	1	х	1	-		-		-	
Number sensing channels (er of capacitive sampling I/Os not	counted)	2	· !4	2	24	1	8	1	7	1	7

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.





Table 31. Available touch sensing channels for STM32F071xx

	Capacitive			STM32	F071Vx		STM32	F071Rx		STM32	F071Cx	
Analog I/O group	sensing signal name	Pin name	UFBG	SA100	LQF	P100	LQF	P64		P48 PN48	WLC	SP49
	TSC_G1_IO1	PA0	х		х		х		х		х	
G1	TSC_G1_IO2	PA1	х	3	х	3	х	3	х	3	х	3
Gi	TSC_G1_IO3	PA2	х		х		х		х	3	х	3
	TSC_G1_IO4	PA3	х		х		х		х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		х		х		х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	х	3	х	3	x	3	х	3
G2	TSC_G2_IO3	PA6	x		х		х		x		x	
	TSC_G2_IO4	PA7	x		х		х		x		x	
	TSC_G3_IO1	PC5	x		х		х		ı		-	
G3	TSC_G3_IO2	PB0	х	3	х	3	х	3	x	2	х	2
93	TSC_G3_IO3	PB1	х		х] 3	х		x		х	
	TSC_G3_IO4	PB2	x		х		х		х		х	
	TSC_G4_IO1	PA9	x		х		х		x		х	
G4	TSC_G4_IO2	PA10	х	3	х	3	х	3	x	3	х	3
04	TSC_G4_IO3	PA11	х		х		х		x		х	
	TSC_G4_IO4	PA12	Х		х		х		Х		х	
	TSC_G5_IO1	PB3	Х		х		х		Х		х	
G5	TSC_G5_IO2	PB4	Х	3	х	3	х	3	Х	3	х	3
	TSC_G5_IO3	PB6	Х		х]	х		Х]	х	
	TSC_G5_IO4	PB7	х		х		х		х		х	

UM1913 Rev 7

Devices with TSC peripheral

Table 31. Available touch sensing channels for STM32F071xx (continued)

	Capacitive			STM32	F071Vx		STM32	F071Rx		STM32	F071Cx	
Analog I/O group	sensing signal name	Pin name	UFBG	6A100	LQF	P100	LQF	P64		P48 PN48	WLC	SP49
	TSC_G6_IO1	PB11	Х		х		х		Х		Х	
G6	TSC_G6_IO2	PB12	х	3	х	3	х	3	х	3	х	3
Go	TSC_G6_IO3	PB13	х	3	х	3	х	3	х	3	х	3
	TSC_G6_IO4	PB14	х		х		х		х		х	
G7	TSC_G7_IO1	PE2	х		х		-		-		-	
	TSC_G7_IO2	PE3	х	3	х	3	-	0	-	0	-	0
	TSC_G7_IO3	PE4	х	3	х	3	-		-		-	
	TSC_G7_IO4	PE5	х		х		-		-		-	
G8	TSC_G8_IO1	PD12	х		х		-		-		-	
	TSC_G8_IO2	PD13	х	3	х	3	-	0	-	0	-	
	TSC_G8_IO3	PD14	х	3	х	3	-		-		-	0
	TSC_G8_IO4	PD15	х		х		-		-		-	
Number sensing channels (er of capacitive sampling I/Os not	counted)	2	4	2	24	1	8	1	7	1	7

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 32. Available touch sensing channels for STM32F058xx

Analog I/O group	Capacitive sensing	Pin name		STM32F	058Rx		STM32I	-058Cx
Analog I/O group	signal name	Pili liaille	LQF	P64	UFB	GA64	UFQF	PN48
	TSC_G1_IO1	PA0	х		х		х	
G1	TSC_G1_IO2	PA1	х	2	х	2	х	2
Gi	TSC_G1_IO3	PA2	х		х	3	х	3
	TSC_G1_IO4	PA3	х		х		х	



Table 32. Available touch sensing channels for STM32F058xx (continued)

A L 1/0	Capacitive sensing	Di		STM32	F058Rx		STM32	F058Cx
Analog I/O group	signal name	Pin name	LQ	FP64	UFB	GA64	UFQF	PN48
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	Х	3	х	3
G2	TSC_G2_IO3	PA6	х		х	3	х	3
	TSC_G2_IO4	PA7	х		х		х	
	TSC_G3_IO1	PC5	х		х		-	
G3	TSC_G3_IO2	PB0	х	2	Х	2	х	1
93	TSC_G3_IO3	PB1	х		Х	2	х	'
	TSC_G3_IO4	-	-		-		-	
	TSC_G4_IO1	PA9	х		х		х	
G4	TSC_G4_IO2	PA10	х	3	Х	3	х	3
04	TSC_G4_IO3	PA11	х		Х	3	х	3
	TSC_G4_IO4	PA12	х		Х		х	
	TSC_G5_IO1	PB3	х		х		х	
G5	TSC_G5_IO2	PB4	х	3	Х	3	х	3
GS	TSC_G5_IO3	PB6	х		Х	3	х] 3
	TSC_G5_IO4	PB7	х		Х		х	
	TSC_G6_IO1	PB11	х		х		х	
G6	TSC_G6_IO2	PB12	х	3	Х	3	х	3
Go	TSC_G6_IO3	PB13	х]	Х	J	х	٦
	TSC_G6_IO4	PB14	х	7	Х		х	

UM1913 Rev 7

Table 32. Available touch sensing channels for STM32F058xx (continued)

Analog I/O group	Capacitive sensing	Din nome		STM32F	058Rx		STM32I	-058Cx
Analog I/O group	signal name	Pin name	LQF	P64	UFBC	GA64	UFQF	PN48
	TSC_G7_IO1	-	-		-		-	
G 7	TSC_G7_IO2	-	-	0	-	0	-	0
G/	TSC_G7_IO3	-	-	0	-	U	-	U
	TSC_G7_IO4	-	-		-		-	
	TSC_G8_IO1	-	-		-		-	
G8	TSC_G8_IO2	-	-	0	-	0	-	0
Go	TSC_G8_IO3	-	-	0	-	U	-	U
	TSC_G8_IO4	-	-	,	-		-	
	mber of capacitive ls (sampling I/Os not counted	1)	1	7	1	7	10	6

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 33. Available touch sensing channels for STM32F051xx

	Capacitive			STM32	F051Rx		STM32	F051Cx		STM32	F051Kx	
Analog I/O group	sensing signal name	Pin name	LQF	P64	UFB	GA64		P48 PN48	LQF	FP32	UFQFPN32	
	TSC_G1_IO1	PA0	х		х		х		х		х	
C1	TSC_G1_IO2	PA1	х	3	х	3	х	3	х	3	х	3
G1 TSC_G1_I	TSC_G1_IO3	PA2	х	3	х	3	х	3	х	3	х	3
	TSC_G1_IO4	PA3	х		х		х		х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		х		х		х	
Ca	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	х	2	х	2	х	3	х	3
G2 —	TSC_G2_IO3	PA6	х] 3	х	3	х	3	х	3	х	3
TSC_G2_IO4	PA7	х	1	х		х		х		Х		





Table 33. Available touch sensing channels for STM32F051xx (continued)

	Capacitive			STM32	F051Rx		STM32	F051Cx		STM32	F051Kx	
Analog I/O group	sensing signal name	Pin name	LQI	P64	UFB	GA64		P48 PN48	LQF	FP32	UFQF	PN32
	TSC_G3_IO1	PC5	Х		х		-		-		-	
G3	TSC_G3_IO2	PB0	Х	3	х	3	х	2	Х	1	х	2
G3	TSC_G3_IO3	PB1	х	3	х] 3	х	2	х] '	х	2
	TSC_G3_IO4	PB2	х		х		х		-		х	
	TSC_G4_IO1	PA9	х		х		х		х		х	
G4	TSC_G4_IO2	PA10	х	3	х	3	х	3	х	3	х	3
G4	TSC_G4_IO3	PA11	х	3	х	3	х	3	х	3	х	3
	TSC_G4_IO4	PA12	х		х		х		х		х	
	TSC_G5_IO1	PB3	х		х		х		х		х	
G5	TSC_G5_IO2	PB4	х	3	х	3	х	3	х	3	х	3
G 3	TSC_G5_IO3	PB6	х		х		х		х		х	
	TSC_G5_IO4	PB7	х		х		х		х		х	
	TSC_G6_IO1	PB11	-		-		-		-		-	
G6	TSC_G6_IO2	PB12	ı	3	-	3	-	3	1	0	-	0
Gu	TSC_G6_IO3	PB13	ı]	-]	-		-		-	
	TSC_G6_IO4	PB14	ı		-		-		ı		-	
	TSC_G7_IO1	-	ı		-		-		-		-	
G7	TSC_G7_IO2	-	ı	0	-	0	-	0	-	0	-	0
O1	TSC_G7_IO3	-	i		-		-		ı		-	
	TSC_G7_IO4	-	-		-		-		-		-	

Table 33. Available touch sensing channels for STM32F051xx (continued)

	Capacitive			STM32	F051Rx		STM32	F051Cx		STM32	F051Kx	
Analog I/O group	sensing signal name	Pin name	LQF	LQFP64		GA64	LQFP48 UFQFPN48		LQFP32		UFQFPN32	
G8	TSC_G8_IO1	-	-		-		-		-		-	
	TSC_G8_IO2	-	-	0	-	0	-	0	-	0	-	0
	TSC_G8_IO3	-	-		-		-	0	-	0	-	
	TSC_G8_IO4	-	-		-		-		-		-	
	Number of capacitive nsing channels (sampling I/Os not counted)		1	8	1	8	1	7	1	3	1	4

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 34. Available touch sensing channels for STM32F048xx

A	Capacitive sensing	Dia mana	STM32	2F048Cx	STM32	F048Tx	STM32I	-048Gx
Analog I/O group	signal name	Pin name	UFQ	FPN48	WLC	SP36	UFQF	PN28
	TSC_G1_IO1	PA0	Х		х		х	
G1	TSC_G1_IO2	PA1	Х	3	Х	3	Х	3
GI	TSC_G1_IO3	PA2	Х	3	Х	3	х	3
	TSC_G1_IO4	PA3	Х		Х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		х		х	
00	TSC_G2_IO2	PA5 ⁽¹⁾	Х		Х	3	Х	2
G2	TSC_G2_IO3	PA6	Х	3	х	3	х	3
	TSC_G2_IO4	PA7	Х		х		х	
	TSC_G3_IO1	-	-		-		-	
C2	TSC_G3_IO2	PB0	х	1	х	1	х	0
G3	TSC_G3_IO3	PB1	х] '	х	'	-	0
	TSC_G3_IO4	-	-		-		-	



Table 34. Available touch sensing channels for STM32F048xx (continued)

	Capacitive sensing		STM3	2F048Cx	STM32	F048Tx	STM32	F048Gx
Analog I/O group	signal name	Pin name	UFC	FPN48	WLC	SP36	UFQF	PN28
	TSC_G4_IO1	PA9 ⁽²⁾	Х		х		x ⁽²⁾	
G4	TSC_G4_IO2	PA10 ⁽²⁾	х	3	х	3	x ⁽²⁾	1
G4	TSC_G4_IO3	PA11 ⁽²⁾	х	3	Х	3	x ⁽²⁾	-
	TSC_G4_IO4	PA12 ⁽²⁾	Х		х		x ⁽²⁾	1
	TSC_G5_IO1	PB3	х		х		х	
G5	TSC_G5_IO2	PB4	Х	3	х	3	х	3
Go	TSC_G5_IO3	PB6	х	3	х	3	х	3
	TSC_G5_IO4	PB7	х		Х		х	
	TSC_G6_IO1	-	-		-		-	
CG	TSC_G6_IO2	-	-		-		-	
G6	TSC_G6_IO3	-	-	0	-	0	-	0
	TSC_G6_IO4	-	-		-		-	1
	TSC_G7_IO1	-	-		-		-	
07	TSC_G7_IO2	-	-		-		-	
G7	TSC_G7_IO3	-	-	0	-	- 0	-	- 0
	TSC_G7_IO4	-	-		-		-	
	TSC_G8_IO1	-	-		-		-	
00	TSC_G8_IO2	-	-		-		-	
G8	TSC_G8_IO3	-	-	0	-	0	-	- 0
	TSC_G8_IO4	-	-		-		-	1
	nber of capacitive Is (sampling I/Os not counted	1)		13	1	3	1	0

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

^{2.} Pin pair PA11/PA12 can be remapped instead of pin pair PA9/PA10 using SYS_CTRL register (28 and 20 pins packages only).

Devices with TSC peripheral

Table 35. Available touch sensing channels for STM32F042xx

	Capacitive		STM32	F042Cx	STM32	F042Tx		STM32	F042Kx		STM32F042Gx		STM32F042Fx	
Analog I/O group	sensing signal name	Pin name	LQFP48 UFQFPN48		WLC	WLCSP36		LQFP32		PN32	UFQF	PN28	TSSOP20	
	TSC_G1_IO1	PA0	Х		Х		Х		х		х		х	
G1	TSC_G1_IO2	PA1	Х	3	Х	3	Х	3	Х	3	Х	3	Х	3
Gi	TSC_G1_IO3	PA2	Х	3	Х	٦	Х	3	Х	3	Х	3	Х	3
	TSC_G1_IO4	PA3	Х		Х		Х		Х		Х		Х	
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		Х		Х	3	Х		Х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х	,	Х	3	Х	3	Х		Х	3	Х	3
G2	TSC_G2_IO3	PA6	Х	x 3	Х	٥	Х	3	Х		Х	3	Х	3
	TSC_G2_IO4	PA7	Х		Х		Х		Х		Х		Х	
	TSC_G3_IO1	-	-		-		-		-		-		-	
G3	TSC_G3_IO2	PB0	Х	2	x 2	Х	1	Х	2	Х	1	-	0	
G3	TSC_G3_IO3	PB1	Х	2		2	Х		Х	2	Х	1 '	Х	U
	TSC_G3_IO4	PB2	Х		Х		-		Х		-		-	
	TSC_G4_IO1	PA9 ⁽²⁾	Х		Х		Х		Х		x ⁽²⁾		x ⁽²⁾	
G4	TSC_G4_IO2	PA10 ⁽²⁾	Х	3	Х	3	Х	3	Х	3	x ⁽²⁾	1	x ⁽²⁾	1
G4	TSC_G4_IO3	PA11 ⁽²⁾	Х	3	Х	٥	Х	3	Х	3	x ⁽²⁾	'	x ⁽²⁾	1
	TSC_G4_IO4	PA12 ⁽²⁾	Х		Х		Х		Х		x ⁽²⁾		x ⁽²⁾	
	TSC_G5_IO1	PB3	Х		Х		Х		х		Х		-	
CF	TSC_G5_IO2	PB4	Х	3	x	Х	3	Х	3	Х	3	-	0	
G5 —	TSC_G5_IO3	PB6	Х			Х		Х		Х	3	-		
	TSC_G5_IO4 PB7	Х		Х		Х		Х		Х		-	Ī	



[5

Table 35. Available touch sensing channels for STM32F042xx (continued)

	Capacitive		STM32	F042Cx	STM32	F042Tx		STM32	F042Kx		STM32	F042Gx	STM32	F042Fx
Analog I/O group	sensing signal name	Pin name	Pin name LQFP48 UFQFPN48		WLC	WLCSP36		P32	UFQFPN32		UFQFPN28		TSSOP20	
	TSC_G6_IO1	-	-		-		-		-		-		-	
G6	TSC_G6_IO2	-	-	0	-	0	-	0	-	0	-	0	-	0
Go	TSC_G6_IO3	-	-		-		-		-		-		-	
	TSC_G6_IO4	-	-		-		-		-		-		-	
	TSC_G7_IO1	-	-		-		-		-		-		-	
G7	TSC_G7_IO2	-	-	-	-	- 0	-	0	-	- 0	-	0	-	0
G/	TSC_G7_IO3	-	-	- 0	-		-		-		-		-	
	TSC_G7_IO4	-	-		-		-		-		-		-	
	TSC_G8_IO1	-	-		-		-		-		-		-	
G8	TSC_G8_IO2	-	-	0	-	0	-	0	-	0	-	0	-	0
Go	TSC_G8_IO3	-	-	. 0	-		-		-		-		-	0
	TSC_G8_IO4	-	-		-		-		-		-		-	
Numbe sensing channels (s	r of capacitive sampling I/Os no	t counted)	1	14	1	4	1	3	1	4	1	1	•	7

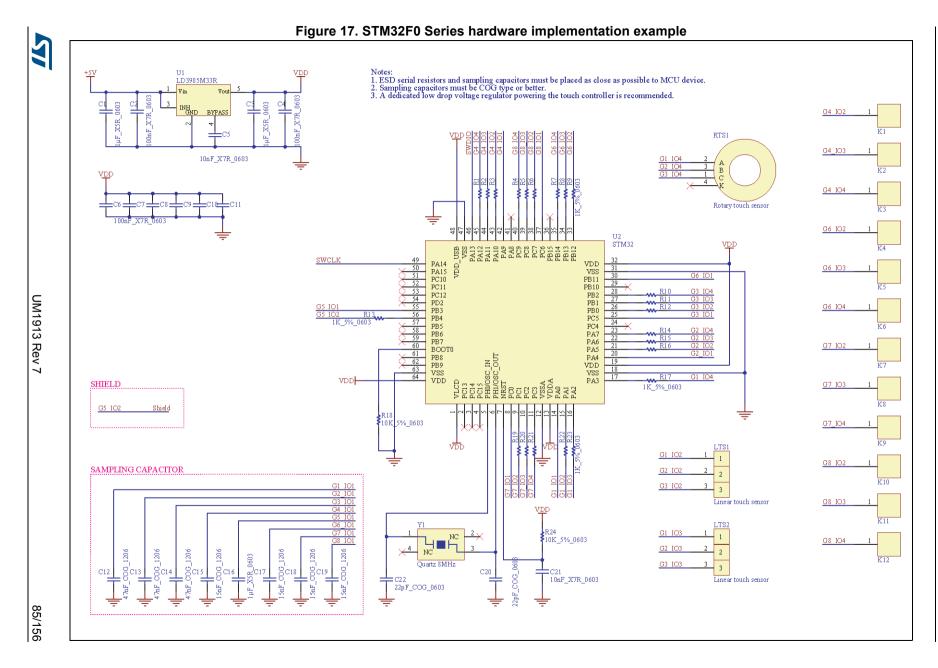
^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

^{2.} Pin pair PA11/PA12 can be remapped instead of pin pair PA9/PA10 using SYS_CTRL register (28 and 20 pins packages only).

3.5.3 Hardware implementation example

Figure 17 shows an example of hardware implementation on STM32F0 Series microcontrollers.





3.6 STM32F3 Series microcontrollers

3.6.1 **Memory footprint**

Conditions

- IAR ANSI C/C++ compiler/linker V7.40.3.8902 for Arm®
- Compiler optimization: high size
- Counted files: tsl*.o
- STM32 TouchSensing library options: ECS=ON, DTO=ON, DXS=OFF, PROX=OFF
- Each sensor has its own parameters placed in RAM

The following tables summarize the memory footprint with different configurations:

Table 36. STM32F3 Series memory footprint⁽¹⁾

Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)
1	1	1 TKey	2.8	100
2	1	2 TKeys	2.8	120
2	2	2 TKeys	2.8	120
24	3	24 TKeys	3.8	620
3	1	1 Linear-3ch	3.8	130
15	3	12 TKeys + 1 Linear-3ch	5.7	420
24	3	18 TKeys + 2 Linear-3ch	6.0	610

^{1.} The content of this table is provided for information purposes only.

3.6.2 Available touch sensing channels

The tables below provide an overview of the available touch sensing channels for the STM32F3 Series microcontrollers.

Note:

The following tables are not restrictive in term of part numbers supported by the STMTouch touch sensing library. The STMTouch touch sensing library can be used on any new device that may become available as part of ST microcontrollers portfolio. Please contact your ST representative for support.

Note:

For n available pins in an I/O group, one pin is used as sampling capacitor and n-1 pins are used as channels.

The I/O group cannot be used if the number of available pins in less or equal to one.

UM1913 Rev 7 86/156



Table 37. Available touch sensing channels for STM32F398VE

Analog I/O group	Capacitive sensing	Pin name	ST	M32F398VE			
Analog I/O group	signal name	Pin name		LQFP100			
	TSC_G1_IO1	PA0	х				
G1	TSC_G1_IO2	PA1	х	3			
Gi	TSC_G1_IO3	PA2 ⁽¹⁾	х				
	TSC_G1_IO4	PA3	х				
	TSC_G2_IO1	PA4 ⁽¹⁾	х				
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3			
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х				
	TSC_G2_IO4	PA7	х				
	TSC_G3_IO1	PC5	х				
G3	TSC_G3_IO2	PB0	х	2			
93	TSC_G3_IO3	PB1 ⁽¹⁾	x 2				
	TSC_G3_IO4	-	-				
	TSC_G4_IO1	PA9	х				
G4	TSC_G4_IO2	PA10	х	3			
04	TSC_G4_IO3	PA13	х				
	TSC_G4_IO4	PA14	х				
	TSC_G5_IO1	PB3	х				
G5	TSC_G5_IO2	PB4	х	3			
03	TSC_G5_IO3	PB6	х	3			
	TSC_G5_IO4	PB7	х				
	TSC_G6_IO1	PB11	х				
G6	TSC_G6_IO2	PB12 ⁽¹⁾	х	3			
	TSC_G6_IO3	PB13	х	Ŭ			
	TSC_G6_IO4	PB14	х				
	TSC_G7_IO1	PE2	х				
G7	TSC_G7_IO2	PE3	х	3			
Oi	TSC_G7_IO3	PE4	х	J			
	TSC_G7_IO4	PE5	х				
	TSC_G8_IO1	PD12	х				
G8	TSC_G8_IO2	PD13	х	3			
30	TSC_G8_IO3	PD14	х				
	TSC_G8_IO4	PD15	Х				
	ber of capacitive s (sampling I/Os not coun	ted)		23			

This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



UM1913 Rev 7 87/156

Table 38. Available touch sensing channels for STM32F378xx

Analog I/O	Capacitive	Pin		STM32			STM32F378Rx				STM32F378Cx		
group	sensing signal name	name	LC	QFP100	В	GA100	L	QFP64	WL	CSP66	L	QFP48	
	TSC_G1_IO1	PA0	х		Х		Х		Х		Х		
G1	TSC_G1_IO2	PA1	х	3	х	3	х	3	х	3	Х	3	
Gi	TSC_G1_IO3	PA2	х		Х	3	Х	3	х	3	Х	3	
	TSC_G1_IO4	PA3	х		х		х		х		Х		
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		х		х		Х		
62	TSC_G2_IO2	PA5 ⁽¹⁾	х	9	х	3	Х	3	х	,	Х	2	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	Х	3	Х	3	х	3	Х	2	
	TSC_G2_IO4	PA7	х		Х		Х		х		-		
	TSC_G3_IO1	PC4	х		х		х		х		-		
G3	TSC_G3_IO2	PC5	х	9	Х	3	Х	3	х	,	-	1	
GS	TSC_G3_IO3	PB0	х	\dashv \vdash	Х	3	Х	3	х	3	Х	1	
	TSC_G3_IO4	PB1	х		Х		Х		х		Х		
TSC	TSC_G4_IO1	PA9	х		х	3	х	3 -	х	3	х		
0.4	TSC_G4_IO2	PA10	х		х		х		х		Х	3	
G4	TSC_G4_IO3	PA13	х	3	Х		Х		х		Х	3	
	TSC_G4_IO4	PA14	х		х		х		х		Х		
	TSC_G5_IO1	PB3	х		х		х		х		х		
05	TSC_G5_IO2	PB4	х		Х	3	Х	3	х	,	Х	2	
G5	TSC_G5_IO3	PB6	х	3	х	3	Х	3	х	3	х	3	
	TSC_G5_IO4	PB7	х		х		Х		х		Х		
	TSC_G6_IO1	PB14	х		х		х		х		х		
00	TSC_G6_IO2	PB15	х		х	•	х	•	х	_	Х	0	
G6	TSC_G6_IO3	PD8	х	3	х	3	х	2	х	2	Х	2	
	TSC_G6_IO4	PD9	х		х		-		-		-		
	TSC_G7_IO1	PE2	х		х		-		-		-		
G7	TSC_G7_IO2	PE3	х	3	х 3	,	-	0	-		-		
	TSC_G7_IO3	PE4	х			-	- 0	-	- 0	-	- 0		
	TSC_G7_IO4	PE5	х		х		-		-		-	 }	

Table 38. Available touch sensing channels for STM32F378xx (continued)

Analog I/O	Capacitive	Pin name	STM32F378Vx				STM32F378Rx				STM32F378Cx	
group	sensing signal name		LQFP100		BGA100		L	LQFP64		WLCSP66		LQFP48
	TSC_G8_IO1	PD12	х		х		-		-		-	
G8	TSC_G8_IO2	PD13	х	3	х	3	-	0	-	0	-	0
Go	TSC_G8_IO3	PD14	х	3	х	_	-	_	-		-	0
	TSC_G8_IO4	PD15	х		х		-		-		-	·
	nber of capacitive nnels (sampling I/ counted)	Os not		24		24		17		17		14

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 39. Available touch sensing channels for STM32F373xx

Analog I/O	Capacitive	Pin		STM32	F373\	/x	STM	32F373Rx	STM32F373Cx	
group	sensing signal name	name	LC	QFP100	В	GA100	L	QFP64	LQF	P48
	TSC_G1_IO1	PA0	х		х		х		Х	
G1	TSC_G1_IO2	PA1	Х	3	Х	3	х	3	Х	3
Gi	TSC_G1_IO3	PA2	Х		х	3	х	3	Х	3
	TSC_G1_IO4	PA3	Х		Х		х		Х	
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		х		Х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х		Х	3	х	3	Х	0
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	Х	3	х	3	Х	2
	TSC_G2_IO4	PA7	Х		Х		х		-	
	TSC_G3_IO1	PC4	Х		Х		х		-	
G3	TSC_G3_IO2	PC5	х	3	Х	3	х	2	-	4
G3	TSC_G3_IO3	PB0	Х	3	Х	3	х	3	х	1
	TSC_G3_IO4	PB1	Х		Х		х		Х	
	TSC_G4_IO1	PA9	х		Х		х		Х	
04	TSC_G4_IO2	PA10	Х	3	Х	3	х	3	Х	2
G4	TSC_G4_IO3	PA13	х	3	Х	3	х	3	Х	3
	TSC_G4_IO4	PA14	Х		Х		х		Х	
	TSC_G5_IO1	PB3	х		х		х		Х	
CF	TSC_G5_IO2	PB4	х	3	Х	x 3	х	x 3	Х	,
G5	TSC_G5_IO3	PB6	х	3	Х		х		Х	3
	TSC_G5_IO4	PB7	х		Х		х		Х	



UM1913 Rev 7 89/156

Table 39. Available touch sensing channels for STM32F373xx (continued)

Analog I/O	Capacitive	Pin		STM32	F373\	/x	STM	32F373Rx	STM32F373Cx	
group	sensing signal name	name	LC	LQFP100		GA100	L	QFP64	LQFP48	
	TSC_G6_IO1	PB14	Х		Х		х		Х	
G6	TSC_G6_IO2	PB15	Х	3	Х	3	х	2	Х	2
Go	TSC_G6_IO3	PD8	Х	3	Х	3	х	2	Х	2
	TSC_G6_IO4	PD9	х		Х		-		-	
	TSC_G7_IO1	PE2	х		Х		-		-	
G7	TSC_G7_IO2	PE3	х з	Х	3	-	0	-	0	
G/	TSC_G7_IO3	PE4	Х		Х	3	-		-	U
	TSC_G7_IO4	PE5	Х		Х		-		-	
	TSC_G8_IO1	PD12	Х		Х		-		-	
G8	TSC_G8_IO2	PD13	х	3	Х	3	-	0	-	0
Go	TSC_G8_IO3	PD14	Х	3	Х	3	-	U	-	U
	TSC_G8_IO4	PD15	Х		Х		-		-	
Number of capacitive sensing channels (sampling I/Os not counted)		s not	24		24		17		14	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 40. Available touch sensing channels for STM32F358xC

Analog I/O group	Capacitive	Pin	STM	32F358Vx	STM	32F358Rx	STM32F358Cx	
Analog I/O group	sensing signal name	name	L	LQFP100		QFP64	LQFP48	
	TSC_G1_IO1	PA0	х		х		Х	
G1	TSC_G1_IO2	3	2	х	3	х	3	
Gi	TSC_G1_IO3	PA2 ⁽¹⁾	х	3	х	3	Х	3
	TSC_G1_IO4	PA3	х		Х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		Х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	х	3	Х	3
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	х	3	х	3
	TSC_G2_IO4	PA7	х		х		Х	
	TSC_G3_IO1	PC5	х		х		-	
C3	TSC_G3_IO2	PB0	х	2	Х	2	Х	1
<u> </u>	TSC_G3_IO3	PB1 ⁽¹⁾	х	2		2	Х	ı
	TSC_G3_IO4	-	-		-		-	

Table 40. Available touch sensing channels for STM32F358xC (continued)

A	Capacitive	Pin	STM	32F358Vx	STM	32F358Rx	STM32F358Cx	
Analog I/O group	sensing signal name	name	L	QFP100	L	QFP64	LQF	P48
	TSC_G4_IO1	PA9	Х		х		Х	
G4	TSC_G4_IO2	PA10	Х	3	х	3	Х	3
G4	TSC_G4_IO3	PA13	Х	3	Х	3	х	3
	TSC_G4_IO4	PA14	Х		Х		Х	
	TSC_G5_IO1	PB3	Х		х		Х	
G5	TSC_G5_IO2	PB4	Х	3	Х	3	х	3
65	TSC_G5_IO3	PB6	Х	3	Х	3	Х	3
	TSC_G5_IO4	PB7	Х		Х		Х	
	TSC_G6_IO1	PB11	Х		Х		х	
G6	TSC_G6_IO2	PB12 ⁽¹⁾	Х	3	Х	3	Х	3
00	TSC_G6_IO3	PB13	Х		х	3	Х	3
	TSC_G6_IO4	PB14	Х		х		Х	
	TSC_G7_IO1	PE2	Х		-		-	
G7	TSC_G7_IO2	PE3	Х	3	-	0	-	0
G/	TSC_G7_IO3	PE4	Х		-	O	-	U
	TSC_G7_IO4	PE5	Х		-		-	
	TSC_G8_IO1	PD12	Х		-		-	
G8	TSC_G8_IO2	PD13	Х	3	-	0	-	0
G8	TSC_G8_IO3	PD14	Х	3		U	-	U
	TSC_G8_IO4	PD15	Х		-		-	
Number of capacitive sensing channels (sampling I/Os not counted)		ot counted)		23		17	1	6

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 41. Available touch sensing channels for STM32F334x4/x6/x8

Analog I/O group	Capacitive	Pin	STM	32F334Rx	STM32	F334Cx	STM32F334Kx	
Analog I/O group	sensing signal name	name	LQFP64		LQFP48		LQFP32	
	TSC_G1_IO1	PA0	х		Х		Х	
G1	TSC_G1_IO2	PA1	х	3	Х	3	х	3
Gi	TSC_G1_IO3	PA2	Х	3	х	3	Х	3
	TSC_G1_IO4	PA3	Х		Х		Х	



UM1913 Rev 7 91/156

Table 41. Available touch sensing channels for STM32F334x4/x6/x8 (continued)

Analog I/O group	Capacitive sensing	Pin	STM	32F334Rx	STM32	F334Cx	STM32F334Kx		
Analog #O group	signal name	name	L	QFP64	LQF	P48	L	QFP32	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		X		х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	Х	3	х	3	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	Х	3	Х	3	
	TSC_G2_IO4	PA7	х		Х		х		
	TSC_G3_IO1	PC5	Х		-		-		
Ca	TSC_G3_IO2	PB0	х	2	Х	,	х	1	
G3	TSC_G3_IO3	PB1	х	3	Х	2	х	1	
	TSC_G3_IO4	PB2	х		Х		-		
	TSC_G4_IO1	PA9	х		Х		х		
0.4	TSC_G4_IO2	PA10	х	0	Х		х	0	
G4	TSC_G4_IO3	PA13	х	3	х	3	х	3	
	TSC_G4_IO4	PA14	х		Х		х		
	TSC_G5_IO1	PB3	х		Х		х		
0.5	TSC_G5_IO2	PB4	х		Х		х	0	
G5	TSC_G5_IO3	PB6	х	3	Х	3	х	3	
	TSC_G5_IO4	PB7	х		Х		х		
	TSC_G6_IO1	PB11	х		х		-		
	TSC_G6_IO2	PB12	х		х		-	0	
G6	TSC_G6_IO3	PB13	х	3	Х	3	-	0	
	TSC_G6_IO4	PB14	х		х		-		
	TSC_G7_IO1	-	-		-		-		
07	TSC_G7_IO2	-	-	0	-		-	0	
G7	TSC_G7_IO3	-	-	0	-	0	-	0	
	TSC_G7_IO4	-	-		-		-		
	TSC_G8_IO1	-	-		-		-		
CO	TSC_G8_IO2	-	-		-		-		
G8 -	TSC_G8_IO3	-	-	0	-	0	-	0	
	TSC_G8_IO4	-	-		-		-		
Numbe sensing channels (s	r of capacitive campling I/Os no	t counted)		18	1	7		13	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 42. Available touch sensing channels for STM32F328C8

Analog I/O group	Capacitive sensing	Pin name	STM32	F328C8			
Analog #O group	signal name	Fill Hallie	LQI	FP48			
	TSC_G1_IO1	PA0	Х				
G1	TSC_G1_IO2	PA1	Х	3			
Gi	TSC_G1_IO3	PA2	Х] 3			
	TSC_G1_IO4	PA3	Х				
	TSC_G2_IO1	PA4 ⁽¹⁾	Х				
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х	3			
G2	TSC_G2_IO3	PA6 ⁽¹⁾	Х	3			
	TSC_G2_IO4	PA7	Х				
	TSC_G3_IO1	-	-				
G3	TSC_G3_IO2	PB0	Х	1			
G3	TSC_G3_IO3	PB1	Х	- 			
	TSC_G3_IO4	-	-				
	TSC_G4_IO1	PA9	Х				
G4	TSC_G4_IO2	PA10	Х	3			
G4	TSC_G4_IO3	PA13	Х	3			
	TSC_G4_IO4	PA14	Х				
	TSC_G5_IO1	PB3	Х				
G5	TSC_G5_IO2	PB4	Х	3			
93	TSC_G5_IO3	PB6	Х				
	TSC_G5_IO4	PB7	Х				
	TSC_G6_IO1	PB11	Х				
G6	TSC_G6_IO2	PB12	Х	3			
90	TSC_G6_IO3	PB13	Х				
	TSC_G6_IO4	PB14	Х				
	TSC_G7_IO1	-	-				
G7	TSC_G7_IO2	-	-	0			
G/	TSC_G7_IO3	-	-				
	TSC_G7_IO4	-	-				
	TSC_G8_IO1	-	-				
G8	TSC_G8_IO2	-	-	0			
Go	TSC_G8_IO3	-	-] "			
	TSC_G8_IO4	-	-	1			
	Number of capacitive sensing channels (sampling I/Os not counted) 16						

This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



Table 43. Available touch sensing channels for STM32F318x8

A I I	Capacitive		STM32	F318C8	STM	132F318K8	
Analog I/O group	sensing signal name	Pin name	WLC	SP49	ι	JQFN32	
	TSC_G1_IO1	PA0	х		Х		
G1	TSC_G1_IO2	PA1	х	3	Х	3	
Gi	TSC_G1_IO3	PA2 ⁽¹⁾	х	3	х	3	
	TSC_G1_IO4	PA3	х		Х		
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		
62	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	Х	2	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	Х	3	
	TSC_G2_IO4	PA7	Х	1	Х		
	TSC_G3_IO1	-	-		-		
62	TSC_G3_IO2	PB0	х	1	Х	0	
G3	TSC_G3_IO3	PB1	х	1	-	0	
	TSC_G3_IO4	-	-	1	-		
	TSC_G4_IO1	PA9	Х		Х		
04	TSC_G4_IO2	PA10	Х	2	Х		
G4	TSC_G4_IO3	PA13	х	3	Х	3	
	TSC_G4_IO4	PA14	х		Х		
	TSC_G5_IO1	PB3	Х		Х		
05	TSC_G5_IO2	PB4	Х	3	Х		
G5	TSC_G5_IO3	PB6	х	3	Х	2	
	TSC_G5_IO4	PB7	х	1	-		
	TSC_G6_IO1	PB11	х		-		
00	TSC_G6_IO2	PB12	х	2	-	0	
G6	TSC_G6_IO3	PB13	х	3	-	0	
	TSC_G6_IO4	PB14	х		-		
	TSC_G7_IO1	-	-		-		
G7	TSC_G7_IO2	-	-	1	-	0	
G/	TSC_G7_IO3	-	-	- 0	-	0	
	TSC_G7_IO4	-	-	1	-		
	TSC_G8_IO1	-	-		-		
G8	TSC_G8_IO2	-	-	0	-	0	
96	TSC_G8_IO3	-	-] "	-	U	
	TSC_G8_IO4	-	-]	-		
	Number of capacitive sensing channels (sampling I/Os not count		1	16		11	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



Table 44. Available touch sensing channels for STM32F303xD/xE

Analog I/O	Capacitive	Pin		132F303Zx		STM32			STM32F303Rx		
group	sensing signal name	name	L	QFP144	LC	QFP100	UF	BGA100	LQFP64		
	TSC_G1_IO1	PA0	Х		Х		Х		Х		
G1	TSC_G1_IO2	PA1	х	3	Х	3	Х	3	х	3	
01	TSC_G1_IO3	PA2 ⁽¹⁾	х		Х	3	Х		х	3	
	TSC_G1_IO4	PA3	х		Х		Х		х		
	TSC_G2_IO1	PA4 ⁽¹⁾	х		Х		х		х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	Х	3	Х	2	х	3	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х		Х		Х	3	Х	3	
	TSC_G2_IO4	PA7	х		Х		Х		х		
	TSC_G3_IO1	PC5	х		Х		х		х		
G3	TSC_G3_IO2	PB0	х	3	Х	3	Х	3	Х	2	
GS	TSC_G3_IO3	PB1 ⁽¹⁾	х	3	Х	3	Х	J	х	3	
	TSC_G3_IO4	PB2	х		Х		Х		х		
	TSC_G4_IO1	PA9	х		Х	3	Х		х		
G4	TSC_G4_IO2	PA10	х	3	Х		Х	3	х	3	
G 4	TSC_G4_IO3	PA13	х	3	Х		Х		Х	3	
	TSC_G4_IO4	PA14	х		Х		Х		х		
	TSC_G5_IO1	PB3	х		Х		х		х		
G5	TSC_G5_IO2	PB4	х	3	Х	3	Х	3	Х	3	
Go	TSC_G5_IO3	PB6	х	3	Х	3	Х	3	х	3	
	TSC_G5_IO4	PB7	х		Х		Х		х		
	TSC_G6_IO1	PB11	х		Х		х		х		
G6	TSC_G6_IO2	PB12 ⁽¹⁾	х	3	Х	3	Х	3	Х	2	
Go	TSC_G6_IO3	PB13	х	3	Х	3	Х	3	Х	3	
	TSC_G6_IO4	PB14	х		Х		Х		Х		
	TSC_G7_IO1	PE2	Х		Х		Х		-		
07	TSC_G7_IO2	PE3	X 3	Х		Х	x	-			
G7	TSC_G7_IO3	PE4	х	<u> </u>	Х	3	Х	3	-	0	
	TSC_G7_IO4	PE5	Х		Х		х		-		



UM1913 Rev 7 95/156

Table 44. Available touch sensing channels for STM32F303xD/xE (continued)

Analog I/O	Capacitive sensing signal	Pin	STM	132F303Zx		STM32	STM32F303Rx			
group	name	name	L	LQFP144		LQFP100		UFBGA100		.QFP64
	TSC_G8_IO1	PD12	х		Х		Х		-	
G8	TSC_G8_IO2	PD13	x 3	Х	3	Х	3	-	0	
Go	TSC_G8_IO3	PD14	х	3	Х	3	Х		-	U
	TSC_G8_IO4	PD15	х	х			Х		-	
Number of capacitive sensing channels (sampling I/Os n counted)		Os not	24		24			24	18	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 45. Available touch sensing channels for STM32F303xB/xC

A	Capacitive	Pin	STM	32F303Vx	STM	32F303Rx	STM32F303Cx		
Analog I/O group	sensing signal name	name	L	QFP100	L	QFP64	LQFP48		
	TSC_G1_IO1	PA0	Х		х		х		
G1	TSC_G1_IO2	PA1	х	3	х	3	х	3	
91	TSC_G1_IO3	PA2 ⁽¹⁾	х	3	х	3	х	3	
	TSC_G1_IO4	PA3	х		х		Х		
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		Х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	х	3	Х	2	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	х	3	Х	3	
	TSC_G2_IO4	PA7	х		Х		Х		
	TSC_G3_IO1	PC5	х		х			-	
G3	TSC_G3_IO2	PB0	х	3	х	2	Х	2	
GS	TSC_G3_IO3	PB1 ⁽¹⁾	х	3	х	3	Х		
	TSC_G3_IO4	PB2	х		х		Х		
	TSC_G4_IO1	PA9	х		х		Х		
G4	TSC_G4_IO2	PA10	х	3	Х	3	Х	3	
G4	TSC_G4_IO3	PA13	х	3	х	3	Х	ა	
	TSC_G4_IO4	PA14	х		х		Х		
	TSC_G5_IO1	PB3	х		х		х		
G5	TSC_G5_IO2	PB4	х	2	Х	3	Х	3	
	TSC_G5_IO3	PB6	х	3	Х		х		
	TSC_G5_IO4	PB7	х		х		х	1	

Table 45. Available touch sensing channels for STM32F303xB/xC (continued)

Analog I/O group	Capacitive sensing	Pin	STM	32F303Vx	STM	32F303Rx	STM32	F303Cx	
Analog I/O group	signal name name		LQFP100		L	QFP64	LQFP48		
	TSC_G6_IO1	PB11	Х		Х		Х		
G6	G6 TSC_G6_IO2 PB12 ⁽¹⁾ x 3	2	х	3	Х	3			
00	TSC_G6_IO3	PB13	Х	3	х	3	Х	3	
	TSC_G6_IO4	PB14	Х		х		Х		
	TSC_G7_IO1	PE2	Х	- 3	-	- 0	-	0	
67	TSC_G7_IO2	PE3	Х		-		-		
G7	TSC_G7_IO3	PE4	Х		-		-		
	TSC_G7_IO4	PE5	Х		-		-		
	TSC_G8_IO1	PD12	Х		-		-		
G8	TSC_G8_IO2	PD13	Х	3	-	0	-	0	
Go	TSC_G8_IO3	PD14	Х	3	-	U	-	0	
	TSC_G8_IO4	PD15	Х		-		-		
Number of capacitive sensing channels (sampling I/Os not counted)		24		18		17			

This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 46. Available touch sensing channels for STM32F303x6/x8

Analog I/O group	Capacitive	Pin	STM	32F303Rx	STM32	F303Cx	STM32F303Kx	
Analog I/O group	sensing signal name	name	L	LQFP64		P48	LQFP32	
	TSC_G1_IO1	PA0	Х		Х		х	
G1	TSC_G1_IO2	PA1	х	3	х	- 3	х	3
01	TSC_G1_IO3	PA2 ⁽¹⁾	Х		Х		Х	3
	TSC_G1_IO4	PA3	Х		Х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		Х	- 3	х	3
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	Х		х	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	Х		х	
	TSC_G2_IO4	PA7	х		Х		х	
	TSC_G3_IO1	PC5	х		-		-	
G3 -	TSC_G3_IO2	PB0	х	3	Х	2	х	0
	TSC_G3_IO3	PB1 ⁽¹⁾	х	3	Х		-	
	TSC_G3_IO4	PB2	х		Х		-	

577

UM1913 Rev 7 97/156

Table 46. Available touch sensing channels for STM32F303x6/x8 (continued)

A I I/O	Capacitive	Pin	STM	32F303Rx	STM32	F303Cx	STM32F303Kx	
Analog I/O group	sensing signal name	name	L	QFP64	LQF	P48	LQFP32	
	TSC_G4_IO1	PA9	Х		Х		х	
G4	TSC_G4_IO2	PA10	Х	3	Х	3	х	3
G4	TSC_G4_IO3	PA13	Х	3	х	3	х	3
	TSC_G4_IO4	PA14	Х		Х		х	
	TSC_G5_IO1	PB3	Х		Х		х	
G5	TSC_G5_IO2	PB4	Х	3	Х	3	х	3
65	TSC_G5_IO3	PB6	Х	3	Х	3	х	3
	TSC_G5_IO4	PB7	Х		Х		х	
	TSC_G6_IO1	PB11	Х		х	3	-	0
G6	TSC_G6_IO2	PB12 ⁽¹⁾	Х	3	Х		-	
00	TSC_G6_IO3	PB13	Х	3	Х	3	-	
	TSC_G6_IO4	PB14	Х		Х		-	
	TSC_G7_IO1	-	ı		-		-	
G7	TSC_G7_IO2	-	-	0	-	0	-	0
G/	TSC_G7_IO3	-	ı	O	-	U	-	O
	TSC_G7_IO4	-	ı		-		-	
	TSC_G8_IO1	-	-		-		-	
G8	TSC_G8_IO2	-	-	0	-	0	-	0
G8 -	TSC_G8_IO3	-	-		-	U	-	U
	TSC_G8_IO4	-	ı		-		-	
Number of capacitive sensing channels (sampling I/Os not counted)				18	1	7		12

This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 47. Available touch sensing channels for STM32F302xD/xE

Analog I/O Capacitive sensing signal		Pin	STM	STM32F302Zx		STM32	STM32F302Rx			
group	name	name	LQFP144		LQFP100		UFBGA100		LQFP64	
	TSC_G1_IO1	PA0	Х		Х		Х		Х	
G1	TSC_G1_IO2	PA1	х	3	Х	3	Х	3	Х	3
G1	TSC_G1_IO3	PA2 ⁽¹⁾	х		Х	3	Х	3	х	3
	TSC_G1_IO4	PA3	х	Х		Х		Х		



Table 47. Available touch sensing channels for STM32F302xD/xE (continued)

Analog I/O	Capacitive	Pin	STM	32F302Zx		STM32	F302\	/x	STM	32F302Rx
group	sensing signal name	name	L	QFP144	LC	QFP100	UF	BGA100	LQFP64	
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		Х		Х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х	3	Х	3	Х	3	х	3
G2	TSC_G2_IO3	PA6 ⁽¹⁾	Х	3	Х	3	Х	3	х	3
	TSC_G2_IO4	PA7	Х		Х		Х		х	
	TSC_G3_IO1	PC5	Х		Х		Х		х	
G3	TSC_G3_IO2	PB0	Х	3	Х	3	Х	3	Х	3
GS	TSC_G3_IO3	PB1 ⁽¹⁾	Х	3	Х	3	Х	3	х	3
	TSC_G3_IO4	PB2	Х		Х		Х		х	
	TSC_G4_IO1	PA9	Х		Х		Х		х	
0.4	TSC_G4_IO2	PA10	Х	0	Х	0	Х	0	х	2
G4	TSC_G4_IO3	PA13	Х	x 3		3	Х	3	х	3
	TSC_G4_IO4	PA14	Х		Х		Х		х	
	TSC_G5_IO1	PB3	Х		Х		Х		х	
05	TSC_G5_IO2	PB4	Х	0	Х	0	Х	0	х	2
G5	TSC_G5_IO3	PB6	Х	3	Х	3	Х	3	х	3
	TSC_G5_IO4	PB7	Х		Х		Х		х	
	TSC_G6_IO1	PB11	Х		х		х		х	
00	TSC_G6_IO2	PB12 ⁽¹⁾	Х	2	Х	2	Х	2	х	2
G6	TSC_G6_IO3	PB13	Х	3	Х	3	Х	3	х	3
	TSC_G6_IO4	PB14	Х		Х		Х		х	
	TSC_G7_IO1	PE2	Х		Х		Х		-	
07	TSC_G7_IO2	PE3	Х	2	Х	2	Х	2	-	0
G7	TSC_G7_IO3	PE4	Х	3	Х	3	Х	3	-	0
	TSC_G7_IO4	PE5	Х		Х		Х		-	
	TSC_G8_IO1	PD12	Х		х		х		-	
C0	TSC_G8_IO2	PD13	Х	3	х	2	х	2	-	0
G8 TSC_0	TSC_G8_IO3	PD14	Х		Х	3	Х	3	-	0
	TSC_G8_IO4	PD15	Х		Х		Х		-	
	Number of capacitive sensing channels (sampling I/Os not counted)			24		24		24	18	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



UM1913 Rev 7 99/156

Table 48. Available touch sensing channels for STM32F302xB/xC

A a l a 1/0	Capacitive	Pin	STM	32F302Vx	STM	32F302Rx	STM32F302Cx		
Analog I/O group	sensing signal name	name	L	QFP100	L	QFP64	LQF	P48	
	TSC_G1_IO1	PA0	х		х		Х		
G1	TSC_G1_IO2	PA1	х	3	х	3	Х	3	
Gi	TSC_G1_IO3	PA2 ⁽¹⁾	х		х	3	Х		
	TSC_G1_IO4	PA3	х		х		Х		
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х		Х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	х	3	Х	3	х	3	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	х	3	х	3	Х	3	
	TSC_G2_IO4	PA7	х		х		х	L	
	TSC_G3_IO1	PC5	х		х		-		
C2	TSC_G3_IO2	PB0	х	,	х	3	х	2	
G3	TSC_G3_IO3	PB1 ⁽¹⁾	х	3	х	3	х		
	TSC_G3_IO4	PB2	х		х		Х		
	TSC_G4_IO1	PA9	х		х		Х		
G4	TSC_G4_IO2	PA10	х	3	х	3	Х	3	
G4	TSC_G4_IO3	PA13	х	٥	х	3	х	3	
	TSC_G4_IO4	PA14	х		х		Х		
	TSC_G5_IO1	PB3	х		х		Х		
G5	TSC_G5_IO2	PB4	х	3	х	3	х	3	
G5	TSC_G5_IO3	PB6	х	٥	х	3	х	3	
	TSC_G5_IO4	PB7	х		х		Х		
	TSC_G6_IO1	PB11	х		х		Х		
00	TSC_G6_IO2	PB12 ⁽¹⁾	х		Х	2	Х	,	
G6	TSC_G6_IO3	PB13	х	3	х	3	Х	3	
	TSC_G6_IO4	PB14	х		х		Х		
	TSC_G7_IO1	PE2	х		-		-		
G7	TSC_G7_IO2	PE3	х	3	-	0	-	0	
G/	TSC_G7_IO3	PE4	х	3	-	U	-	U	
	TSC_G7_IO4	PE5	х		-		-		
	TSC_G8_IO1	PD12	х		-		-		
	TSC_G8_IO2	PD13	х	2	-	0	-		
G8	TSC_G8_IO3	PD14	х	<u> </u>		0	-	- 0	
	TSC_G8_IO4	PD15	х		-		-		
Numbe sensing channels (s	r of capacitive sampling I/Os no	ot counted)		24		18	1	7	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



Table 49. Available touch sensing channels for STM32F302x6/x8

Analog I/O	Capacitive	Pin		132F302Rx		STM32			STM32F302Kx		
group	sensing signal name	name	L	.QFP64	LQF	P48	WLC	SP49	U	UQFN32	
	TSC_G1_IO1	PA0	Х		Х		Х		х		
G1	TSC_G1_IO2	PA1	Х	3	Х	3	Х	3	х	3	
01	TSC_G1_IO3	PA2 ⁽¹⁾	Х		Х	3	Х	3	Х	3	
	TSC_G1_IO4	PA3	Х		Х		Х		х		
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		Х		х		
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х	3	Х	3	Х	3	х	3	
G2	TSC_G2_IO3	PA6 ⁽¹⁾	Х	3	Х	3	Х	3	Х	3	
	TSC_G2_IO4	PA7	Х		Х		Х		Х		
	TSC_G3_IO1	PC5	Х		-		-		-		
00	TSC_G3_IO2	PB0	Х		Х		Х		х	0	
G3	TSC_G3_IO3	PB1 ⁽¹⁾	Х	3	Х	2	Х	2	-	0	
	TSC_G3_IO4	PB2	х		Х		х		-		
	TSC_G4_IO1	PA9	Х		Х		Х		х		
0.4	TSC_G4_IO2	PA10	х	3	Х	3	х	_	х	0	
G4	TSC_G4_IO3	PA13	Х	3	3 x		Х	3	х	3	
	TSC_G4_IO4	PA14	Х		Х		Х		х		
	TSC_G5_IO1	PB3	х		Х		х		х		
0.5	TSC_G5_IO2	PB4	Х		Х		Х		х	3	
G5	TSC_G5_IO3	PB6	х	3	Х	3	Х	3	х	ა ა	
	TSC_G5_IO4	PB7	Х		Х		Х		х		
	TSC_G6_IO1	PB11	Х		Х		-		-		
	TSC_G6_IO2	PB12 ⁽¹⁾	Х		Х		-		-	•	
G6	TSC_G6_IO3	PB13	Х	3	Х	3	-	3	-	0	
	TSC_G6_IO4	PB14	Х	1	Х		-		-		
	TSC_G7_IO1	-	-		-		-		-		
07	TSC_G7_IO2	-	-		-		-		-	0	
G7	TSC_G7_IO3	-	-	0	-	0	-	0	-	0	
	TSC_G7_IO4	-	-	-	-		-		-	-	
	TSC_G8_IO1	-	-		-		-		-		
	TSC_G8_IO2	-	-	0	-		-		-		
G8	TSC_G8_IO3	-	-		-	0	-	0	-	0	
	TSC_G8_IO4	-	-	1	-	1	-		-		
	Number of capacitive sensing channels (sampling I/Os not counted)			18	1	7	1	7		12	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



UM1913 Rev 7 101/156

Table 50. Available touch sensing channels for STM32F301x6/x8

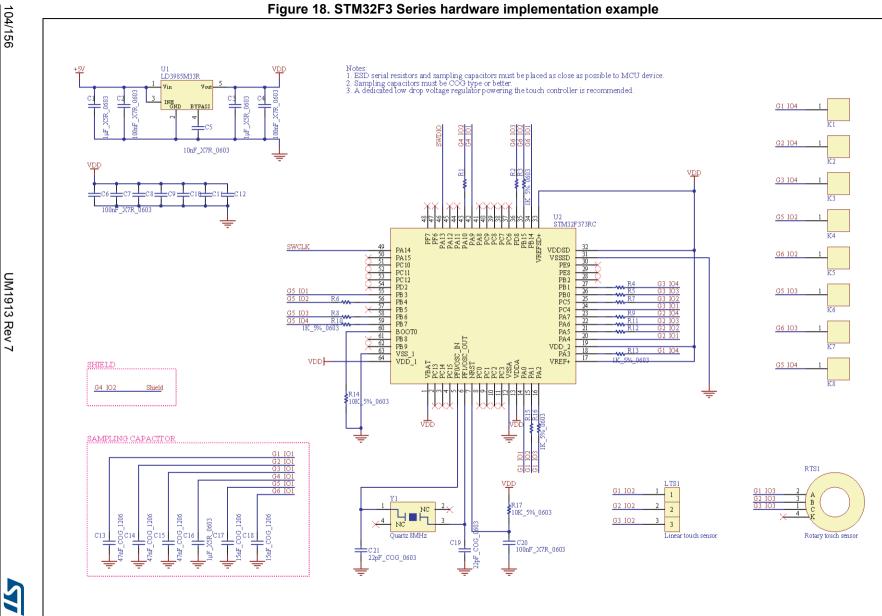
Analog I/O	Capacitive	Pin	STM	STM32F301Rx STM32		STM32	F301Cx		STM32F301Kx	
group	sensing signal name	name	LQFP64		LQFP48		WLCSP49		UQFN32	
G1	TSC_G1_IO1	PA0	Х		х	3	Х	3	Х	3
	TSC_G1_IO2	PA1	Х	3	Х		Х		х	
	TSC_G1_IO3	PA2 ⁽¹⁾	Х	3	Х		Х		Х	
	TSC_G1_IO4	PA3	Х		Х		Х		Х	
	TSC_G2_IO1	PA4 ⁽¹⁾	Х	- 3	х	3	х	3	х	
G2	TSC_G2_IO2	PA5 ⁽¹⁾	Х		Х		Х		Х	3
G2	TSC_G2_IO3	PA6 ⁽¹⁾	Х		Х		Х		Х	3
	TSC_G2_IO4	PA7	Х		Х		Х		Х	
	TSC_G3_IO1	PC5	Х		-		-		-	
62	TSC_G3_IO2	PB0	Х		Х	,	Х	2	х	0
G3	TSC_G3_IO3	PB1 ⁽¹⁾	Х	3	Х	2	Х	2	-	0
	TSC_G3_IO4	PB2	Х		Х		Х		-	
	TSC_G4_IO1	PA9	х	3	х	3	х	. 3	х	3
0.4	TSC_G4_IO2	PA10	х		Х		Х		х	
G4	TSC_G4_IO3	PA13	х		Х		х		х	
	TSC_G4_IO4	PA14	х		х		х		х	
	TSC_G5_IO1	PB3	х	3	Х	3 x	х	3	х	3
0.5	TSC_G5_IO2	PB4	Х		Х		Х		х	
G5	TSC_G5_IO3	PB6	Х		Х		Х		х	
	TSC_G5_IO4	PB7	Х		Х		Х		х	
	TSC_G6_IO1	PB11	Х		х	2	-	3	-	0
00	TSC_G6_IO2	PB12 ⁽¹⁾	Х		Х		-		-	
G6	TSC_G6_IO3	PB13	Х	3	Х	3	-		-	
	TSC_G6_IO4	PB14	Х	1	Х		-		-	
	TSC_G7_IO1	-	-	0	-	0	-	0	-	0
07	TSC_G7_IO2	-	-		-		-		-	
G7	TSC_G7_IO3	-	-		-		-		-	
	TSC_G7_IO4	-	-		-		-		-	
G8	TSC_G8_IO1	-	-		-	0	-	0	-	
	TSC_G8_IO2	-	-	0 -	-		-		-	0
	TSC_G8_IO3	-	-		-		-		-	
	TSC_G8_IO4	-	-		-		-		-	
Number of capacitive sensing channels (sampling I/Os not counted)			18	1	7	1	7		12	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

3.6.3 Hardware implementation example

Figure 18 shows an example of hardware implementation on STM32F3 Series microcontrollers.







3.7 STM32L0 Series microcontrollers

3.7.1 Memory footprint

Conditions

- IAR ANSI C/C++ compiler/linker V7.40.3.8902 for Arm®
- Compiler optimization: high size
- Counted files: tsl*.o
- STM32 TouchSensing library options: ECS=ON, DTO=ON, DXS=OFF, PROX=OFF
- Each sensor has its own parameters placed in RAM

The following table summarize the memory footprint with different configurations:

Table 51. STM32L0 Series memory footprint⁽¹⁾

Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)	
1	1	1 TKey	3.0	100	
2	1	2 TKeys	3.0	120	
2	2	2 TKeys	3.0	120	
24	3	24 TKeys	4.0	620	
3	1	1 Linear-3ch	4.1	130	
15	3	12 TKeys + 1 Linear-3ch	6.2	420	
24	3	18 TKeys + 2 Linear-3ch	6.5	610	

^{1.} The content of this table is provided for information purposes only.

3.7.2 Available touch sensing channels

The tables below provide an overview of the available touch sensing channels for the STM32L0 Series microcontrollers.

Note:

The following tables are not restrictive in term of part numbers supported by the STMTouch touch sensing library. The STMTouch touch sensing library can be used on any new device that may become available as part of ST microcontrollers portfolio. Please contact your ST representative for support.

Note:

For n available pins in an I/O group, one pin is used as sampling capacitor and n-1 pins are used as channels.

The I/O group cannot be used if the number of available pins in less or equal to one.

577

UM1913 Rev 7 105/156

Table 52. Capacitive sensing GPIOs available on STM32L083xx devices

Group	Capacitive sensing signal name	Pin name
1	TSC_G1_IO1	PA0
	TSC_G1_IO2	PA1
	TSC_G1_IO3	PA2
	TSC_G1_IO4	PA3
	TSC_G2_IO1	PA4
2	TSC_G2_IO2	PA5
2	TSC_G2_IO3	PA6
	TSC_G2_IO4	PA7
	TSC_G3_IO1	PC5
3	TSC_G3_IO2	PB0
	TSC_G3_IO3	PB1
	TSC_G3_IO4	PB2
4	TSC_G4_IO1	PA9
	TSC_G4_IO2	PA10
	TSC_G4_IO3	PA11
	TSC_G4_IO4	PA12

Group	Capacitive sensing signal name	Pin name
	TSC_G5_IO1	PB3
5	TSC_G5_IO2	PB4
5	TSC_G5_IO3	PB6
	TSC_G5_IO4	PB7
	TSC_G6_IO1	PB11
6	TSC_G6_IO2	PB12
ь	TSC_G6_IO3	PB13
	TSC_G6_IO4	PB14
	TSC_G7_IO1	PC0
7	TSC_G7_IO2	PC1
,	TSC_G7_IO3	PC2
	TSC_G7_IO4	PC3
8	TSC_G8_IO1	PC6
	TSC_G8_IO2	PC7
	TSC_G8_IO3	PC8
	TSC_G8_IO4	PC9

Table 53. Capacitive sensing GPIOs available on STM32L082xx devices

Group	Capacitive sensing signal name	Pin name
	TSC_G1_IO1	PA0
1	TSC_G1_IO2	PA1
ı	TSC_G1_IO3	PA2
	TSC_G1_IO4	PA3
	TSC_G2_IO1	PA4
2	TSC_G2_IO2	PA5
2	TSC_G2_IO3	PA6
	TSC_G2_IO4	PA7
	-	-
3	TSC_G3_IO2	PB0
3	TSC_G3_IO3	PB1
	TSC_G3_IO4	PB2
	TSC_G4_IO1	PA9
4	TSC_G4_IO2	PA10
4	TSC_G4_IO3	PA11
	TSC_G4_IO4	PA12

Group	Capacitive sensing signal name	Pin name	
	TSC_G5_IO1	PB3	
5	TSC_G5_IO2	PB4	
5	TSC_G5_IO3	PB6	
	TSC_G5_IO4	PB7	
6	TSC_G6_IO1	PB11	
	TSC_G6_IO2	PB12	
	TSC_G6_IO3	PB13	
	TSC_G6_IO4	PB7	
7	TSC_G7_IO1	PC0	
	TSC_G7_IO2	PC1	
	TSC_G7_IO3	PC2	
	-	-	



UM1913 Rev 7 107/156

Table 54. Available touch sensing channels for STM32L063x8

Analog I/O group	Capacitive	Din nama	STM32	L063R8	STM32	L063C8
Analog I/O group	sensing signal name	Pin name	LQFP64		LQFP48	
	TSC_G1_IO1	PA0	х		х	3
G1	TSC_G1_IO2	PA1	х	3	х	
G1	TSC_G1_IO3	PA2	х		х	
	TSC_G1_IO4	PA3	х		х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		х	3
G2	TSC_G2_IO2	PA5	х	3	х	
G2	TSC_G2_IO3	PA6	х	3	х	
	TSC_G2_IO4	PA7	х		х	
	TSC_G3_IO1	PC5	х		-	2
G3	TSC_G3_IO2	PB0	х	9	х	
Go	TSC_G3_IO3	PB1	х	3	х	
	TSC_G3_IO4	PB2	х		х	
	TSC_G4_IO1	PA9	х		х	3
G4	TSC_G4_IO2	PA10	х	3	х	
G4	TSC_G4_IO3	PA11	х		3	
	TSC_G4_IO4	PA12	х		х]
	TSC_G5_IO1	PB3	х	х		
05	TSC_G5_IO2	PB4	х		х	
G5	TSC_G5_IO3	PB6	х	-	х	3
	TSC_G5_IO4	PB7	х		х	
	TSC_G6_IO1	PB11	х		х	3
00	TSC_G6_IO2	PB12	х		х	
G6	TSC_G6_IO3	PB13	х	3	х	
	TSC_G6_IO4	PB14	х		х	
	TSC_G7_IO1	PC0	х		-	0
G7	TSC_G7_IO2	PC1	х	2	-	
G/	TSC_G7_IO3	PC2	х	3	-	
	TSC_G7_IO4	PC3	х		-	

Table 54. Available touch sensing channels for STM32L063x8 (continued)

Analog I/O group	Capacitive	Pin name	STM32	L063R8	STM32	L063C8
Analog I/O group	sensing signal name	Pili liaille	LQF	P64	LQF	P48
	TSC_G8_IO1	PC6	х		-	
G8	TSC_G8_IO2	PC7	х	3	-	0
96	TSC_G8_IO3	PC8	х		-	U
	TSC_G8_IO4	PC9	х		-	
Number sensing channels (er of capacitive sampling I/Os not c	ounted)	2	24	1	7

This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 55. Available touch sensing channels for STM32L062K8

Analog I/O group	Capacitive sensing	Pin name	ST	M32L062K8
Analog I/O group	signal name	Pin name	U	FQFPN32
	TSC_G1_IO1	PA0	Х	
G1	TSC_G1_IO2	PA1	х	3
01	TSC_G1_IO3	PA2	х	3
	TSC_G1_IO4	PA3	х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х	
G2	TSC_G2_IO2	PA5	х	3
G2	TSC_G2_IO3	PA6	х	3
	TSC_G2_IO4	PA7	х	
	TSC_G3_IO1	PC5	-	
G3	TSC_G3_IO2	PB0	х	2
G3	TSC_G3_IO3	PB1	х	2
	TSC_G3_IO4	PB2	х	
	TSC_G4_IO1	PA9	х	
G4	TSC_G4_IO2	PA10	х	3
G4	TSC_G4_IO3	PA11	х	3
	TSC_G4_IO4	PA12	х	
	TSC_G5_IO1	PB3	х	
CE	TSC_G5_IO2	PB4	х	2
G5	TSC_G5_IO3	PB6	х	3
	TSC_G5_IO4	PB7	х	



Table 55. Available touch sensing channels for STM32L062K8 (continued)

Analog I/O group	Capacitive sensing	Pin name	ST	M32L062K8
Analog I/O group	signal name	Pili liaille	U	JFQFPN32
	TSC_G6_IO1	PB11	-	
G6	TSC_G6_IO2	PB12	-	0
Go	TSC_G6_IO3	PB13	-	
	TSC_G6_IO4	PB14	-	
	TSC_G7_IO1	PC0	-	
G7	TSC_G7_IO2	PC1	-	0
G/	TSC_G7_IO3	PC2	-	
	TSC_G7_IO4	PC3	-	
	TSC_G8_IO1	PC6	-	
G8	TSC_G8_IO2	PC7	-	0
Go	TSC_G8_IO3	PC8	-	
	TSC_G8_IO4	PC9	-	
	er of capacitive (sampling I/Os not count	ted)		14

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

Table 56. Available touch sensing channels for STM32L053x6/x8

Analog I/O grave	Capacitive	Pin	STM32	L053Rx	STM32	L053Rx	STM32	L053Cx
Analog I/O group	sensing signal name	name	LQF	P64	TFB	3A64	LQF	P48
	TSC_G1_IO1	PA0	х		Х		х	
G1	TSC_G1_IO2	PA1	х	3	Х	3	х	3
Gi	TSC_G1_IO3	PA2	х	3	Х	3	х	3
	TSC_G1_IO4	PA3	Х		Х		Х	
	TSC_G2_IO1	PA4 ⁽¹⁾	х		Х		х	
G2	TSC_G2_IO2	PA5	Х	3	Х	3	Х	3
G2	TSC_G2_IO3	PA6	х	3	Х	3	Х	3
	TSC_G2_IO4	PA7	Х		Х		Х	
	TSC_G3_IO1	PC5	х		Х		-	
C3	TSC_G3_IO2	PB0	х	3	Х	3	х	2
G3	TSC_G3_IO3	PB1	х	3	Х	3	х	2
	TSC_G3_IO4	PB2	х		Х		Х	

110/156 UM1913 Rev 7



Table 56. Available touch sensing channels for STM32L053x6/x8 (continued)

Amelog I/O group	Capacitive	Pin	STM32	L053Rx	STM32	L053Rx	STM32	L053Cx
Analog I/O group	sensing signal name	name	LQF	P64	TFB	3A64	LQF	P48
	TSC_G4_IO1	PA9	Х		Х		х	
G4	TSC_G4_IO2	PA10	х	3	Х	3	х	3
G4	TSC_G4_IO3	PA11	Х	3	Х	3	Х	3
	TSC_G4_IO4	PA12	Х		Х		Х	
	TSC_G5_IO1	PB3	Х		х		х	
G5	TSC_G5_IO2		Х	3	Х	3	х	3
G5	TSC_G5_IO3	PB6	Х	3	Х	3	Х	3
	TSC_G5_IO4	PB7	х		Х		х	
	TSC_G6_IO1	PB11	Х		Х		х	
G6	TSC_G6_IO2	PB12	х	3	Х	3	х	3
90	TSC_G6_IO3	PB13	Х	3	Х	3	х	3
	TSC_G6_IO4	PB14	х		Х		Х	
	TSC_G7_IO1	PC0	х		х		-	
G7	TSC_G7_IO2	PC1	Х	3	Х	2	-	0
G/	TSC_G7_IO3	PC2	Х	3	Х	2	-	U
	TSC_G7_IO4	PC3	х		-		-	
	TSC_G8_IO1	PC6	Х		х		-	
TSC_G8_IO2		PC7	Х	3	Х	3	-	0
Go	TSC_G8_IO3 PC8		Х	٥	Х	٥	-	U
	TSC_G8_IO4 PC9				х		-	
Numbe sensing channels (s	2	4	2	3	1	7		

This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.



UM1913 Rev 7 111/156

Devices with TSC peripheral

Table 57. Available touch sensing channels for STM32L052x6/x8

Analog I/O	Capacitive	Pin	STM32	L052Rx	STM32	L052Rx	STM32	L052Cx	STM32	L052Tx		STM32	2L052Kx	
group	sensing signal name	name	LQF	P64	TFBGA64		LQF	P48	WLC	SP36	LQFI	P32	UFQF	PN32
	TSC_G1_IO1	PA0	Х		Х		Х		Х		Х		Х	
G1	TSC_G1_IO2	PA1	Х	3	Х	3	х	3	Х	3	Х	3	Х	3
Gi	TSC_G1_IO3	PA2	Х	3	Х	3	Х	3	Х	٦	Х	3	Х	3
	TSC_G1_IO4	PA3	Х		Х		х		Х		Х		Х	
	TSC_G2_IO1	PA4 ⁽¹⁾	Х		Х		х		Х		Х		Х	
G2	TSC_G2_IO2	PA5	Х	3	Х	3	х	3	Х	3	Х	3	Х	3
G2	TSC_G2_IO3	PA6	Х	3	Х] 3	х	3	Х	٦	Х	٦	Х	3
	TSC_G2_IO4	PA7	Х		Х		Х		Х		Х		Х	Ī
	TSC_G3_IO1	PC5	Х		Х		-		-		-		-	
G3	TSC_G3_IO2	PB0	Х	3	Х	3	х	2	Х	2	Х	1	Х	2
GS	TSC_G3_IO3	PB1	Х	3	Х	3	Х	2	Х	2	Х		Х	
	TSC_G3_IO4	PB2	Х		Х		х		Х		-		Х	1
	TSC_G4_IO1	PA9	Х		Х		х		Х		Х		Х	
G4	TSC_G4_IO2	PA10	Х	3	Х	3	Х	3	Х	3	Х	3	Х	
G4	TSC_G4_IO3	PA11	Х	3	Х	3	х	3	Х	3	Х	3	Х	3
	TSC_G4_IO4	PA12	Х		Х		х		Х		Х		Х	1
	TSC_G5_IO1	PB3	Х		Х		Х		х		Х		Х	
G5	TSC_G5_IO2	PB4	Х	3	Х	3	Х	3	х	3	Х	3	Х	,
Go	TSC_G5_IO3	PB6	Х] 3	Х	3	Х)	Х] 3	Х	3	Х	3
	TSC_G5_IO4	PB7	Х		х		Х		Х		Х		Х	





Table 57. Available touch sensing channels for STM32L052x6/x8 (continued)

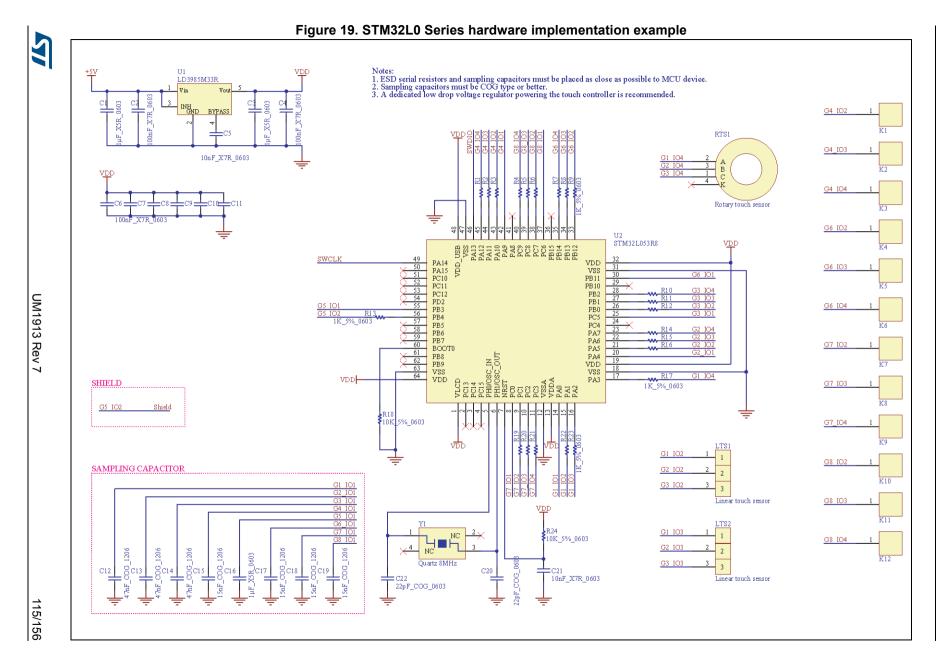
Analog I/O	Capacitive	Pin	STM32	L052Rx	STM32	L052Rx	STM32	L052Cx	STM32	L052Tx		STM32	2L052Kx	
group	sensing signal name	name	LQF	P64	TFB	GA64	LQF	P48	WLC	SP36	LQFI	P32	UFQF	PN32
	TSC_G6_IO1	PB11	Х		Х		х		Х		-		-	
G6	TSC_G6_IO2	PB12	Х	3	х	3	Х	3	-	0	-	0	-	0
Go	TSC_G6_IO3	PB13	Х	3	х	٦	Х	3	-	U	-		-	U
	TSC_G6_IO4	PB14	Х		Х		Х		-		-		-	•
	TSC_G7_IO1	PC0	Х		х		-		-		-		-	
G7	TSC_G7_IO2	PC1	Х	_	х	2	-	_	-		-	0	-	0
G/	TSC_G7_IO3	PC2	Х	3	х	2	-	0	-	U	-	U	-	U
	TSC_G7_IO4	PC3	Х		-		-		-		-		-	•
	TSC_G8_IO1	PC6	Х		х		-		-		-		-	
00	TSC_G8_IO2	PC7	Х	3	х	3	-		-	_	-		-	0
G8	TSC_G8_IO3	PC8	Х	3	х	٥	-	0	-	0	-	0	-	0
	TSC_G8_IO4	PC9	Х		Х		-		-		-		-	
	nber of capacitive annels (sampling I/O: counted)	s not	2	4	2	3	1	7	1	4	13	3	1	4

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

3.7.3 Hardware implementation example

Figure 19 shows an example of hardware implementation on STM32L0 Series microcontrollers.





3.8.1 Memory footprint

Conditions

- IAR ANSI C/C++ compiler/linker V7.40.3.8902 for Arm®
- Compiler optimization: high size
- Counted files: tsl*.o
- STM32 TouchSensing library options: ECS=ON, DTO=ON, DXS=OFF, PROX=OFF
- Each sensor has its own parameters placed in RAM

The following table summarizes the memory footprint with different configurations:

Table 58. STM32L4 Series memory footprint⁽¹⁾

Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)
1	1	1 TKey	2.8	100
2	1	2 TKeys	2.8	120
2	2	2 TKeys	2.8	120
24	3	24 TKeys	3.8	620
3	1	1 Linear-3ch	3.8	130
15	3	12 TKeys + 1 Linear-3ch	5.7	420
24	3	18 TKeys + 2 Linear-3ch	6.0	610

^{1.} The content of this table is provided for information purposes only.

3.8.2 Available touch sensing channels

The tables below provide an overview of the available touch sensing channels for the STM32L4 Series microcontrollers.

Note:

The following tables are not restrictive in term of part numbers supported by the STMTouch touch sensing library. The STMTouch touch sensing library can be used on any new device that may become available as part of ST microcontrollers portfolio. Please contact your ST representative for support.

Note:

For n available pins in an I/O group, one pin is used as sampling capacitor and n-1 pins are used as channels.

The I/O group cannot be used if the number of available pins in less or equal to one.

116/156 UM1913 Rev 7





Table 59. Available touch sensing channels for STM32L4A6xG

Analog I/O	Capacitive	Din nome	STM32L	4A6AG	STM32I	L4A6ZG	STM32I	_4A6QG		STM32L	.4A6V	G	STM32I	L4A6RG
group	sensing signal name	Pin name	UFBG	A169	S9 LQFP144		UFBO	SA132	LQF	P100	WLCSP100		LQFP64	
	TSC_G1_IO1	PB12	х		Х		Х		Х		Х		Х	
G1	TSC_G1_IO2	PB13	х	3	Х	3	Х	3	Х	3	Х	3	х	3
GI	TSC_G1_IO3	PB14	х	3	Х	3	Х	3	Х	3	Х	3	х	3
	TSC_G1_IO4	PB15	х		Х		Х		Х		Х		х	
	TSC_G2_IO1	PB4	х		Х		Х		Х		х		х	
G2	TSC_G2_IO2	PB5	х	3	Х	3	Х	3	Х	3	Х	3	х	3
G2	TSC_G2_IO3	PB6	х	3	Х	3	Х	3	Х	3	Х	3	х	3
	TSC_G2_IO4	PB7	х		Х		Х		Х		Х		х	
	TSC_G3_IO1	PA15	х		Х		Х		Х		х		х	
G3	TSC_G3_IO2	PC10	х	3	Х	3	Х	3	Х	3	Х	3	х	3
GS	TSC_G3_IO3	PC11	х	3	Х	3	Х	3	Х	3	Х	3	х	3
	TSC_G3_IO4	PC12	х		Х		Х		Х		Х		х	
	TSC_G4_IO1	PC6	х		Х		Х		Х		Х		х	
G4	TSC_G4_IO2	PC7	х	3	Х	3	Х	3	Х	3	Х	3	х	3
G 4	TSC_G4_IO3	PC8	х	3	Х	٦	Х	3	Х	3	Х	3	х	3
	TSC_G4_IO4	PC9	х		Х		Х		Х		Х		х	
	TSC_G5_IO1	PE10	х		Х		Х		х		х		-	
G5	TSC_G5_IO2	PE11	х	,	Х	,	Х	2	Х	,	Х	2	-	
Go	TSC_G5_IO3	PE12	х	3	Х	3	Х	3	Х	3	Х	3	-	0
	TSC_G5_IO4	PE13	х		Х		Х		Х		Х		-	

Table 59. Available touch sensing channels for STM32L4A6xG (continued)

Analog I/O	Capacitive	D:	STM32L	4A6AG	STM32I	L4A6ZG	STM32L	4A6QG	,	STM32L	.4A6V	G	STM32L	_4A6RG
group	sensing signal name	Pin name	UFBG	A169	LQF	P144	UFBG	6A132	LQF	P100	WL	.CSP100	LQF	P64
	TSC_G6_IO1	PD10	х		х		Х		Х		-		-	
G6	TSC_G6_IO2	PD11	х	3	х	3	х	3	Х	3	-	0	-	0
Go	TSC_G6_IO3	PD12	х	3	х	3	х	3	Х	٦	-	U	-	U
	TSC_G6_IO4	PD13	х		Х		Х		Х		-		-	
	TSC_G7_IO1	PE2	х		Х		Х		Х		Х		-	
G7 TS	TSC_G7_IO2	PE3	х	3	х		х	3	Х	3	Х	3	-	0
G/	TSC_G7_IO3	PE4	х	3	х	3	х	3	Х	٦	Х	3	-	U
	TSC_G7_IO4	PE5	х		х		х		Х		х		-	
	TSC_G8_IO1	PF14	х		х		х		-		-		-	
G8	TSC_G8_IO2	PF15	х	3	х	3	х	3	-	0	-	0	-	0
Go	TSC_G8_IO3	PG0	х	3	х	3	х	3	-		-	U	-	U
	TSC_G8_IO4	PG1	х		Х		Х		-		-		-	
	umber of capacitive channels (sampling counted)		24	4	2	4	2	4	2	:1		18	1	2

Table 60. Available touch sensing channels for STM32L496xx

Analog I/O	Capacitive	Din nome	STM32L	_496Ax	STM32	L496Zx	STM32	L496Qx		STM32L	_496V	x	STM32	L496Rx
group	sensing signal name	Pin name	UFBG	A169			UFBG	SA132	LQF	P100	WL	.CSP100	LQF	-P64
	TSC_G1_IO1	PB12	х		Х		Х		Х		Х		Х	
G1	TSC_G1_IO2	PB13	х	3	Х	3	х	3	Х	3	Х	3	Х	
GI	TSC_G1_IO3	PB14	х	3	Х	3	Х	3	Х	3	Х	3	Х	3
	TSC_G1_IO4	PB15	х		Х		х		Х		Х		Х	
	TSC_G2_IO1	PB4	х		Х		Х		Х		х		х	
G2	TSC_G2_IO2	PB5	х	3	Х	3	Х	3	Х	3	Х	3	Х	3
GZ	TSC_G2_IO3	PB6	х]	Х		х	3	Х]	Х	3	Х	
	TSC_G2_IO4	PB7	х		Х		Х		Х		Х		Х	
	TSC_G3_IO1	PA15	х		Х		х		Х		Х		х	
G3	TSC_G3_IO2	PC10	х	3	Х	3	Х	3	Х	3	Х	3	Х	3
G 3	TSC_G3_IO3	PC11	х	3	Х	3	х	3	Х	3	Х	3	Х	
	TSC_G3_IO4	PC12	х		Х		х		Х		Х		Х	
	TSC_G4_IO1	PC6	х		Х		х		Х		Х		х	
G4	TSC_G4_IO2	PC7	х	3	Х	3	х	3	Х	3	Х	3	Х	3
G 4	TSC_G4_IO3	PC8	х	3	Х	3	х	3	Х	٦	Х	3	Х	3
	TSC_G4_IO4	PC9	х		Х		х		Х		Х		Х	
	TSC_G5_IO1	PE10	х		Х		х		Х		Х		-	
G5	TSC_G5_IO2	PE11	х	3	х	3	х	3	Х	3	Х	3	-	0
Go	TSC_G5_IO3	PE12	х	3	Х	3	Х	٥	Х	3	х	S	-	1 0
	TSC_G5_IO4	PE13	х		Х		Х		Х		Х		-	

Table 60. Available touch sensing channels for STM32L496xx (continued)

Analog I/O	Capacitive	D:	STM32I	_496Ax	STM32	L496Zx	STM32	L496Qx		STM32L	_496V	х	STM32I	L496Rx
group	sensing signal name	Pin name	UFBG	A169 LQFP144		UFBG	SA132	LQF	P100	WL	.CSP100	LQF	P64	
	TSC_G6_IO1	PD10	х		Х		х		Х		-		-	
G6	TSC_G6_IO2	PD11	х	3	х	3	х	3	Х	3	-	0	-	0
Go	TSC_G6_IO3	PD12	х	3	х	3	х	3	Х	٦	-	U	-	U
	TSC_G6_IO4	PD13	х		Х		х		Х		-		-	
	TSC_G7_IO1	PE2	х		х		х		Х		Х		-	
G7	TSC_G7_IO2	PE3	х	3	х	3	х	3	Х	3	Х	3	-	0
G/	TSC_G7_IO3	PE4	х	3	х	3	х	3	Х	٦	Х	3	-	U
	TSC_G7_IO4	PE5	х		х		х		Х		Х		-	
	TSC_G8_IO1	PF14	х		х		х		-		-		-	
G8	TSC_G8_IO2	PF15	х	3	х	,	х	3	-	0	-	0	-	0
Go	TSC_G8_IO3	PG0	х	3	х	3	х	3	-		-	0	-	0
	TSC_G8_IO4	PG1	х		х		х		-		-		-	
	umber of capacitiv channels (sampling counted)		24	4	2	4	2	4	2	:1		18	1.	2



Table 61. Available touch sensing channels for STM32L486xx

A ! !	Capacitive	nable of . A		L486Zx		L486Qx	STM32	L486Vx	STN	132L486Jx	STM32L486Rx			
Analog I/O group	sensing signal name	Pin name	LQF	P144	UFBO	SA132	LQF	P100	W	LCSP72	LQFP64			
	TSC_G1_IO1	PB12	Х		х		Х		х		х			
G1	TSC_G1_IO2	PB13	х	3	х	3	х	3	х	3	х	3		
Gi	TSC_G1_IO3	PB14	х		х		х]	х		х	3		
	TSC_G1_IO4	PB15	х		х		х		х		х			
	TSC_G2_IO1	PB4	х		х		х		х		х			
G2	TSC_G2_IO2	PB5	х	3	х	3	х	3	х	3	х	3		
G2	TSC_G2_IO3	PB6	х	3	х	3	х	3	Х	3	х	3		
	TSC_G2_IO4	PB7	х		х		х		Х		х			
	TSC_G3_IO1	PA15	х		х		х		х		х			
02	TSC_G3_IO2	PC10	х	3	х		х	3	Х	2	х			
G3	TSC_G3_IO3	PC11	х	3	х	3	х	3	Х	3	х	3		
	TSC_G3_IO4	PC12	х		х		х		Х		х			
	TSC_G4_IO1	PC6	х		х		х		х		х			
G4	TSC_G4_IO2	PC7	х	3	х	3	х	3	Х	3	х]		
G4	TSC_G4_IO3	PC8	х	3	х	3	х	3	Х	3	х	3		
	TSC_G4_IO4	PC9	х		х		х		х		х	1		
	TSC_G5_IO1	PE10	Х		х		Х		-		-			
G5	TSC_G5_IO2	PE11	Х	3	х	3	Х	,	-	0	-	1		
Go	TSC_G5_IO3	PE12	х		3	3	3	х	٦	х	3	-	0	-
	TSC_G5_IO4	PE13	Х		х		Х		-		-	1		

Table 61. Available touch sensing channels for STM32L486xx (continued)

Amalam I/O mmaum	Capacitive	Din nama	STM32	L486Zx	STM32	L486Qx	STM32	L486Vx	STN	//32L486Jx	STM32	L486Rx
Analog I/O group	sensing signal name	Pin name	LQF	LQFP144		UFBGA132		LQFP100		/LCSP72	LQFP64	
	TSC_G6_IO1	PD10	х		х		х		-		-	
G6	TSC_G6_IO2	PD11	х	3	х	3	х	3	-	0	-	0
Go	TSC_G6_IO3	PD12	х	3	х	3	х	3	-		-	
	TSC_G6_IO4	PD13	х		х		х		-		-	
	TSC_G7_IO1	PE2	х		х		х		-		-	
G7	TSC_G7_IO2	PE3	х	3	х	3	х	3	-	0	-	0
G/	TSC_G7_IO3	PE4	х		х		х	3	-		-	
	TSC_G7_IO4	PE5	х		х		х		-		-	
	TSC_G8_IO1	PF14	х		х		-		-		-	
G8	TSC_G8_IO2	PF15	х	3	х	3	-	0	-	0	-	1 .
Go	TSC_G8_IO3	PG0	х	3	х] 3	-		-		-	- 0
	TSC_G8_IO4	PG1	х		х	1	-		-		-	
	Number of capacitive sensing channels (sampling I/Os not counted)		24		24		21		12		12	

Table 62. Available touch sensing channels for STM32L476xx

			<u> </u>											
Analog I/O group	Capacitive sensing	Pin name	STM32	L476Zx	STM32	L476Qx	STM32	L476Vx	STM	32L476Mx	STM	32L476Jx	STM32	L476Rx
Allalog #O group	signal name	FIII IIaille	LQFP144		UFBGA132		LQFP100		WLCSP81		WLCSP72		LQFP64	
	TSC_G1_IO1	PB12	Х		Х		Х		х		х		Х	
G1	TSC_G1_IO2	PB13	Х	2	Х	2	Х	3	х	3	х	2	Х	3
Gi	TSC_G1_IO3	PB14	Х	3	Х	3	Х	3	х	3	х	3	Х	3
	TSC_G1_IO4	PB15	Х		х		х		Х		Х		х	





Table 62. Available touch sensing channels for STM32L476xx (continued)

	Capacitive		STM32	L476Zx	STM32	L476Qx	STM32	L476Vx	STM	32L476Mx	STM	132L476Jx	STM32L476Rx				
Analog I/O group	sensing signal name	Pin name	LQF	P144	UFBO	UFBGA132		P100	WLCSP81		WLCSP72		LQFP64				
	TSC_G2_IO1	PB4	Х		Х		Х		Х		Х		Х				
G2	TSC_G2_IO2	PB5	х	3	Х	3	Х	3	х	3	Х	3	Х	3			
G2	TSC_G2_IO3	PB6	Х	3	Х	3	Х]	х	3	х	3	Х				
	TSC_G2_IO4	PB7	Х		Х		Х		х		х		Х				
	TSC_G3_IO1	PA15	х		Х		Х		х		Х		Х				
G3	TSC_G3_IO2	PC10	Х	3	Х	3	Х	3	х	3 x	х	3	Х	3			
G3	TSC_G3_IO3	PC11	х		х	3	Х		х	3	Х	3	Х				
	TSC_G3_IO4	PC12	х		Х		Х		х		Х		Х				
	TSC_G4_IO1	PC6	Х		Х		Х		х		х		Х				
G4	TSC_G4_IO2	PC7	х	3	Х	х х	Х	3	х	3	х	3	Х	3			
G4	TSC_G4_IO3	PC8	х	3	Х		х		х		Х		Х				
	TSC_G4_IO4	PC9	Х		Х		Х		х		х		Х				
	TSC_G5_IO1	PE10	Х		Х		Х		-		-		-				
G5	TSC_G5_IO2	PE11	х	3	Х	3	Х	3	-	0	-	0	-	0			
GS	TSC_G5_IO3	PE12	Х	3	Х	3	Х]	-	U	-		-	- 0			
	TSC_G5_IO4	PE13	Х		Х		Х		-		-		-				
	TSC_G6_IO1	PD10	Х		Х		Х		-		-		-				
G6	TSC_G6_IO2	PD11	Х	3 –	Х	,	Х	3 -	-	0	-	0	-	0			
Gu	TSC_G6_IO3	PD12	Х		3 x	Х	3		3	3		- 0				-	
	TSC_G6_IO4	PD13	Х		Х		х		-		-		-				

Devices with TSC peripheral

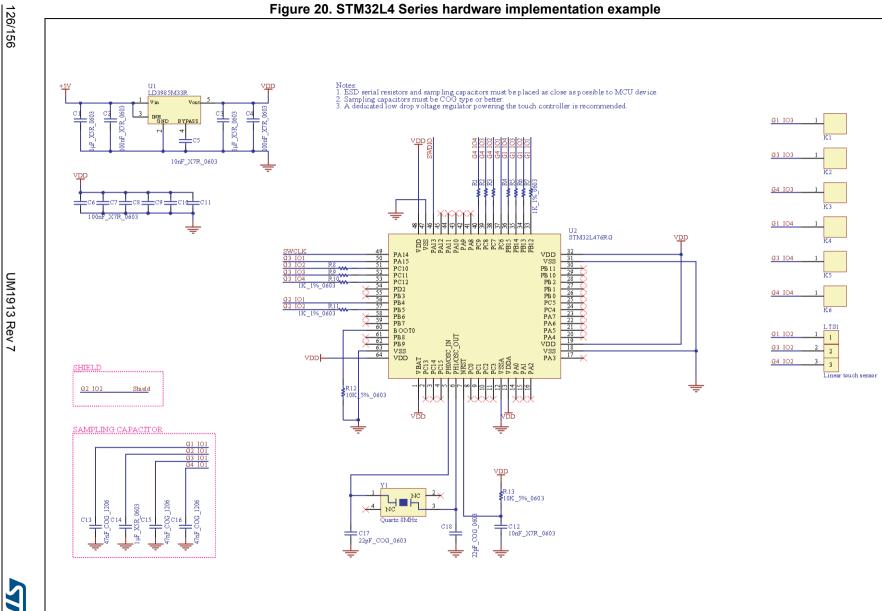
Table 62. Available touch sensing channels for STM32L476xx (continued)

Analog I/O group	Capacitive	Din name	STM32	L476Zx	STM32	L476Qx	STM32	L476Vx	STM	32L476Mx	STN	132L476Jx	STM32	L476Rx
Analog I/O group	sensing signal name	Pin name	LQF	P144	UFBGA132		LQFP100		w	LCSP81	W	LCSP72	LQFP64	
	TSC_G7_IO1	PE2	Х		Х		Х		-		-		-	
G7	TSC_G7_IO2	PE3	Х	x 3		3	Х	3	-	0	-	0	-	0
G/	TSC_G7_IO3	PE4	Х	3	х	3	Х	3	-	U	-	U	-	U
	TSC_G7_IO4	PE5	х		х		х		-		-		-	
	TSC_G8_IO1	PF14	Х		х		-		-		-		-	
G8	TSC_G8_IO2	PF15	Х	3	х	3	-	0	-	0	-	0	-	0
90	TSC_G8_IO3	PG0	Х	3	Х	3	-		-	U	-	U	-	U
	TSC_G8_IO4	PG1	Х		х		-		-		-		-	
	Number of capacitive sensing channels (sampling I/Os not co		24		24		21		12		12		12	

3.8.3 Hardware implementation example

Figure 20 shows an example of hardware implementation on STM32L4 Series microcontrollers.







These microcontrollers support two different acquisition modes: hardware and software.

4.1 Acquisition

The STM32L1 Series microcontrollers **hardware acquisition mode** (using two timers) is done in the files:

- tsl_acq_stm32l1xx_hw.c
- tsl_acq_stm32l1xx_hw.h

Warning: This acquisition mode is only available for the STM32L1 Series microcontrollers featuring a minimum of 384 K of Flash.

The STM32L1 Series microcontrollers software acquisition mode is done in the files:

- tsl_acq_stm32l1xx_sw.c
- tsl_acq_stm32l1xx_sw.h

This acquisition is available for all STM32L1 Series microcontrollers.

Note:

The hardware acquisition mode is selected per default for the STM32L1 Series microcontrollers featuring a minimum of 384 K of Flash. If you want to use the software acquisition mode you must add the following constant in the toolchain compiler preprocessor:

TSLPRM_STM32L1XX_SW_ACQ

Functions used by the application layer and that are device dependent:

- TSL_acq_BankConfig()
- TSL_acq_BankStartAcq()
- TSL acg BankWaitEOC()
- TSL_acq_GetMeas()

The other functions in this file are for internal use and the user doesn't need to call them directly.

4.2 Timings

The timing management is done in the files:

- tsl time.c
- tsl_time.h

The **Systick** is used to generate a timebase for the ECS and DTO modules. It must be initialized in the user code (already done by the HAL init function).



UM1913 Rev 7

127/156

4.3 Parameters

The parameters specific to the STM32L1 Series microcontrollers are described in the file:

- tsl_conf_stm32l1xx_template.h (to be copied in project and rename in **tsl_conf.h**) and are checked in the file:
- tsl_check_config_stm32l1xx.h

4.4 Memory footprint

Conditions

- IAR ANSI C/C++ compiler/linker V7.40.3.8902 for Arm[®]
- Compiler optimization: high size
- Counted files: tsl*.o
- STM32 TouchSensing library options: ECS=ON, DTO=ON, DXS=OFF, PROX=OFF
- Each sensor has its own parameters placed in RAM

The following tables summarize the memory footprint with different configurations

Table 63. STM32L1 Series with hardware acquisition mode memory footprint⁽¹⁾

Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)
1	1	1 TKey	5.3	340
2	1	2 TKeys	5.3	360
2	2	2 TKeys	5.5	360
24	3	24 TKeys	6.2	870
3	1	1 Linear-3ch	6.3	370
15	3	12 TKeys + 1 Linear-3ch	8.3	660
24	3	18 TKeys + 2 Linear-3ch	8.5	850

^{1.} The content of this table is provided for information purposes only.

Table 64. STM32L1 Series with software acquisition mode memory footprint⁽¹⁾

Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)
1	1	1 TKey	5.5	410
2	1	2 TKeys	5.5	430
2	2	2 TKeys	5.5	430
24	3	24 TKeys	6.2	930
3	1	1 Linear-3ch	6.5	440

128/156 UM1913 Rev 7



		continuit acquio.	mon mous mone	. y . o o tp
Channels	Banks	Sensors	ROM (~ Kbyte)	RAM (~ byte)
15	3	12 TKeys + 1 Linear-3ch	8.2	730
24	3	18 TKeys + 2 Linear-3ch	8.5	920

Table 64. STM32L1 Series with software acquisition mode memory footprint⁽¹⁾

4.5 MCU resources

The tables below show the peripherals that are used by the STMTouch touch sensing library on STM32L1 Series microcontrollers. Care must be taken when using them to avoid any unwanted behavior.

Table 65. MCU resources used on STM32L1 Series with hardware acquisition

Peripheral	Function
GPIOs	Acquisition
Systick	Time base for ECS and DTO
2 Timers (TIM9, TIM11)	Acquisition
Routing interface	Acquisition

Table 66. MCU resources used on STM32L1 Series with software acquisition

Peripheral	Function
GPIOs	Acquisition
Systick	Time base for ECS and DTO
Routing interface	Acquisition

4.6 Available touch sensing channels

The tables below provide an overview of the available touch sensing channels for the STM32L1 Series microcontrollers.

Note:

The following tables are not restrictive in term of part numbers supported by the STMTouch touch sensing library. The STMTouch touch sensing library can be used on any new device that may become available as part of ST microcontrollers portfolio. Please contact your ST representative for support.

Note:

For n available pins in an I/O group, one pin is used as sampling capacitor and n-1 pins are used as channels. The I/O group cannot be used if the number of available pins in less or equal to one.



^{1.} The content of this table is provided for information purposes only.

Table 67. Available touch sensing channels for STM32L1 Series 512K

S	ubfamily							STM32	2L1 Series	512K					
P	ackages			LQFP64	ı		LQFP100	/ WLCSP1	04		UFBGA1	32		LQFP14	4
Pa	rt numbers	S	,	STM32L15 STM32L15 STM32L16	2RE		STM3	2L151VE 2L152VE 2L162VE			STM32L15 STM32L15 STM32L16	2QE	;	STM32L15 STM32L15 STM32L16	2ZE
Analog I/O group	Gx_IOy	GPIO	LQFP pin	Number of available pins	Usage	LQFP Pin	WLCSP ball	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G1_IO1	PA0	14		3	23	K9		3	L2		3	34		3
	G1_IO2	PA1	15		channels with	24	L9		channels with	M2		channels with	35	_	channels with
Group 1	G1_IO3	PA2	16	4	1 sampling	25	J8	4	1 sampling	K3	4	1 sampling	36	4	1 sampling
	G1_IO4	PA3 ⁽¹⁾	17		sampling capacitor	26	H7		sampling capacitor	L3		capacitor	37		capacitor
	G2_IO1	PA6	22		Сарасног	31	H6			L4			42		
	G2_IO2	PA7	23		1	32	K7	1	1	J5	1	3	43		3
	G2_IO3	PF15	-		channel with	-	-		channel with	J9	4 ⁽²⁾	channels with	55	4 ⁽²⁾	channels with
Group 2	G2_IO4	PG0 (3)	-	2	1 sampling	-	-	2	1 sampling	Н9	4(2)	1 sampling	56		1 sampling
	G2_IO5	PG1 ⁽³	-		capacitor	-	-		capacitor	G9		capacitor	57		capacitor
	G3_IO1	PB0 ⁽¹⁾	26		2	35	J6		2	M5		4	46		4
	G3_IO2	PB1	27		channels	36	K6	=	channels	M6		channels	47		channels
Group 3	G3_IO3	PB2	28	3	with 1 sampling	37	M6	3	with	L6	5	with 1	48	5	with 1
	G3_IO4	PF11	-			-	-		sampling	K6		sampling	49]	sampling
	G3_IO5	PF12	-		capacitor	-	-		capacitor	J7		capacitor	50		capacitor





Table 67. Available touch sensing channels for STM32L1 Series 512K (continued)

S	ubfamily							STM32	2L1 Series	512K		-			
P	ackages			LQFP64	•		LQFP100	/ WLCSP1	04		UFBGA1	32		LQFP14	4
Pa	rt numbers	s		STM32L15 ² STM32L15 ² STM32L16 ²	2RE		STM3	2L151VE 2L152VE 2L162VE			STM32L15 STM32L15 STM32L16	2QE	;	STM32L15 STM32L15 STM32L16	2ZE
Analog I/O group	Gx_IOy	GPIO	LQFP pin	Number of available pins	Usage	LQFP Pin	WLCSP ball	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G4_IO1	PA8	41		2 .	67	F3		. 2	D11		. 2	100		2 .
0	G4_IO2	PA9	42	_	channels with	68	F1	3	channels with	D10	3	channels with	101		channels with
Group 4	G4_IO3	PA10	43	3	1 sampling capacitor	69	F2		1 sampling capacitor	C12		1 sampling capacitor	102	3	1 sampling capacitor
	G5_IO1	PA13	46		2	72	E3		2	A11		2	105		2
0 5	G5_IO2	PA14	49		channels with	76	D3		channels with	A10		channels with	109		channels with
Group 5	G5_IO3	PA15	50	3	1 sampling capacitor	77	B1	3	1 sampling capacitor	A9	3	1 sampling capacitor	110	3	1 sampling capacitor
	G6_IO1	PB4	56		3	90	A5		3	A7		3	134		3
C***** C	G6_IO2	PB5	57	4	channels with	91	A6	┥ .	channels with	C5] ,	channels with	135		channels with
Group 6	G6_IO3	PB6	58	4	1	92	C5	4	1 sampling	B5	4	1 sampling	136	4	1 sampling
	G6_IO4	PB7	59		sampling -	93	C7	1	capacitor	B4		capacitor	137		capacitor

Table 67. Available touch sensing channels for STM32L1 Series 512K (continued)

S	ubfamily							STM32	L1 Series	512K	<u> </u>	·			
Р	ackages			LQFP64	ļ		LQFP100	/ WLCSP1	04		UFBGA1	32		LQFP14	4
Pai	rt numbers	3		STM32L15 ² STM32L15 ² STM32L16 ²	2RE		STM3	2L151VE 2L152VE 2L162VE			STM32L15 STM32L15 STM32L16	2QE	;	STM32L15 STM32L15 STM32L16	2ZE
Analog I/O group	Gx_IOy	GPIO	LQFP pin	Number of available pins	Usage	LQFP Pin	WLCSP ball	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G7_IO1	PB12	33			51	J4			L12			73		
	G7_IO2	PB13	34			52	J3			K12			74		
	G7_IO3	PB14	35		3	53	L1		3	K11		4	75		4
	G7_IO4	PB15	36		channels with	54	K2		channels with	K10		channels with	76		channels with
Group 7	G7_IO5	PG2 ⁽³	-	4	1 sampling	-	-	4	1 sampling	G10	5 ⁽²⁾	1 sampling	87	5 ⁽²⁾	1 sampling
	G7_IO6	PG3 ⁽³	-		capacitor	-	-		capacitor	F9		capacitor	88		capacitor
	G7_IO7	PG4 ⁽³	-			-	-			F10			89		
	G8_IO1	PC0	8		3	15	F6		3	H1		3	26		3
0	G8_IO2	PC1	9	4	channels with	16	Н9	4	channels with	J2	4	channels with	27	_	channels with
Group 8	G8_IO3	PC2	10	4	1 sampling	17	G9	4	1 sampling	J3	4	1 sampling	28	4	1 sampling
	G8_IO4	PC3	11		capacitor	18	G8		capacitor	K2	_	capacitor	29		capacitor
	G9_IO1	PC4	24		1	33	L7		1	K5		3	44		3
Group 9	G9_IO2	PC5	25	2	channel with	34	M7	2	channel with	L5	4	channels with	45	4	channels with
Group 9	G9_IO3	PF13	-		1 sampling	i	-		1 sampling	K7	+	1 sampling	53	-	1 sampling
	G9_IO4	PF14	-		capacitor	-			capacitor	J8	_	capacitor	54		capacitor





Table 67. Available touch sensing channels for STM32L1 Series 512K (continued)

s	ubfamily							STM32	2L1 Series	512K	· · · · · ·	·			
Р	ackages			LQFP64	ļ		LQFP100	/ WLCSP1	04		UFBGA1	32		LQFP14	4
Par	rt numbers	i		STM32L15 ² STM32L15 ² STM32L16 ²	2RE		STM3	2L151VE 2L152VE 2L162VE			STM32L15 STM32L15 STM32L16	2QE	:	STM32L15 STM32L15 STM32L16	2ZE
Analog I/O group	Gx_IOy	GPIO	LQFP pin	Number of available pins	Usage	LQFP Pin	WLCSP of available pins Usage BGA ball Number of available pins Usage pins Usage pins						Number of available pins	Usage	
	G10_IO1 PC				. 3	63	H1		3	E12		. 3	96		3
Croup 10	G10_IO2	PC7	38	4	channels with	64	G1	4	channels with	E11	4	channels with	97	4	channels with
Group 10	G10_IO3	PC8	39	4	1 sampling	65	G2	4	1 sampling	E10	4	1 sampling	98	4	1 sampling
	G10_IO4	PC9	40		capacitor	66	F4		capacitor	D12		capacitor	99		capacitor
	G11_IO1	PF6	-			-	-			G3		3	18		4
	G11_IO2	PF7	-		Cannot be used	-	-		Cannot be used	G4	-	channels	19		channels
Group 11	G11_IO3	PF8	-	0	for	-	-	0	for	H4	4	with 1	20	5	with 1
	G11_IO4 PF				touch sensing	-	-		touch sensing	J6		sampling	21		sampling
	G11_IO5 PF1				J	-	-			-		capacitor	22		capacitor
	G11_IO5 PF ² Maximum number of channels			channels w				nels with 10 g capacitors			channels was		_	channels v	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

^{2.} Not all the pins are available simultaneously on this group.

^{3.} This GPIO can only be configured as sampling capacitor I/O when using HW acquisition mode and as channel I/O when using SW acquisition mode.

Table 68. Available touch sensing channels for STM32L1 Series 384K

S	Subfamily							STM3	2L1 Series						
F	Packages			LQFP64	/ WLCSP6	64		LQFP10	0		UFBGA1	32		LQFP14	4
Pa	rt numbers	6		STM3	32L151RD 32L152RD 32L162RD		,	STM32L15 ² STM32L15 ² STM32L16 ²	2VD		STM32L15 STM32L15 STM32L16	2QD	;	STM32L15 STM32L15 STM32L16	2ZD
Analog I/O group	Gx_IOy	GPIO	LQFP pin	WLCSP ball	Number of available pins	Usage	LQFP Pin	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G1_IO1	PA0	14	F6		. 3	23		. 3	L2		. 3	34		. 3
0	G1_IO2	PA1	15	E6		channels with	24		channels with	M2		channels with	35	4	channels with
Group 1	G1_IO3	PA2	16	H8	4	1	25	4	1	K3	4	1	36	4	1
	G1_IO4	PA3 ⁽¹⁾	17	G7		sampling capacitor	26		sampling capacitor	L3		sampling capacitor	37		sampling capacitor
	G2_IO1	PA6	22	G5		1	31		1	L4		3	42		3
	G2_IO2	PA7	23	G4		channel	32		channel	J5		channels	43		channels
Group 2	G2_IO3	PF15	-	-	2	with 1	-	2	with 1	J9	4 ⁽²⁾	with 1	55	4 ⁽²⁾	with 1
	G2_IO4	PG0 ⁽³⁾	-	-		sampling	-		sampling	H9		sampling	56		sampling
	G2_IO5	PG1 ⁽³⁾	-	-		capacitor	-		capacitor	G9		capacitor	57		capacitor
	G3_IO1	PB0 ⁽¹⁾	26	H4		2	35		2	M5		4	46		4
G3_IO2	PB1	27	F4		channels	36		channels	M6		channels	47		channels	
Group 3		PB2	28	НЗ	3	with 1	37	3	with 1	L6	5	with 1	48	5	with 1
	G3_IO4	PF11	-	-		sampling	-		sampling	K6		sampling	49		sampling
	G3_IO5	PF12	-	-		capacitor	-		capacitor	J7		capacitor	50		capacitor





Table 68. Available touch sensing channels for STM32L1 Series 384K (continued)

S	Subfamily					•		STM3	2L1 Series	384K	<u> </u>	-			
F	Packages			LQFP64	/ WLCSP6	64		LQFP10	0		UFBGA1	32		LQFP14	4
Pa	rt numbers	6		STM3	32L151RD 32L152RD 32L162RD		;	STM32L15 ² STM32L15 ² STM32L16 ²	2VD		STM32L15 STM32L15 STM32L16	2QD	:	STM32L15 STM32L15 STM32L16	2ZD
Analog I/O group	I/O Gx_IOy GPIC		LQFP pin	WLCSP ball	Number of available pins	Usage	LQFP Pin	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G4_IO1	PA8	41	E4		. 2	67		. 2	D11		. 2	100		2 .
0	G4_IO2	PA9	42	D2	_	channels with	68		channels with	D10		channels with	101		channels with
Group 4	G4_IO3	PA10	43	D3	3	1 sampling capacitor	69	3	1 sampling capacitor	C12	3	1 sampling capacitor	102	3	1 sampling capacitor
	G5_IO1	PA13	46	D4		2	72		2	A11		2	105		2
	G5_IO2	PA14	49	B2	_	channels with	76	_	channels with	A10	_	channels with	109	_	channels with
Group 5	G5_IO3	PA15	50	СЗ	3	1 sampling capacitor	77	3	1 sampling capacitor	A9	3	1 sampling capacitor	110	3	1 sampling capacitor
	G6_IO1	PB4	56	B4		. 3	90		. 3	A7		. 3	134		. 3
0	G6_IO2	PB5	57	A5		channels with	91]	channels with	C5]	channels with	135]	channels with
Group 6	Group 6	PB6	58	B5	4	1	92	4	1	B5	4	1	136	4	1
	G6_IO4	PB7	59	C5		sampling capacitor	93		sampling capacitor	B4		sampling capacitor	137		sampling capacitor

Table 68. Available touch sensing channels for STM32L1 Series 384K (continued)

S	Subfamily							STM3	2L1 Series	384K					
F	Packages			LQFP64	/ WLCSP6	64		LQFP10	0		UFBGA1	32		LQFP14	4
Pa	rt numbers	S		STM3	32L151RD 32L152RD 32L162RD			STM32L15 STM32L15 STM32L16	2VD		STM32L15 STM32L15 STM32L16	2QD		STM32L15 STM32L15 STM32L16	2ZD
Analog I/O group	Gx_IOy	GPIO	LQFP pin	WLCSP ball	Number of available pins	Usage	LQFP Pin	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G7_IO1	PB12	33	G2			51			L12			73		
	G7_IO2	PB13	34	G1		3	52		3	K12		4	74		4
	G7_IO3	PB14	35	F2		channels	53		channels	K11		channels	75		channels
Group 7	G7_IO4	PB15	36	F1	4	with 1	54	4	with 1	K10	5 ⁽²⁾	with 1	76	5 ⁽²⁾	with 1
	G7_IO5	PG2 ⁽³⁾	-	-		sampling	-		sampling	G10	1	sampling	87		sampling
	G7_IO6	PG3 ⁽³⁾	-	-		capacitor	-		capacitor	F9		capacitor	88		capacitor
	G7_IO7	PG4 ⁽³⁾	-	-			-			F10			89		
	G8_IO1	PC0	8	E8		3	15		3	H1		3	26		3
	G8_IO2	PC1	9	F8	_	channels with	16	<u> </u>	channels with	J2	_	channels with	27	<u> </u>	channels with
Group 8	G8_IO3	PC2	10	D6	4	1	17	4	1	J3	4	1	28	4	1
	G8_IO4	PC3 ⁽¹⁾	11	F7		sampling capacitor	18		sampling capacitor	K2		sampling capacitor	29		sampling capacitor
	G9_IO1	PC4	24	H6		1	33		1	K5		3	44		3
	G9_IO2	PC5	25	H5		channel with	34		channel with	L5]	channels with	45] .	channels with
Group 9		PF13	-	-	2	1	-	2	1	K7	4	1	53	4	1
	G9_IO4	PF14	-	-		sampling capacitor	-		sampling capacitor	J8		sampling capacitor	54		sampling capacitor





Table 68. Available touch sensing channels for STM32L1 Series 384K (continued)

S	Subfamily							STM3	2L1 Series	384K	· · · · · ·				
F	Packages			LQFP64	/ WLCSP6	64		LQFP10	0		UFBGA1	32		LQFP14	4
Pa	rt numbers	S		STM3	32L151RD 32L152RD 32L162RD		;	STM32L15 ² STM32L15 ² STM32L16 ²	2VD		STM32L15 STM32L15 STM32L16	2QD		STM32L15 ² STM32L15 ² STM32L16 ²	2ZD
Analog I/O group	Gx_IOy	GPIO	LQFP pin	WLCSP ball	Number of available pins	Usage	LQFP Pin	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G10_IO1	PC6	37	E1		3	63		. 3	E12		. 3	96		. 3
0	G10_IO2	PC7	38	E2		channels with	64		channels with	E11		channels with	97		channels with
Group 10	G10_IO3	PC8	39	E3	4	1	65	4	1	E10	4	1	98	4	1
	G10_IO4	PC9	40	D1		sampling capacitor	66		sampling capacitor	D12		sampling capacitor	99		sampling capacitor
	G11_IO1	PF6	-	-			-			G3		3	18		4
	G11_IO2	PF7	-	-		Cannot be used	-		Cannot be used	G4		channels	19		channels
Group 11	G11_IO3	PF8	-	-	0	for	-	0	for	H4	4	with 1	20	5	with 1
	G11_IO4	PF9	-	-		touch sensing	-		touch sensing	J6		sampling	21		sampling
	G11_IO5	PF10	-	-		3	-			-		capacitor	22		capacitor
	num numbe channels	er of			nels with 10 g capacitor		_	channels w			channels was			channels v	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

^{2.} Not all the pins are available simultaneously on this group.

^{3.} This GPIO can only be configured as sampling capacitor I/O when using HW acquisition mode and as channel I/O when using SW acquisition mode.

Table 69. Available touch sensing channels for STM32L1 Series 256K (table 1/2)

	Subfamily						STM32L1	Series 256K	-	-		
	Packages			LQFP48 c	or UFQFPN48		WLCS	P63		LQF	P64 / WLC	SP64
P	art number	rs		STM3	2L152CC		STM32L1	151UC		S	ГМ32L151F ГМ32L152F ГМ32L162F	RC
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	WLCSP ball	Number of available pins	Usage	LQFP pin	WLCSP ball	Number of available pins	Usage
	G1_IO1	PA0	10			E4			14	F6		
Croup 1	G1_IO2	PA1	11	4	3 channels with	G5	4	3 channels with	15	E6	4	3 channels with
Group 1	G1_IO3	PA2	12	4	1 sampling capacitor	H6	4	1 sampling capacitor	16	H8	4	1 sampling capacitor
	G1_IO4	PA3 ⁽¹⁾	13			J7			17	G7		
	G2_IO1	PA6	16			G4			22	G5		
	G2_IO2	PA7	17		1 channel with	J5		1 channel with	23	G4		1 channel with
Group 2	G2_IO3	PF15	-	2	1 sampling	-	2	1 sampling	-	-	2	1 sampling
	G2_IO4	PG0 ⁽²⁾	-		capacitor	-		capacitor	-	-		capacitor
	G2_IO5	PG1 ⁽²⁾	-			-			-	-		
	G3_IO1	PB0 ⁽¹⁾	18			J3			26	H4		
	G3_IO2	PB1	19		2 channels with	Н3		2 channels with	27	F4		2 channels with
Group 3	G3_IO3	PB2	20	3	1 sampling	G3	3	1 sampling	28	Н3	3	1 sampling
	G3_IO4	_	-		capacitor	-		capacitor	-	-		capacitor
G3_IO5	PF12	-			-			-	-			
	G4_IO1	PA8	29		2 channels with	E3		2 channels with	41	E4		2 channels with
Group 4	G4_IO2	PA9	30	3	1 sampling	C1	3	1 sampling	42	D2	3	1 sampling
	G4_IO3	PA10	31		capacitor	D2		capacitor	43	D3		capacitor



Table 69. Available touch sensing channels for STM32L1 Series 256K (table 1/2) (continued)

	Subfamily						STM32L1	Series 256K			<u>, </u>	
	Packages			LQFP48 o	r UFQFPN48		WLCS	P63		LQF	P64 / WLC	SP64
P	art number	rs		STM3	2L152CC		STM32L1	151UC		S	ГМ32L151F ГМ32L152F ГМ32L162F	RC
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	WLCSP ball	Number of available pins	Usage	LQFP pin	WLCSP ball	Number of available pins	Usage
	G5_IO1 PA13 Group 5 G5_IO2 PA14		34		2 channels with	C2		2 channels with	46	D4		2 channels with
Group 5	Group 5 G5_IO2 PA14		37	3	1 sampling	C3	3	1 sampling	49	B2	3	1 sampling
	G5_IO3	PA15	38		capacitor	A2		capacitor	50	C3		capacitor
	G6_IO1	PB4	40			D4			56	B4		
Group 6	G6_IO2	PB5	41	4	3 channels with	A5	4	3 channels with	57	A5	4	3 channels with
Group 6	G6_IO3	PB6	42	4	1 sampling capacitor	B5	4	1 sampling capacitor	58	B5	4	1 sampling capacitor
	G6_IO4	PB7	43	-		C5			59	C5		
	G7_IO1	PB12	25			G2			33	G2		
	G7_IO2	PB13	26			G1			34	G1		
	G7_IO3	PB14	27]	3 channels with	F3		3 channels with	35	F2		3 channels with
Group 7		PB15	28	4	1 sampling	F2	4	1 sampling	36	F1	4	1 sampling
	G7_IO5	PG2 ⁽²⁾	-]	capacitor	-		capacitor	-	-		capacitor
	G7_IO6	PG3 ⁽²⁾	-]		-			-	-		
	G7_IO7	PG4 ⁽²⁾	-			-			-	-		

Table 69. Available touch sensing channels for STM32L1 Series 256K (table 1/2) (continued)

	Subfamily						STM32L1	Series 256K		(-	
	Packages			LQFP48 o	or UFQFPN48		WLCS	P63		LQF	P64 / WLC	SP64
P	art number	s		STM3	2L152CC		STM32L1	151UC		S	ГМ32L151F ГМ32L152F ГМ32L162F	RC
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	WLCSP ball	Number of available pins	Usage	LQFP pin	WLCSP ball	Number of available pins	Usage
	G8_IO1	PC0	-			E6			8	E8		
Croup 9	G8_IO2	PC1	-	0		E5	4	3 channels with 1 sampling	9	F8	4	3 channels with 1 sampling
Group o	Group 8 G8_IO3 G8 IO4	PC2	-			G7	4	capacitor	10	D6	4	capacitor
	G8_IO4	PC3	-			G6			11	F7		
	G9_IO1	PC4	-			F4			24	H6		
Group 9	G9_IO2	PC5	-	0		J4	2	1 channel with 1 sampling	25	H5	2	1 channel with 1 sampling
Group 9	G9_IO3	PF13	-			-		capacitor	i	-		capacitor
	G9_IO4	PF14	-			-			i	-		
	G10_IO1	PC6	-		Cannot be used for touch sensing	F1			37	E1		
Group 10	G10_IO2	PC7	-	0	G	E1	4	3 channels with 1 sampling	38	E2	4	3 channels with 1 sampling
Group 10	G10_IO3	PC8	-			D1	7	capacitor	39	E3		capacitor
	G10_IO4	PC9	-			E2			40	D1		
	G11_IO1	PF6	-			-			-	-		
	G11_IO2	PF7	-			-		Cannot be used	-	-		Cannot be used
Group11	G11_IO3	PF8	-	0		-	0	for	-	-	0	for
	G11_IO4	PF9	-			-		touch sensing	-	-		touch sensing
	G11_IO5	PF10	-			-			-	-		



Table 69. Available touch sensing channels for STM32L1 Series 256K (table 1/2) (continued)

	Subfamily						STM32L1	Series 256K				
	Packages			LQFP48 c	or UFQFPN48		WLCSI	P63		LQF	P64 / WLC	SP64
P	art number	's		STM3	2L152CC		STM32L1	51UC		S	ГМ32L151F ГМ32L152F ГМ32L162F	RC
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	WLCSP ball	Number of available pins	Usage	LQFP pin	WLCSP ball	Number of available pins	Usage
Maximum	number of	channels			nnels with 7 g capacitors		23 channels sampling ca				hannels wit pling capac	

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

^{2.} This GPIO can only be configured as sampling capacitor I/O when using HW acquisition mode and as channel I/O when using SW acquisition mode.

Table 70. Available touch sensing channels for STM32L1 Series 256K (table 2/2)

9	Subfamily						ST	M32L1 Serie	es 256K			
F	Packages			LQF	P100 / UFB	GA100		UFBG	6A132		LQFP	144
Pa	rt number	'S			STM32L151 STM32L152 STM32L162	VC		STM32L STM32L STM32L	_152QC		STM32L STM32L STM32L	152ZC
Analog I/O group	Gx_IOy	GPIO	LQFP pin	BGA ball	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G1_IO1	PA0	23	L2			L2			34		
Croup 1	G1_IO2	PA1	24	M2	4	3 channels with 1 sampling capacitor K3 L3		1	3 channels with	35	4	3 channels with
Group 1	G1_IO3	PA2	25	K3	4			4	1 sampling capacitor	36	4	1 sampling capacitor
	G1_IO4	PA3 ⁽¹⁾	26	L3						37		
	G2_IO1	PA6	31	L4			L4			42		
	G2_IO2	PA7	32	M4		1 channel with	J5		3 channels with	43		3 channels with
Group 2	G2_IO3	PF15	-	-	2	1 sampling	J9	4 ⁽²⁾	1 sampling	55	4 ⁽²⁾	1 sampling
	G2_IO4	PG0 ⁽³⁾	-	-		capacitor	Н9		capacitor	56		capacitor
	G2_IO5	PG1 ⁽³⁾	-	-			G9			57		
	G3_IO1	PB0 ⁽¹⁾	35	M5			M5			46		
	G3_IO2	PB1	36	M6		2 channels with	M6		4 channels with	47		4 channels with
Group 3	G3_IO3	PB2	37	L6	3	1 sampling	L6	5	1 sampling	48	5	1 sampling
	G3_IO4	PF11	-	-		capacitor K6		capacitor	49		capacitor	
	G3_IO5		-			J7			50			
	G4_IO1	PA8	67	D11		2 channels with	D11		2 channels with	100		2 channels with
Group 4	G4_IO2	PA9	68	D10	3	1 sampling	D10	3	1 sampling	101	3	1 sampling
	G4_IO3	PA10	69	C12		capacitor	C12		capacitor	102		capacitor

Table 70. Available touch sensing channels for STM32L1 Series 256K (table 2/2) (continued)

S	Subfamily					-	ST	M32L1 Serie	s 256K	-	-	
F	Packages			LQF	P100 / UFB	GA100		UFBG	A132		LQFP	144
Pa	rt number	s			STM32L151 STM32L152 STM32L162	VC		STM32L STM32L STM32L	.152QC		STM32L STM32L STM32L	152ZC
Analog I/O group	Gx_IOy	GPIO	LQFP pin	BGA ball	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
	G5_IO1	PA13	72	A11		2 channels with	A11		2 channels with	105		2 channels with
Group 5	G5_IO2	PA14	76	A10	3	1 sampling	A10	3	1 sampling	109	3	1 sampling
	G5_IO3	PA15	77	A9		capacitor	A9		capacitor	110		capacitor
	G6_IO1	PB4	90	A7			A7			134		
Group 6	G6_IO2	PB5	91	C5	4	3 channels with 1 sampling	C5	4	3 channels with 1 sampling	135	4	3 channels with 1 sampling
Group 6	G6_IO3	PB6	92	B5	4	capacitor	B5	4	capacitor	136	4	capacitor
	G6_IO4	PB7	93	B4			B4			137		
	G7_IO1	PB12	51	L12			L12			73		
	G7_IO2	PB13	52	K12			K12			74		
	G7_IO3	PB14	53	K11		3 channels with	K11		4 channels with	75		4 channels with
Group 7	G7_IO4	PB15	54	K10	4	1 sampling	K10	5 ⁽²⁾	1 sampling	76	5 ⁽²⁾	1 sampling
	G7_IO5	PG2 ⁽³⁾	-	-		capacitor	G10		capacitor	87		capacitor
	G7_IO6	PG3 ⁽³⁾	-	-			F9			88		
	G7_IO7	PG4 ⁽³⁾	-	-			F10			89		
	G8_IO1	PC0	15	H1			H1			26		
Croup 0	G8_IO2	PC1	16	J2	4	3 channels with	J2		3 channels with	27		3 channels with
Group 8	G8_IO3	PC2	17	J3	4	1 sampling capacitor	J3	4	1 sampling capacitor	28	4	1 sampling capacitor
	G8_IO4	PC3	18	K2			K2 ⁽³⁾			29 ⁽³⁾		

Table 70. Available touch sensing channels for STM32L1 Series 256K (table 2/2) (continued)

	STM32L1 Series 256K											
ı	LQFP100 / UFBGA100 STM32L151VC STM32L152VC STM32L162VC				UFBGA132 STM32L151QC STM32L152QC STM32L162QC			LQFP144 STM32L151ZC STM32L152ZC STM32L162ZC				
Pa												
Analog I/O group	Gx_IOy	GPIO	LQFP pin	BGA ball	Number of available pins	Usage	BGA ball	Number of available pins	Usage	LQFP pin	Number of available pins	Usage
Group 9	G9_IO1	PC4	33	K5	2	1 channel with 1 sampling capacitor	K5	4	3 channels with 1 sampling capacitor	44	4	3 channels with 1 sampling capacitor
	G9_IO2	PC5	34	L5			L5			45		
	G9_IO3	PF13	-	-			K7			53		
	G9_IO4	PF14	-	-			J8			54		
Group 10	G10_IO1	PC6	63	E12	4	3 channels with 1 sampling capacitor	E12	4	3 channels with 1 sampling capacitor	96	4	3 channels with 1 sampling capacitor
	G10_IO2	PC7	64	E11			E11			97		
	G10_IO3	PC8	65	E10			E10			98		
	G10_IO4	PC9	66	D12			D12			99		
Group11	G11_IO1	PF6	-	-	0	Cannot be used for touch sensing	G3	4	3 channels with 1 sampling capacitor	18	5	4 channels with 1 sampling capacitor
	G11_IO2	PF7	-	-			G4			19		
	G11_IO3	PF8	-	-			H4			20		
	G11_IO4	PF9	-	-			J6			21		
	G11_IO5	PF10	-	-			-			22		
Maximum number of channels			23 channels with 10 sampling capacitors				33 channels with 11 sampling capacitors			34 channels with 11 sampling capacitors		

^{1.} This GPIO offers a reduced touch sensing sensitivity. It is thus recommended to use it as sampling capacitor I/O.

^{3.} This GPIO can only be configured as sampling capacitor I/O when using HW acquisition mode and as channel I/O when using SW acquisition mode.



^{2.} Not all the pins are available simultaneously on this group.

Table 71. Available touch sensing channels for STM32L15x 32K to 128K

S	ubfamily		STM32L15x 32K to 128K											
Р	ackages			LQFP48	VFQFPN48		l	LQFP64 / B	GA64	LQFP100 / BGA100				
Par	t numbers	i		STM3 STM3 STM3 STM3	2L151C6 2L151C8 2L151CB 2L152C6 2L152C8 2L152CB			STM32L18 STM32L18 STM32L18 STM32L18 STM32L18	51R8 51RB 52R6 52R8	STM32L151V8 STM32L151VB STM32L152V8 STM32L152VB				
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	LQFP pin	BGA ball	Number of available pins	Usage	LQFP pin	BGA ball	Number of available pins	Usage	
	G1_IO1	PA0	10	- 4	3 channels with 1 sampling capacitor	14	G2	4	3 channels with 1 sampling capacitor	23	L2	4	3 channels with 1 sampling capacitor	
Group 1	G1_IO2	PA1	11			15	H2			24	M2			
Gloup I	G1_IO3	PA2	12			16	F3			25	K3			
	G1_IO4	PA3	13			17	G3			26	L3			
Group 2	G2_IO1	PA6	16	2	1 channel with 1 sampling capacitor	22	G4	2	1 channel with 1 sampling capacitor	31	L4	2	1 channel with 1 sampling capacitor	
	G2_IO2	PA7	17			23	H4			32	M4			
	G3_IO1	PB0	18	2	1 channel with 1 sampling capacitor	26	F5	2	1 channel with 1 sampling capacitor	35	M5	- 2	1 channel with 1 sampling capacitor	
Group 3	G3_IO2	PB1	19			27	G5			36	M6			
	G4_IO1	PA8	29		2 channels with	41	D7		2 channels with 1 sampling capacitor	67	D11	3	2 channels with 1 sampling capacitor	
Group 4	G4_IO2	PA9	30	3	1 sampling capacitor	42	C7	3		68	D10			
	G4_IO3	PA10	31			43	C6			69	C12			
	G5_IO1	PA13	34	3	2 channels with 1 sampling capacitor	46	A8	3	2 channels with 1 sampling capacitor	72	A11	3	2 channels with 1 sampling capacitor	
Group 5	G5_IO2	PA14	37			49	A7			76	A10			
	G5_IO3	PA15	38			50	A6			77	A9			

UM1913 Rev 7

STM32L1 Series microcontrollers

Table 71. Available touch sensing channels for STM32L15x 32K to 128K (continued)

S	ubfamily		STM32L15x 32K to 128K											
Р	ackages		LQFP48 / VFQFPN48				ı	LQFP64 / B	GA64	LQFP100 / BGA100				
Par	Part numbers			STM32L151C6 STM32L151C8 STM32L151CB STM32L152C6 STM32L152C8 STM32L152CB				STM32L15 STM32L15 STM32L15 STM32L15 STM32L15	11R8 1RB 12R6 12R8	STM32L151V8 STM32L151VB STM32L152V8 STM32L152VB				
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	LQFP pin	BGA ball	Number of available pins	Usage	LQFP pin	BGA ball	Number of available pins	Usage	
0 0	G6_IO1	PB4	40	2	1 channel with 1 sampling capacitor	56	A4		1 channel with	90	A7		1 channel with	
Group 6	G6_IO2	PB5	41			57	C4	2	1 sampling capacitor	91	C5	2	1 sampling capacitor	
	G7_IO1	PB12	25	26 4	3 channels with 1 sampling capacitor	33	H8	4	3 channels with 1 sampling capacitor	51	L12	4	3 channels with 1 sampling capacitor	
Group 7	G7_IO2	PB13	26			34	G8			52	K12			
Gloup /	G7_IO3	PB14	27			35	F8			53	K11			
	G7_IO4	PB15	28			36	F7			54	K10			



Table 71. Available touch sensing channels for STM32L15x 32K to 128K (continued)

Subfamily Packages			STM32L15x 32K to 128K											
			LQFP48 / VFQFPN48					LQFP64 / B	GA64	LQFP100 / BGA100				
Part numbers			STM32L151C6 STM32L151C8 STM32L151CB STM32L152C6 STM32L152C8 STM32L152CB					STM32L18 STM32L18 STM32L18 STM32L18 STM32L18	51R8 51RB 52R6 52R8	STM32L151V8 STM32L151VB STM32L152V8 STM32L152VB				
Analog I/O group	Gx_IOy	GPIO	Pin	Number of available pins	Usage	LQFP pin	BGA ball	Number of available pins	Usage	LQFP pin	BGA ball	Number of available pins	Usage	
	G8_IO1	PC0	-	0	8 9 10 11 Cannot be used for touch sensing 25 37 38 39 40	8	E3	4/3	3/2 channels with 1 sampling capacitor	15	H1	- - 4	3 channels with 1 sampling capacitor	
Group 8	G8_IO2	PC1	-			9	E2			16	J2			
	G8_IO3	PC2	-			10	F2			17	J3			
	G8_IO4	PC3	-			11	-			18	K2			
	G9_IO1	PC4	-	0		24	H5	2	1 channel with 1 sampling capacitor	33	K5	2	1 channel with 1 sampling capacitor	
Group 9	G9_IO2	PC5	-			25	H6			34	L5			
	G10_IO1	PC6	-	0		37	F6	4	3 channels with 1 sampling capacitor	63	E12	4	3 channels with 1 sampling capacitor	
Group 10	G10_IO2	PC7	-			38	E7			64	E11			
	G10_IO3	PC8	-			39	E8			65	E10			
	G10_IO4	PC9	-			40	D8			66	D12			
Maximum number of channels				13 channels with 7 sampling capacitors			20/19 channels with 10 sampling capacitors				20 channels with 10 sampling capacitors			

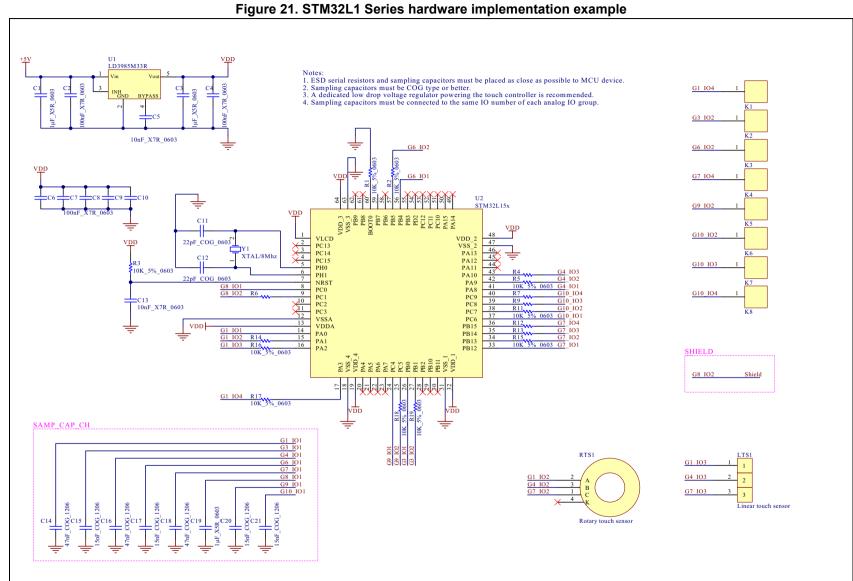
UM1913 Rev 7

4.7 Hardware implementation example

Figure 21 shows an example of hardware implementation on STM32L1 Series microcontrollers.







UM1913 Rev 7

Getting started UM1913

5 Getting started

5.1 Create your application

Start with an application example present in the STM32Cube package of the device you intend to use. Take an example that is close in term of number of channels/sensors with your target application. Copy and paste the example in the same parent folder and rename it according your target application. Then modify the files as described below.

The following sections describe the necessary steps to create a new application project.

5.1.1 Toolchain compiler preprocessor section

The device that you intend to use must be written in the **toolchain compiler preprocessor section** of your project.

These defines are the same as those used by the STM32Cube. Please see the stm<xxx>.h map file to have the list of the microcontrollers definition.

Note:

The hardware acquisition mode is selected per default for the STM32L1 Series microcontrollers with a minimum of 384 K of Flash. If you want to use the software acquisition mode you must add the following constant in the toolchain compiler preprocessor:

TSLPRM_STM32L1XX_SW_ACQ

5.1.2 The tsl conf.h file

The **tsl_conf.h** file contains all the STMTouch touch sensing library parameters. The following edits must be done:

- 1. Change the number of channels, banks, sensors according your application.
- 2. Change the common parameters: thresholds, debounce, ECS, DTO, etc.
- 3. Change the parameters specific to the device.

5.1.3 The main file

The **main.c** and **main.h** files contain the application code itself (LEDs and LCD management, etc.) and the call to the STMTouch touch sensing library initialization and action functions.

5.1.4 The tsl user file

The **tsl_user.c** and **tsl_user.h** files contain the STMTouch touch sensing library configuration (definition of channels, banks, sensors, etc.) and the STMTouch touch sensing library initialization (**TSL_user_Init**) and action (**TSL_user_Action**) functions.

Create the channels variables using the structures (mandatory):

- TSL_ChannelSrc_T
- TSL_ChannelDest_T
- TSL_ChannelData_T

Create the Banks variables using the structures (mandatory):

TSL_Bank_T

150/156 UM1913 Rev 7

UM1913 Getting started

Create the touchkeys variables using the structures (optional):

- TSL_TouchKeyData_T
- TSL_TouchKeyParam_T
- TSL_State_T
- TSL_TouchKeyMethods_T
- TSL_TouchKeyB_T
- TSL_TouchKey_T

Create the linear and rotary touch sensors variables using the structures (optional):

- TSL LinRotData T
- TSL_LinRotParam_T
- TSL State T
- TSL LinRotMethods T
- TSL_LinRotB_T
- TSL_LinRot_T

Create the generic sensors (objects) variables using the structures (mandatory):

- TSL Object T
- TSL_ObjectGroup_T

The **TSL_user_Init()** function contains the initialization of the STMTouch touch sensing library. Modify this function to take into account your bank array name and object groups names.

The **TSL_user_Exec()** function contains the main state machine. Modify it also if you have several object groups to process or to change the ECS period, etc.

5.2 Debug with STM Studio

The STM Studio software is very useful to observe variables of the STMTouch touch sensing library. Its powerful features allow a better understanding of how the sensors behave and to find the better parameters to apply.

This section does not intend to explain how to use this tool, but give some advice to better understand and debug user's application.

This is a non-exhaustive list of the STMTouch touch sensing library variables to observe:

- The channels measure, reference and delta. These variables are present inside the TSL_ChannelData_T structure. This is useful to adjust the thresholds parameters.
- The sensors state present in the TSL_TouchKeyData_T and TSL_LinRotData_T structures. This is useful to adjust the Debounce, ECS and DTO parameters.
- The linear and rotary touch sensors position in the TSL_LinRotData_T structure.

The following snapshot is an example of data visualization on STM Studio:

UM1913 Rev 7 151/156

Getting started UM1913

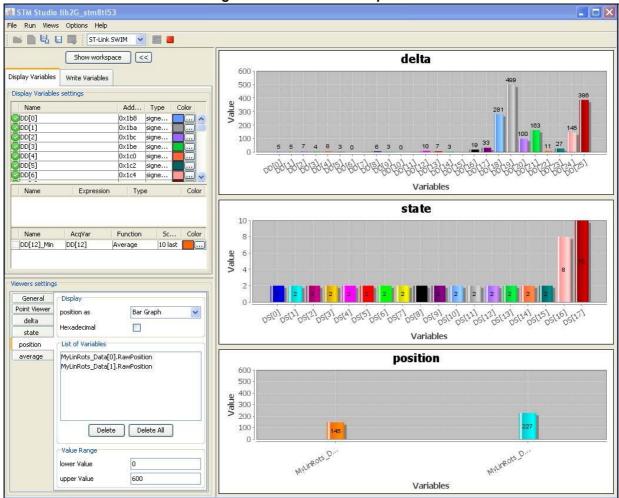


Figure 22. STM Studio snapshot

5.3 Low-power strategy

The following figure shows the acquisition sequencing for a single bank acquisition to optimize the power consumption of the device.

To reduce the power consumption, the acquisitions are sequenced with a long delay in between. During this delay, the MPU can be in low-power mode (i.e. Stop mode). This delay can be shortened or even removed between two consecutive acquisitions when the delta becomes greater than a detection threshold (proximity or touch). The long delay is restored if all the sensors return in RELEASE state.

For optimum power consumption, the acquisition must be performed with the MCU in Sleep or Low-power sleep mode and with the optimum TSC peripheral clock frequency (not too low or too high). The sensor processing must be performed at the highest possible frequency in order to minimize the processing duration. The user application processing must be done at the optimum CPU frequency to offer the best trend between task duration and power consumption.

57

UM1913 Getting started

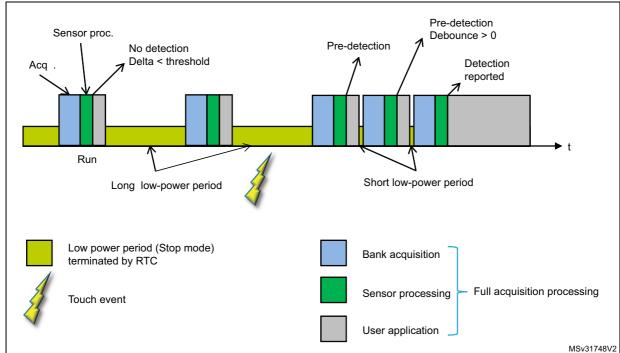


Figure 23. Low-power strategy

This approach allows power consumption saving without increasing the response time. The maximum response time is obtained when a touch occurs during the sensor processing. It can be expressed as followed:

Max Response Time = long low-power period + (n) x short low-power period + (n+2) x full acquisition processing - bank acquisition

with n being the debounce value.

5.4 Tips and tricks

5.4.1 Recommendations to increase the noise immunity on the PCB

To ensure a correct operation in noisy environment, the floating nets must be avoided (tracks, copper elements, conductive frames, etc.).

As a consequence:

- All unused touch controller I/Os must be either configured to output push-pull low or externally tied to GND.
- The parameter TSLPRM_TSC_IODEF must also be configured to the output push-pull low state.
- We recommend to drive the sampling capacitor common node using a standard I/O of the touch controller configured in output push-pull low mode.
- It may also be required to add a capacitor-input filter (pi filter) on each channel line.

Getting started UM1913

5.4.2 Bank definition

For optimum sensitivity and position reporting, all the channels composing a linear or a rotary touch sensor must be acquired **simultaneously**. This means that all the channels must belong to the **same bank**.

Note:

The library allows the definition of a linear or a rotary touch sensor with channels belonging to different banks. A such configuration induces a **loss of sensitivity** and a **higher noise level**. Moreover, depending on the acquisition time, it is also possible to observe a position change when removing the finger from the sensor.

5.4.3 Channel assignment

It is recommended to assign GPIOs offering the same sensitivity level to all the channels composing a linear or a rotary touch sensor. Moreover, it is not recommended to use GPIOs offering a reduced sensitivity.

5.4.4 IO Default state parameter

For optimum acquisition noise level, it is recommended to set the **TSLPRM_TSC_IODEF** or **TSLPRM_IODEF** parameter to **output push-pull low**.

However, if your application is using a linear or a rotary touch sensor with channels belonging to different banks, this parameter must be set to **input floating**. This ensures optimum sensitivity.

5.5 Related documents

- AN4312 Guidelines for designing touch sensing applications with surface sensors.
- AN4299 Guidelines to improve conducted noise robustness on STM32F0/F3, STM32L0/L4 Series touch sensing applications.
- AN4316 Tuning a STMTouch-based application.

577

154/156 UM1913 Rev 7

UM1913 Revision history

6 Revision history

Table 72. Document revision history

Date	Revision	Changes
05-Jan-2016	1	Initial release.
29-Feb-2016	2	Updated Section 2.4.3: Acquisition and processing layers. Removed former Section 2.7: Zone.
19-May-2016	3	Updated document title. Updated Section: Introduction. Updated line TSC_G3_IO4 in Table 41: Available touch sensing channels for STM32F334x4/x6/x8.
24-Nov-2016	4	Updated Section 5.5: Related documents.
26-Sep-2017	5	Added STM32L083 and STM32L082 lines in Section 3.7.2. Added STM32L496 and STM32L4A6 lines in Section 3.8.2.
14-Mar-2018	6	Updated Section 2.9.4: Electrodes placement including Figure 8: Electrodes designs, Figure 9: Positions 0 and 255, and Table 3: Supported linear and rotary touch sensors.
26-Sep-2018	7	Added Section 2.18: Sensors acquisition timings and Section 2.19: Error management. Updated: - Section 2.12: Environment change system (ECS) - Section 2.12.4: Usage example - Section 5.1.4: The tsl_user file

155/156

IMPORTANT NOTICE - PLEASE READ CAREFULLY

STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, enhancements, modifications, and improvements to ST products and/or to this document at any time without notice. Purchasers should obtain the latest relevant information on ST products before placing orders. ST products are sold pursuant to ST's terms and conditions of sale in place at the time of order acknowledgement.

Purchasers are solely responsible for the choice, selection, and use of ST products and ST assumes no liability for application assistance or the design of Purchasers' products.

No license, express or implied, to any intellectual property right is granted by ST herein.

Resale of ST products with provisions different from the information set forth herein shall void any warranty granted by ST for such product.

ST and the ST logo are trademarks of ST. All other product or service names are the property of their respective owners.

Information in this document supersedes and replaces information previously supplied in any prior versions of this document.

© 2018 STMicroelectronics - All rights reserved

156/156 UM1913 Rev 7